Entanglement-assisted guessing of complementary measurement outcomes

Mario Berta,1 Patrick J. Coles,2,3 and Stephanie Wehner3,4

1Institute for Quantum Information and Matter, Caltech, Pasadena, California 91125, USA
2Institute for Quantum Computing and Department of Physics and Astronomy, University of Waterloo, Waterloo, Ontario, Canada N2L3G1
3Centre for Quantum Technologies, National University of Singapore, 2 Science Drive 3, 117543 Singapore
4QuTech, Delft University of Technology, Lorentzweg 1, 2628 CJ Delft, Netherlands

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Heisenberg’s uncertainty principle implies that if one party (Alice) prepares a system and randomly measures one of two incompatible observables, then another party (Bob) cannot perfectly predict the measurement outcomes. This implication assumes that Bob does not possess an additional system that is entangled to the measured one; indeed, the seminal paper of Einstein, Podolsky, and Rosen (EPR) showed that maximal entanglement allows Bob to perfectly win this guessing game. Although not in contradiction, the observations made by EPR and Heisenberg illustrate two extreme cases of the interplay between entanglement and uncertainty. On the one hand, no entanglement means that Bob’s predictions must display some uncertainty. Yet on the other hand, maximal entanglement means that there is no more uncertainty at all. Here we follow an operational approach and give an exact relation—an equality—between the amount of uncertainty as measured by the guessing probability and the amount of entanglement as measured by the recoverable entanglement fidelity. From this equality, we deduce a simple criterion for witnessing bipartite entanglement and an entanglement monogamy equality.

I. UNCERTAINTY RELATIONS

Heisenberg’s uncertainty principle forms one of the fundamental elements of quantum mechanics. Originally proven for measurements of position and momentum, it is one of the most striking examples of the difference between a quantum and a classical world [1]. Uncertainty relations today are probably the most best known in the form given by Robertson [2], who extended Heisenberg’s result to two arbitrary observables X and Z. More precisely, Robertson’s relation states that when measuring the state $|\psi\rangle$ using either X or Z, one finds

$$\Delta X \Delta Z \geq \frac{1}{2} \left| \langle \psi | [X,Z] | \psi \rangle \right|, \quad (1)$$

where $\Delta Y = \sqrt{\langle \psi | Y^2 | \psi \rangle - \langle \psi | Y | \psi \rangle^2}$ for $Y \in \{X,Z\}$ is the standard deviation resulting from measuring $|\psi\rangle$ with observable Y.

In the modern-day literature, uncertainty is usually measured in terms of entropies (starting with [3–5]; see [6] for a survey). One of the reasons this is desirable is that Eq. (1) makes no statement if $|\psi\rangle$ happens to give zero expectation on $\{X,Z\}$ [7]. To see how uncertainty can be quantified in terms of entropies, let us start with a simple example. Throughout, we let Alice (A) denote the system to be measured. For now, let us consider measuring a single qubit in the state $\rho_A$ using two incompatible measurements given by the Pauli $\sigma_x$ or $\sigma_z$ eigenbases, and let K be the random variable associated with the measurement outcome. We have from [8] that for any state $\rho_A$,

$$H(K|\Theta) = \frac{1}{2} \left[ H(K|\Theta = \sigma_x) + H(K|\Theta = \sigma_z) \right] \geq \frac{1}{2}, \quad (2)$$

where $H(K|\Theta) = -\sum_k p_k(\Theta=k) \log p_k(\Theta=k)$ is the Shannon entropy (all logarithms are base 2 in this article) of the probability distribution over measurement outcomes $k \in \{0,1\}$ when we perform the measurement labeled $\Theta$ on the state $\rho_A$, and each measurement is chosen with probability $p_\Theta = 1/2$. To see that this is an uncertainty relation, note that if one of the two entropies is zero, then (2) tells us that the other is necessarily nonzero, i.e., there is at least some amount of uncertainty. If we measure a $d_A$-dimensional system A in two orthonormal bases $\Theta_0 = \{ |x_0\rangle \}_{x_0=1}^{d_A}$ and $\Theta_1 = \{ |x_1\rangle \}_{x_1=1}^{d_A}$, then the right-hand side (r.h.s.) of (2) becomes $\log(1/c)$, where $c = \max_{x_0,x_1} |\langle x_0 | x_1 \rangle|^2$. The largest amount of uncertainty, i.e., the largest $\log(1/c)$, is thereby obtained when $|\langle x_0 | x_1 \rangle| = 1/\sqrt{d_A}$, that is, the two bases are mutually unbiased (MUB) [9].

When thinking about uncertainty, it is often illustrative to adopt an adversarial perspective and consider an “uncertainty game” [10], commonly used in quantum cryptography [11]. In particular, we will think about uncertainty from the perspective of an observer called Bob holding a second system (B) whose task is to guess the outcome of the measurement on Alice’s system successfully. Bob thereby knows ahead of time what measurements could be made and the probability that a particular measurement setting is chosen. To help him win the game, Bob may even prepare $\rho_A$ himself, and Alice tells him which measurement she performed before he has to make his guess. The amount of uncertainty as measured by entropies can be understood as a limit on how well Bob can guess Alice’s measurement outcome—the more difficult it is for Bob to guess, the more uncertain Alice’s measurement outcomes are. If Bob is not entangled with A but only keeps classical information about the state, such as for example a description of the density operator $\rho_A$, then (2) still holds even if we condition on Bob’s classical information B [12]. More precisely, we have $H(K|B_{\text{classical}}) \geq 1/2$ for any states or distribution of states that Bob may prepare.

II. UNCERTAINTY AND ENTANGLEMENT

Another central element of quantum mechanics is the possibility of entanglement, and examples suggest that there
is a strong interplay between entanglement and uncertainty. In particular, Einstein, Poldolsky, and Rosen (EPR) [13] observed that if Bob is maximally entangled with A, then his uncertainty can be reduced dramatically. To see this, imagine that \( \rho_{AB} = |\Phi\rangle\langle\Phi| \) where \( |\Phi\rangle = (|00\rangle + |11\rangle)/\sqrt{2} \) is the maximally entangled state between A and B. Since \(|\Phi\rangle \) is maximally correlated in both the \( \sigma_x \) and \( \sigma_y \) eigenbases, Bob can simply measure his half of the EPR pair in the same \( \sigma_x \) as Alice to predict her measurement outcome perfectly, winning the guessing game described above. This is precisely the effect observed in [13] and highlights that the uncertainty relations of (1) and (2) do not capture the uncertainty in one direction. In particular, Einstein, Poldolsky, and Rosen (EPR) [13] showed [18] that if we measure \( A \) in one of \( d_A \) possible mutually unbiased bases chosen uniformly at random, then

\[
H(K|B\Theta) \geq \log(1/c) + H(A|B),
\]

where \( H(A|B) \) is the conditional von Neumann entropy of A given B. If A and B are entangled, then \( H(A|B) \) can be negative. Indeed, \( H(A|B) = - \log d_A \) when \( \rho_{AB} \) is the maximally entangled state, in which case the lower bound in (3) becomes trivial. The uncertainty relation of (3) thus allows for the possibility that Bob’s uncertainty could be reduced in the presence of entanglement. It also provides us with a first clue to the relation between entanglement and uncertainty in one direction, namely, that little uncertainty [i.e., \( H(K|B\Theta) \) is small] implies that \( H(A|B) \) must be negative and hence \( \rho_{AB} \) is entangled [15]. As such, (3) is useful for the task of witnessing entanglement [16,17].

Many more similar relations have since been proven for more than two measurements on Alice’s system, and in terms of other forms of entropies. One entropy measure that is of central importance in cryptography is the conditional min-entropy \( H_{\min}(K|B\Theta) \) and it yields a more immediate link between uncertainty relations with quantum side information and the uncertainty game mentioned above. Specifically, it was shown [18] that if we measure \( A \) in one of \( d_A \) possible mutually unbiased bases chosen uniformly at random, then

\[
H_{\min}(K|B\Theta) \geq \log d_A + \min(0, H_{\min}(A|B)).
\]

[More precisely, smoothing of the entropies is required for (4) to hold, and hence the symbol \( \geq \) refers to an additional term that depends on the smoothing.] With \( K \) being a classical random variable, the conditional min-entropy \( H_{\min}(K|B\Theta) = - \log P_{\text{guess}}(K|B\Theta) \) is simply derived from the maximum probability that Bob can guess \( K \), averaged over the choice of basis \( \theta \) [19]. That is, it captures exactly how well Bob can guess Alice’s measurement outcome \( K \) by performing a measurement on \( B \). The fully quantum conditional min-entropy \( H_{\min}(A|B) \) has the operational interpretation \( H_{\min}(A|B) = - \log[d_A F(A|B)] \), with

\[
F(A|B) = \max_{\Lambda_{B\rightarrow A}} F(\Phi_{AA'} | \mathcal{I}_A \otimes \Lambda_{B\rightarrow A}(\rho_{AB})).
\]

where \( F(\rho,\sigma) = (\text{Tr}\sqrt{\sqrt{\rho} \sigma \sqrt{\rho}})^2 \) is Uhlmann’s fidelity [20], \( \Phi_{AA'} = |\Phi_{AA'}\rangle\langle\Phi_{AA'}| \), and \( |\Phi_{AA'}\rangle = (1/\sqrt{d_A}) \sum_{j=1}^{d_A} |j\rangle_A |j\rangle_{A'} \) is the maximally entangled state between \( A \) and \( A' \) [19]. In other words, the conditional min-entropy \( H_{\min}(A|B) \) measures how close one can bring a bipartite quantum state \( \rho_{AB} \) to the maximally entangled state by performing an arbitrary operation \( \Lambda \) on the \( B \) system. Recall from the example above that Bob can win the uncertainty game perfectly if \( \rho_{AB} \) really is maximally entangled. Intuitively, the conditional min-entropy thus measures how far away Bob is from this scenario. Needless to say, one could write similar statements for R"enyi entropies other than the min-entropy, but these are, in fact, equivalent up to small error terms.

Do these relations resolve the question of how uncertainty relates to entanglement? Note that the uncertainty relation (4) again provides us with a relation between entanglement and uncertainty in one direction. In particular, it tells us that if it is easy for Bob to guess Alice’s measurement outcome \( H_{\min}(K|B\Theta) \) is small, then there really exists some \( \Lambda_{B\rightarrow A} \) that Bob can use to bring \( \rho_{AB} \) at least somewhat close to being maximally entangled with \( A \). That is, it tells us that a reduction in uncertainty implies the presence of entanglement. However, it does not tell us that the presence of entanglement really does lead to a significant reduction in uncertainty. Of course, if \( \rho_{AB} \) is close to the maximally entangled state, then uncertainty is reduced by at least some amount because two states which are close yield similar statistics when measured. Yet we will see below that this alone is insufficient for our purpose.

### III. MAIN RESULT

Here, we prove the following finite-dimensional equality if we measure \( A \) in one of \( d_A \) possible mutually unbiased bases with uniformly random probability

\[
H_2(K|B\Theta) = \log(d_A + 1) - \log \left( 2^{-H_2(A|B)} + 1 \right),
\]

where

\[
H_2(A|B) = - \log (\text{Tr}[\rho_{AB}(\mathcal{I}_A \otimes \rho_B)^{-1/2} \rho_{AB}(\mathcal{I}_A \otimes \rho_B)^{-1/2}])
\]

is the conditional R"enyi 2-entropy used in quantum cryptography (see, e.g., [21,22]), and \( K \) is the classical measurement outcome obtained by measuring \( A \) in the basis labeled \( \Theta = \theta \). Since \( K \) is a classical random variable, the R"enyi 2-entropy \( H_2(K|B\Theta) \) has an operational interpretation as given by the probability that Bob manages to guess Alice’s measurement outcome \( K \) using the pretty good measurement [23,24] after he learns which measurement \( \Theta \) was made: \( H_2(K|B\Theta) = - \log P_{\text{guess}}(K|B\Theta) \). For the fully quantum R"enyi 2-entropy \( H_2(A|B) \), we prove (see Appendix A) that

\[
H_2(A|B) = - \log [d_A F_{\text{pg}}(A|B)],
\]

with

\[
F_{\text{pg}}(A|B) = F(\Phi_{AA'}, \mathcal{I}_A \otimes \Lambda_{B\rightarrow A,\text{pg}}(\rho_{AB})),
\]

where \( \Lambda_{\text{pg}} \) is the pretty good recovery map [25]. [We denote by \( \Phi_{AA'} \) the normalized maximally entangled state, and hence a factor \( d_A \) appears in (8).] Both the pretty good
measurement and the pretty good recovery map get very close to the performance of the optimal processes [24,25]. For the special case \( \rho_{AB} = \rho_A \otimes \rho_B \), (6) becomes an equation relating unconditional entropies that was discussed in [26,27] and used to derive uncertainty relations for Shannon entropies (see [6] for an overview). Furthermore, the conditional Rényi 2-entropy also appears in the study of randomness extractors against quantum side information (see, e.g., [22,28]), and in its quantum counterpart decoupling (see, e.g., [29,30]).

We mention that the existence of a full set of MUBs is only known in prime power dimension [31,32], but we show in Appendix D1 that our main result (6) also holds for informationally complete positive operator valued measures (SIC-POVMs) and unitary 2-designs. For the latter, efficient constructions are known in any dimension [33,34], and in particular the set of all bases defines a unitary 2-design.

Our relation (6) establishes an equivalence between uncertainty as measured by \( H_2(K|B\Theta) \) and our ability to recover entanglement as given by \( H_2(A|B) \). It is an operational way to merge the observations of EPR and Heisenberg into a single equation, demonstrating that both effects can be seen as flip sides of the same coin.

IV. DISCUSSION

A. Operational examples

To gain further intuition about (6), let us first return to the uncertainty game discussed earlier. Note that in terms of the operational interpretations of the conditional Rényi 2-entropy, we can rewrite (6) as

\[
\begin{align*}
\mathcal{P}^{\text{guess}}_{\text{pg}}(K|B\Theta) & = \frac{1}{d_A + 1} \sum_\theta \mathcal{P}^{\text{guess}}_{\text{pg}}(K|B\Theta = \theta) \\
& = \frac{d_A \mathcal{P}^{\text{pg}}(A|B) + 1}{d_A + 1}.
\end{align*}
\]

(10)

In the game, Bob prepares a state \( \rho_{AB} \) and sends the \( A \) system to Alice. She measures \( A \) in one basis chosen uniformly at random from the complete set of \( d_A + 1 \) MUBs, and announces the basis (the index \( \theta \)) to Bob. Bob’s task is to guess Alice’s outcome using the pretty good measurement on \( B \). Equation (10) says that Bob’s ability to win or lose this game is quantitatively connected to the recoverable entanglement fidelity of \( \rho_{AB} \), as measured by \( \mathcal{P}^{\text{pg}}(A|B) \).

Let us consider a number of special cases that illustrate this concept. In what follows, we refer to \( H_2(A|B) \geq 0 \) as the Heisenberg-limited regime and \( H_2(A|B) < 0 \) as the enhanced regime. As we will see below, this terminology refers to two distinct regimes, one in which Bob’s guessing probability is restricted by a Heisenberg-like uncertainty relation [see Eq. (11)], and the other in which his guessing probability can be enhanced beyond this restriction (although, of course, not in violation of the uncertainty principle). For example, if \( \rho_{AB} \) is the maximally entangled state, we have \( \mathcal{P}^{\text{pg}}(A|B) = 1 \) and Bob can guess Alice’s measurement outcome perfectly regardless of which measurement she performs, i.e., \( \mathcal{P}^{\text{guess}}_{\text{pg}}(K|B\Theta = \theta) = 1 \) for all \( \theta \). That is, there is no uncertainty, as expected. If Bob prepares \( \rho_{AB} \) with less than maximal entanglement, then \( \mathcal{P}^{\text{pg}}(A|B) < 1 \) and there will be at least one basis for which Bob cannot perfectly guess the outcome. Thus, there is at least some amount of uncertainty expressed quantitatively as \( H_2(K|B\Theta) \). If \( \rho_{AB} \) is separable, then Bob is stuck in the Heisenberg-limited regime \( \mathcal{P}^{\text{pg}} \leq 1/d_A \) and his ability to guess is very poor, constrained by the uncertainty relation

\[
\mathcal{P}^{\text{pg}}_{\text{guess}}(K|B\Theta) \leq 2/(d_A + 1).
\]

(11)

This illustrates that entanglement is necessary for Bob to gain an advantage in the guessing game.
allowed to keep any quantum information $B$ about $A$). Clearly, when $\rho_A$ is an eigenstate of $\sigma_Y$, the outcome distribution for both $\sigma_X$ and $\sigma_Z$ is uniform and hence $H_{\text{min}}(K|\Theta) = 1$, which is the maximum value. This argument generalizes to any extendable set of MUBs, since there exists a state (from another MUB) that has $H_{\text{min}}(K|\Theta) = \log d_A$, which is the maximum value that it can take and hence only the trivial upper bound or certainty relation holds. It is thus clear that equalities such as (6) can only hold for sets of measurements that are sufficiently rich.

C. Bounds for fewer bases

Even though there does not exist an uncertainty equality for measuring in less than $d_A + 1$ MUBs, we can still give lower (and trivial upper) bounds for Bob’s uncertainty about $A$ whenever $1 \leq n < d_A$ MUBs on $A$ in terms of the recoverable entanglement fidelity between $A$ and $B$. Moreover, these inequalities are tight for all $n$: that is, fixing the set of measurements, there exist states that achieve the upper and lower bounds. Our relations are again in terms of the conditional R\"{e}nyi $2$-entropy. Using $P_{\text{guess}}(n)$ as a shorthand to denote Bob’s guessing probability $P_{\text{guess}}(K|B,\Theta)$ when Alice does measurements in a subset of size $n$ of a complete set of MUBs, we find that the following bounds are tight in the Heisenberg-limited regime $\{F_{\text{PG}}(A|B) \leq 1/d_A\}$:

$$\frac{1}{d_A} \leq P_{\text{guess}}(n) \leq \frac{d_A}{n} F_{\text{PG}}(A|B) + \frac{n-1}{nd_A}. \quad (14)$$

Moreover, the following bounds are tight in the enhanced regime $\{F_{\text{PG}}(A|B) > 1/d_A\}$:

$$F_{\text{PG}}(A|B) \leq P_{\text{guess}}(n) \leq \frac{n-1}{n} F_{\text{PG}}(A|B) + \frac{1}{n}. \quad (15)$$

Here, the upper bounds (lower bounds) can be thought of as uncertainty relations (certainty relations). Note that we can derive these tight relations for all $n$ directly from our main result. Taken together, (14) and (15) completely characterize the allowable range of values that $P_{\text{guess}}(n)$ can attain. As an example, consider $d_A = 5$. Figure 1 plots the tight upper and lower bounds as a function of $F_{\text{PG}}(A|B)$. Notice that the (trivial) lower bound does not change as $n$ varies from 1 to 5; it only increases when we include the sixth basis. This is consistent with our discussion in the previous section, where we noted that a nontrivial certainty relation, i.e., a relation stronger than the certainty relation one obtains for a single basis, requires sufficiently rich sets of measurements. In contrast, the tight upper bound steadily decreases with $n$, reflecting the complementarity between the different bases. Overall, as $n$ increases from 1 to 6, the area of the allowed range monotonically shrinks towards zero, and the allowed area becomes zero for $n = 6$ since the two quantities $P_{\text{guess}}(n)$ and $F_{\text{PG}}(A|B)$ are deterministically related by our main result.

From Fig. 1, one can also see that if Bob can guess two MUBs on $A$ well, then he can also guess $d_A + 1$ MUBs on $A$ fairly well. Conceptually, this follows from a two-step chain of reasoning: if Bob’s uncertainty is low for two MUBs, then he must be entangled to Alice, which in turn implies that he must have a low uncertainty for all bases. So entanglement provides the key link, from two MUBs to all bases. From the above results, it is straightforward to derive the following quantitative statement of this idea:

$$P_{\text{guess}}(d_A + 1) \geq \frac{d_A}{d_A} [2 P_{\text{guess}}(2) - 1] + 1 = \frac{d_A}{d_A} + 1. \quad (16)$$

which says that as $P_{\text{guess}}(2) \rightarrow 1$, then $P_{\text{guess}}(d_A + 1) \rightarrow 1$.

D. Applications in quantum information theory

We briefly discuss some applications of our main result to quantum information processing tasks. Because entanglement is crucial for several quantum information technologies, the experimenter often needs a method to verify that their source is indeed producing entangled pairs, i.e., an “entanglement witness.” Following [10,37–39], our main result offers a simple strategy for witnessing entanglement since it connects entanglement to uncertainty, which is experimentally measurable. In particular, Alice and Bob (in their distant laboratories, receiving $A$ and $B$, respectively) can sample from the source multiple times and communicate their results to gather statistics, say, regarding the $K_0$ observable on $A$ and the $L_0$ observable on $B$. Suppose they do this for a set of $n$ MUBs $\{K_{\theta}\}_{\theta=1}^n$ on $A$, with Bob measuring in some arbitrary set of $n$ bases $\{L_{\theta}\}_{\theta=1}^n$ on $B$. They then estimate the joint probability distribution for each pair $\{K_{\theta}, L_{\theta}\}$, and hence they can evaluate the classical entropies $H_2(K_{\theta}|L_{\theta})$. According to our main result, their source is necessarily entangled if

$$\sum_{\theta=1}^n 2^{-H_2(K_{\theta}|L_{\theta})} > 1 + \frac{n-1}{d_A}. \quad (17)$$

Note that this method offers the flexibility of witnessing entanglement with $2 \leq n \leq d_A + 1$ observables (see also [40].
for a different approach). For \( n = 2 \), the same strategy based on the uncertainty relation (3) was implemented in [16,17].

Another application of our main result is to quantum error correction of noisy quantum channels. By viewing (6) from the dynamic perspective of Alice sending states through a quantum channel to Bob, and noting that the entanglement fidelity such as that appearing in (8) is a standard figure of merit for quantum error correction, we see from (6) that Bob’s ability to error correct is quantitatively linked to his ability to guess which states Alice sends, when she is sending basis elements from a complete set of MUBs.

Our uncertainty equality (6) also gives insight for studying the monogamy of correlations. The basic idea of monogamy is that A’s entanglement with B limits the degree to which A can be entangled with a third system, E. There have been several statements of monogamy in the literature; however, a nice aspect of our results is the potential to state monogamy as an equation rather than an inequality. We show that for any tripartite pure state \( \rho_{AEB} \),

\[
\inf_{\sigma} D_{\frac{1}{2}} \left( \rho_{AE} \||_{A}^{1} \otimes \sigma_{E} \right) = \log d_{A} - \log \left[ \left( d_{A} + 1 \right) P_{\text{guess}}^{\text{pg}} (K | B \Theta) - 1 \right],
\]

where the infimum is over all quantum states \( \sigma_{E} \), and \( D_{\frac{1}{2}} \) denotes the relative Rényi 1/2-entropy (see Appendix B3 for details). This relation states that Bob’s guessing probability for a complete set of Alice’s MUBs is a quantitative measure of the distance of \( \rho_{AE} \) (Alice’s and Eve’s state) to a completely uncorrelated state. According to (18), Bob and Eve fight in a “zero-sum game” to be correlated to Alice, i.e., any gain of knowledge about Alice’s system by Bob forces Eve’s state to get closer to being uncorrelated with Alice, and conversely any gain of distance from the uncorrelated state by Eve forces Bob to lose knowledge.

Finally, we remark that the conditional Rényi 2-entropy is an important quantity in the study of classical and quantum randomness extractors against quantum side information (see, e.g., [28,29]). Since our uncertainty equality (6) connects the conditional Rényi 2-entropy of the premeasurement state to the conditional Rényi 2-entropy of the postmeasurement state, our main result (6) shines some light on the relation between classical and quantum extractors. It can be used to get a new perspective on the results in [18], where security of the noisy storage model [41] was first linked to the quantum capacity.

**E. Conclusions**

In summary, we considered a two-party guessing game, where Alice measures her system A in one of \( n \) possible complementary observables and Bob uses his system B to help him guess Alice’s outcome. We showed that Bob’s probability for winning this game, assuming he does the “pretty good measurement” on B, is connected through an equality for \( n = d_{A} + 1 \) (inequality for \( n < d_{A} + 1 \)) to the prior entanglement between B and A. The latter is measured by the entanglement fidelity that can be recovered with the “pretty good recovery map,” which we proved is given by the conditional Rényi 2-entropy. We therefore showed that our operationally motivated equality can be thought of as an entropic uncertainty relation and, as such, connects Heisenberg’s uncertainty principle to EPR’s guessing game via an equation. We expect our approach to inspire further quantitative relations capturing the connection between uncertainty and entanglement. In addition, it would be interesting to explore the connection between the guessing game considered here and other nonlocal uncertainty games that have been considered in the literature, e.g., in the context of Bell inequalities [42] and steering [43,44].

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**APPENDIX A: QUANTITATIVE MEASURES**

1. Entanglement

Despite not being monotonic under local operations and classical communication, conditional entropies play an important role in entanglement theory [45]. For example, the conditional von Neumann entropy \( H(A|B) \) quantifies the asymptotic rate for distilling EPR pairs via a one-way hashing protocol [15]. Another important conditional entropy studied in cryptography is the min-entropy. It was originally defined in an abstract form [22], but was later given an intuitive operational meaning [19] in terms of the recoverable entanglement fidelity, i.e., \( H_{\text{min}} (A|B) = - \log [d_{A} F(A|B)] \)

\[
F(A|B) = \max_{\Lambda_{B \rightarrow A}} F(\Phi_{A^{\prime} A}.(\mathcal{I}_{A} \otimes \Lambda_{B \rightarrow A}) (\rho_{AB})),
\]

where the maximum is over all quantum operations \( \Lambda_{B \rightarrow A} \) with \( A^{\prime} \) a copy of A. (See, e.g., [46] for discussion of the importance of the entanglement fidelity in quantum information theory.)

A related entropy measure is the conditional Rényi 2-entropy, which is defined as

\[
H_{2}(A|B) = - \log \text{Tr} [\rho_{AB} (1_{A} \otimes \rho_{B})^{-1/2} (1_{A} \otimes \rho_{B})^{-1/2}].
\]

Here we give an operational meaning for the conditional Rényi 2-entropy by showing that like the conditional min-entropy, it is linked to the recoverable entanglement fidelity in that \( H_{2}(A|B) = - \log [d_{A} F_{\text{pg}} (A|B)] \),

\[
F_{\text{pg}} (A|B) = F(\Phi_{A^{\prime} A}.(\mathcal{I}_{A} \otimes \Lambda_{B \rightarrow A}^{\text{pg}}) (\rho_{AB})),
\]

and \( \Lambda_{B \rightarrow A}^{\text{pg}} \) is the pretty good recovery map. To see this, we note that the pretty good recovery map can be written as

\[
\Lambda_{B \rightarrow A}^{\text{pg}} (\cdot) = \frac{1}{d_{A}} \mathcal{E}_{B \rightarrow A}^{\text{pg}} (\rho_{B}^{-1/2} (\cdot) \rho_{B}^{-1/2}).
\]

where \( \mathcal{E}_{B \rightarrow A}^{\text{pg}} \) denotes the adjoint of the Choi-Jamikowski map of \( \rho_{AB}^{\text{pg}} \),

\[
\mathcal{E}_{A \rightarrow B} (\cdot) = d_{A} \text{Tr}_{A} [(\cdot)^{T} \otimes 1_{B} | \rho_{AB}].
\]

Putting this in (A2), we arrive at (A3). The map \( \Lambda_{B \rightarrow A}^{\text{pg}} \) is pretty good in the sense that it is close to optimal for recovering the

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maximally entangled state, i.e., we have [25]

\[ F^2(A|B) \leq F_{\text{pg}}(A|B) \leq F(A|B). \]  

(A6)

We also remark that both \( F(A|B) \) and \( F_{\text{pg}}(A|B) \) are nonincreasing under the action of local quantum channels acting on system \( B \) and local unitary (identity-preserving) quantum channels acting on system \( A \) (see, e.g., [21]).

\section{2. Uncertainty}

When measuring a bipartite quantum state \( \rho_{AB} \) on \( A \) in some basis \( K = \{|k\rangle\} \), we arrive at a classical-quantum state,

\[ \rho_{KB} = \sum_k \langle k|k\rangle \otimes B \rho_{AB}(|k\rangle \otimes B) \]  

(A7)

The conditional min-entropy of \( \rho_{KB} \), using the formula for \( F(K|B) \) from (A1), translates to

\[ H_{\min}(K|B) = -\log P_{\text{guess}}(K|B), \]  

with

\[ P_{\text{guess}}(K|B) = \max_{\{E_k\}} \sum_k \text{Tr}[E_k \rho_B^k] \]  

(A9)

the probability for guessing \( K \) correctly by performing the optimal measurement \( \{E_k\} \) on the quantum side information \( B \). The conditional min-entropy quantifies the uncertainty of \( K \) in the exact sense of the uncertainty game, namely, it quantifies the probability that Bob wins the uncertainty game.

The conditional Rényi 2-entropy of a classical-quantum state is again defined as in (A2). Furthermore, it was shown in [23] that its operational form (A3) is given by

\[ H_2(K|B) = -\log P_{\text{pg}}^{\text{guess}}(K|B), \]  

(A10)

where \( P_{\text{pg}}^{\text{guess}}(K|B) \) denotes the probability of guessing \( K \) by performing the pretty good measurement [24]. For the classical-quantum state (A7), the pretty good measurement operators are defined as

\[ \Pi_B^{k} = \rho_B^{-1/2} \rho_B^{k} \rho_B^{-1/2}. \]  

(A11)

By calculating \( P_{\text{pg}}^{\text{guess}}(K|B) = \sum_k \text{Tr}[\Pi_B^{k} \rho_B^{k}] \), the equivalence of (A10) to the definition of the conditional Rényi 2-entropy in (A2) can be seen. Hence, the conditional Rényi 2-entropy corresponds to the probability that Bob wins the uncertainty game by using the pretty good measurement. It is known that the pretty good measurement performs close to optimal, i.e., analogous to (A6), we have [24]

\[ P_{\text{pg}}^{\text{guess}}(K|B) \leq P_{\text{pg}}^{\text{guess}}(K|B) \leq P_{\text{pg}}(K|B). \]  

(A12)

In the following, we will not only measure in one fixed basis, but with equal probability in one of \( d_A + 1 \) MUBs. For that reason, we will work with the state

\[ \rho_{KB}(\theta) = \frac{1}{d_A + 1} \sum_{\theta=1}^{d_A + 1} (|\theta\rangle \langle \theta| \otimes I_B) \times \rho_{AB}(|\theta\rangle \langle \theta| \otimes I_B), \]  

(A13)

where the elements of the \( d_A + 1 \) MUBs \( \theta \) are denoted by \(|\theta\rangle\). It is straightforward to see that

\[ P_{\text{pg}}^{\text{guess}}(K|B)(\theta) = \frac{1}{d_A + 1} \sum_{\theta=1}^{d_A + 1} P_{\text{pg}}^{\text{guess}}(K|B) = \theta. \]  

(A14)

\section{APPENDIX B: PROOF OF MAIN RESULTS}

\subsection{1. Full set of mutually unbiased bases}

Here we prove our main result, the uncertainty equality (6). For this, we define \( \tilde{\rho}_{AB} = (1_A \otimes \rho_B^{-1/2}) \rho_{AB} (1_A \otimes \rho_B^{-1/2}) \) and rewrite the fully quantum conditional Rényi 2-entropy as \( H_2(A|B) = -\log \text{Tr}[(\tilde{\rho}_{AB}^2)^2] \). Similarly, we rewrite the classical-quantum conditional Rényi 2-entropy as

\[ H_2(K|B) \]  

\[ = -\log \left( \frac{1}{d_A + 1} \sum_{\theta=1}^{d_A + 1} \text{Tr}[(\tilde{\rho}_{AB}^2)^2] \right). \]  

(B1)

Now we introduce the space \( \mathcal{H}_{A'B'} \cong \mathcal{H}_{AB} \) as well as the state \( \tilde{\rho}_{A'B'} \cong \tilde{\rho}_{AB} \). We have

\begin{equation}
(d_A + 1) \times 2^{-H_2(K|B)(\theta)} = \sum_{\theta,k} \text{Tr}_B[\text{Tr}_A(|\theta\rangle \langle \theta| \otimes \tilde{I}_B) \tilde{\rho}_{AB} \text{Tr}_A(|\theta\rangle \langle \theta| \otimes \tilde{I}_B) \tilde{\rho}_{AB}] \tag{B2}
\end{equation}

\begin{equation}
= \sum_{\theta,k} \text{Tr}_{BB'} \text{Tr}_{AA'} [(|\theta\rangle \langle \theta| \otimes |\theta\rangle \langle \theta| \otimes \tilde{\rho}_{AB} \otimes \tilde{\rho}_{A'B'}) F_{BB'}] \tag{B3}
\end{equation}

\begin{equation}
= \text{Tr}_{BB'} \text{Tr}_{AA'} [(I_{AA'} + F_{AA'}) \tilde{\rho}_{AB} \otimes \tilde{\rho}_{A'B'} F_{BB'}] \tag{B4}
\end{equation}

\begin{equation}
= \text{Tr}_{BB'} \text{Tr}_{AA'} [(\tilde{\rho}_{AB} \otimes \tilde{\rho}_{A'B'}) F_{BB'}] + \text{Tr}_{BB'} \text{Tr}_{AA'} [F_{AA'} (\tilde{\rho}_{AB} \otimes \tilde{\rho}_{A'B'}) F_{BB'}] \tag{B5}
\end{equation}

\begin{equation}
= \text{Tr}_{B} (\text{Tr}_{A} (\tilde{\rho}_{AB} \text{Tr}_{A} (\tilde{\rho}_{AB})) + \sum_{t,s} \text{Tr}_{BB'} \text{Tr}_{AA'} [(|t\rangle \langle s| \otimes |t\rangle \otimes \tilde{I}_B) (\tilde{\rho}_{AB} \otimes \tilde{\rho}_{A'B'}) F_{BB'}] \tag{B6}
\end{equation}

\begin{equation}
= 1 + \sum_{t,s} \text{Tr}_B [\text{Tr}_A (|t\rangle \langle s| \otimes \tilde{I}_B) \tilde{\rho}_{AB}] + \text{Tr}_B [\text{Tr}_A (|s\rangle \langle t| \otimes \tilde{I}_B) \tilde{\rho}_{AB}] \tag{B7}
\end{equation}

\begin{equation}
= 1 + \text{Tr}[\tilde{\rho}_{AB}^2], \tag{B8}
\end{equation}

where \( F_{AA'} = \sum_{t,s} |t\rangle \langle s| \otimes |s\rangle \langle t| \) is the operator that swaps \( A \) and \( A' \) (similarly for \( F_{BB'} \)). The second line uses the “swap trick,” for operators \( M \) and \( N \), and swap operator \( F: \text{Tr}(MN) = \text{Tr}((M \otimes N)F) \). The third line invokes that a full set of MUBs generates
a complex projective 2-design [47], that is,
\[ \sum_{\theta, k} |\theta_k\rangle\langle \theta_k| \otimes |\theta_k\rangle\langle \theta_k| = I_{AA'} + F_{AA'}. \tag{B9} \]

In Appendix D1, we show that our result also holds for other measurements as long as they form a complex projective 2-design.

2. Fewer bases

Here, we derive the upper and lower bounds (14) and (15) on the uncertainty when Alice measures in \(1 \leq n < d_A + 1\) MUBs. It is helpful to first analyze the case for one basis \(K\).

**Lemma 1.** Let \(K = \{ |k\rangle \}\) be an orthonormal basis on some Hilbert space \(\mathcal{H}_A\). Then, we have for any bipartite quantum state \(\rho_{AB}\) that
\[ P_{\text{guess}}^{\text{PE}}(K|B) \geq P_{\text{guess}}^{\text{PE}}(A|B), \tag{B10} \]
where \(\rho_{KB} = \sum_k |k\rangle\langle k| \otimes 1_B \rho_{AB} |k\rangle\langle k| \otimes 1_B\).

**Proof.** We calculate
\[ P_{\text{guess}}^{\text{PE}}(K|B) = \text{Tr}[\rho_{KB}^{1/2} \rho_{KB}^{1/2} \rho_{KB}^{1/2}] \tag{B11} \]
\[ = \text{Tr}[\rho_{AB}^{1/2} \rho_{KB} \rho_{KB}^{1/2}] \tag{B12} \]
\[ = d_A \text{Tr}[\Phi_{AA'}(I_\mathcal{A} \otimes \Lambda_{B \rightarrow A}^{\text{PE}})(\rho_{KB})] \tag{B13} \]
\[ = F[\Phi_{AA'}(I_\mathcal{A} \otimes \Lambda_{B \rightarrow A}^{\text{PE}})(\rho_{AB})] \tag{B14} \]
\[ \geq F[\Phi_{AA'}(I_\mathcal{A} \otimes \Lambda_{B \rightarrow A}^{\text{PE}})(\rho_{AB})] \tag{B15} \]
\[ = P_{\text{guess}}^{\text{PE}}(A|B). \tag{B16} \]

The inequality step in this proof invoked the property that the fidelity decreases upon decreasing one of its arguments, and hence it remains to show
\[ d_A (I_\mathcal{A} \otimes \Lambda_{B \rightarrow A}^{\text{PE}})(\rho_{KB}) \geq (I_\mathcal{A} \otimes \Lambda_{B \rightarrow A}^{\text{PE}})(\rho_{AB}) \tag{B17} \]
We denote the non-negative operator \(\sigma_{AA'} = (I_\mathcal{A} \otimes \Lambda_{B \rightarrow A}^{\text{PE}})(\rho_{AB})\), and note that the measurement in \(K\) on the \(A\) system commutes with \(I_\mathcal{A} \otimes \Lambda_{B \rightarrow A}^{\text{PE}}\). We get
\[ d_A (I_\mathcal{A} \otimes \Lambda_{B \rightarrow A}^{\text{PE}})(\rho_{KB}) - (I_\mathcal{A} \otimes \Lambda_{B \rightarrow A}^{\text{PE}})(\rho_{AB}) \]
\[ = d_A \sum_k (|k\rangle\langle k| \otimes 1_A) \sigma_{AA'} (|k\rangle\langle k| \otimes 1_A) \]
\[ - \sum_{k,k'} (|k\rangle\langle k| \otimes 1_A) \sigma_{AA'} (|k\rangle\langle k| \otimes 1_A) \tag{B18} \]
\[ = (d_A - 1) \left[ \sum_k (|k\rangle\langle k| \otimes 1_A) \sigma_{AA'} (|k\rangle\langle k| \otimes 1_A) \right] \]
\[ - \left[ \frac{1}{d_A - 1} \sum_{k,k \neq k} (|k\rangle\langle k| \otimes 1_A) \sigma_{AA'} (|k\rangle\langle k| \otimes 1_A) \right] \tag{B19} \]
\[ = (d_A - 1) (\mathcal{F} \otimes I)(\sigma_{AA'}), \tag{B20} \]
where we set in the last line
\[ \mathcal{F} = \frac{1}{d_A - 1} \sum_{m=1}^{d_A - 1} Z^m \sigma(Z^m), \quad \sigma = \sum_{k=0}^{d_A - 1} \omega^k |k\rangle\langle k|, \tag{B21} \]
Since \(\mathcal{F}\) is a completely positive trace-preserving map, the claim follows.

Equation (B10) states that the entanglement fidelity quantified by \(P_{\text{guess}}^{\text{PE}}(A|B)\) lower bounds the guessing probability \(P_{\text{guess}}^{\text{PE}}(K|B)\). By combining (B10) with our uncertainty equality (6), we get that for subset of size \(1 \leq n \leq d_A + 1\) of a complete set of MUBs,
\[ \sum_{\theta=1}^n P_{\text{guess}}^{\text{PE}}(K|B \Theta = \theta) = (n - 1) P_{\text{guess}}^{\text{PE}}(A|B) + 1 + \left( d_A + 1 - n \right) P_{\text{guess}}^{\text{PE}}(A|B) - \sum_{\theta=n+1}^{d_A+1} P_{\text{guess}}^{\text{PE}}(K|B \Theta = \theta) \tag{B22} \]
\[ \leq (n - 1) P_{\text{guess}}^{\text{PE}}(A|B) + 1, \tag{B23} \]
and this proves (15). Similarly, we can invoke the immediate relation \(P_{\text{guess}}^{\text{PE}}(K|B) \geq 1/d_A\) to get
\[ \sum_{\theta=1}^n P_{\text{guess}}^{\text{PE}}(K|B \Theta = \theta) = d_A P_{\text{guess}}^{\text{PE}}(A|B) + \frac{n - 1}{d_A} + \left( d_A + 1 - n \right) P_{\text{guess}}^{\text{PE}}(A|B) - \sum_{\theta=n+1}^{d_A+1} P_{\text{guess}}^{\text{PE}}(K|B \Theta = \theta) \tag{B24} \]
\[ \leq d_A P_{\text{guess}}^{\text{PE}}(A|B) + \frac{n - 1}{d_A}, \tag{B25} \]
and this proves (14). The tightness of the bounds in (14) and (15) follows by construction. In the region \(P_{\text{guess}}^{\text{PE}}(A|B) \geq 1/d_A\), the upper bound is achieved by a bipartite pure state whose Schmidt basis is one of the \(\Theta\) bases appearing in the sum of guessing probabilities under consideration, and the lower bound is achieved by a bipartite pure state whose Schmidt basis is one of the \(\Theta\) bases that belongs to the same complete MUB set as the bases under consideration, but whose guessing probability was removed from the sum under consideration.
3. Monogamy of correlations

Here we show (18) from the main text. The precise statement is as follows.

**Corollary 1.** Let \( \{ \theta \}_0^{\theta_0} \) be a complete set of MUBs on some Hilbert space \( \mathcal{H}_A \), and denote \( \theta = |(\theta_i)_{k=1}^d \rangle \). Then, we have for any tripartite pure quantum state \( \rho_{ABE} \) that

\[
\inf_{\sigma} D_{\frac{1}{2}} \left( \rho_{AE} \| \frac{1}{d_A} \otimes \sigma_E \right) = \log d_A - \log \left[ (d_A - 1) P_{\text{guess}}^p (K \{ B \theta \}) - 1 \right].
\]

(B26)

where the infimum is over all quantum states \( \sigma_E \), and the relative Rényi \( 1/2 \)-entropy is given by

\[
D_{\frac{1}{2}} \left( \rho_{AE} \| \frac{1}{d_A} \otimes \sigma_E \right) = -\log \left\{ \text{tr} \left[ \rho^{1/2}_{AE} \left( \frac{1}{d_A} \otimes \sigma_E \right)^{1/2} \right] \right\}^2.
\]

(B27)

**Proof.** For any conditional entropy that is invariant under local isometries on the conditioning system, one can define a dual entropy. For some generic entropy \( H_K \), the dual entropy \( H^\text{dual}_K \) is defined by

\[
H_K(A|B) = -H^\text{dual}_K(A|E)_\theta,
\]

(B28)

where \( E \) is a system that purifies \( \rho_{AB} \). Since \( H(K|B) \) is invariant under local isometries on \( B \), the dual entropy is well defined, and it is known that [48]

\[
-H^\text{dual}_K(A|E) = \inf_{\sigma} D_{\frac{1}{2}} \left( \rho_{AE} \| \frac{1}{d_A} \otimes \sigma_E \right).
\]

(B29)

By the standard rewriting,

\[
D_{\frac{1}{2}} \left( \rho_{AE} \| \frac{1}{d_A} \otimes \sigma_E \right) = D_{\frac{1}{2}} \left( \rho_{AE} \| \frac{1}{d_A} \otimes \sigma_E \right) - \log d_A.
\]

(B30)

the claim follows from our main result (6).

**APPENDIX C: APPLICATIONS**

1. Witnessing entanglement

Here we show the origin of (17), our condition for witnessing entanglement. We will make use of the following lemma, which says that separable states cannot have a negative conditional entropy.

**Lemma 2.** Let \( \rho_{AB} \) be a separable quantum state. Then, we have

\[
H_2(A|B) \geq H_{\text{min}}(A|B) \geq 0.
\]

(C1)

**Proof.** The inequality \( H_2(A|B) \geq H_{\text{min}}(A|B) \) holds for any quantum state \( \rho_{AB} \) since \( \Lambda_{\text{PG}} \) in (A3) is a particular map, and the conditional min-entropy involves an optimization over all maps \( \Lambda_{B \rightarrow A'} \) in (A1).

To prove \( H_{\text{min}}(A|B) \geq 0 \), note that any local operation on a separable state results in another separable state. Now suppose \( \sigma_{AA'} = (I_A \otimes \Lambda_{B \rightarrow A'}) \rho_{AB} \) is the separable state that achieves the optimization when evaluating the conditional min-entropy for \( \rho_{AB} \) [i.e., \( \Lambda \) is the optimal channel in (A3)]. Then, we have

\[
F(A|B) = F(\Phi_{AA'}, \sigma_{AA'}) \leq F(\Phi_{AA'}, 1A \otimes \sigma_A) \leq 1/d_A,
\]

(C2)

which follows because the fidelity increases upon increasing one of its arguments, and for separable \( \sigma_{AA'} \) we have \( \sigma_{AA'} \leq 1A \otimes \sigma_A \) with \( \sigma_A = \text{Tr}_A(\sigma_{AA'}) \). Using \( H_{\text{min}}(A|B) = -\log d_A F(A|B) \), the claim follows.

Lemma 3. Let \( \rho_{AB} \) be a separable quantum state. Let \( \{ K_{\theta} \}_{\theta=1}^{\theta_0} \) be a subset of a complete set of MUBs on \( A \), and let \( \{ L_{\theta} \}_{\theta=1}^{\theta_0} \) be an arbitrary set of \( n \) orthonormal bases on \( B \). Then, we have

\[
\sum_{\theta=1}^n 2^{-H_2(K_{\theta}|L_{\theta})} \leq 1 + n - \frac{1}{d_A}.
\]

(C4)

where

\[
\rho_{K_{\theta}L_{\theta}} = \sum_{p,q} ( |K_{\theta,p} \rangle |\bar{K}_{\theta,p} \rangle \otimes |L_{\theta,q} \rangle |\bar{L}_{\theta,q} \rangle) \rho_{AB}
\]

\[
\times ( |K_{\theta,p} \rangle |\bar{K}_{\theta,p} \rangle \otimes |L_{\theta,q} \rangle |\bar{L}_{\theta,q} \rangle).
\]

(C5)

**Proof.** Since \( \rho_{AB} \) is separable, the previous lemma (Lemma 2) tells us that \( F^{\text{PG}}(A|B) \leq 1/d_A \). Combining this with the bound in (14), we have

\[
\frac{n-1}{d_A} + 1 \geq (n-1) F^{\text{PG}}(A|B) + 1
\]

(C6)

\[
\geq \sum_{\theta=1}^n P_{\text{guess}}^p (K_{\theta}|B) - 1
\]

(C7)

\[
= \sum_{\theta=1}^n 2^{-H_2(K_{\theta}|B)}
\]

(C8)

\[
\geq \sum_{\theta=1}^n 2^{-H_2(K_{\theta}|L_{\theta})},
\]

(C9)

where the last inequality follows because the conditional Rényi 2-entropy satisfies the data-processing inequality [21].

2. Quantum cryptography

Here we show the uncertainty and certainty relations (12) and (13) in terms of the smooth conditional min-entropy. For a bipartite quantum state \( \rho_{AB} \) and smoothing parameter \( \varepsilon \geq 0 \), the smooth conditional min-entropy is defined as

\[
H^\varepsilon_{\text{min}}(A|B)_\rho = \sup_{\tilde{\rho}_{AB}} H_{\text{min}}(A|B)_\rho,
\]

(C10)

where the supremum is over all subnormalized states \( \tilde{\rho}_{AB} \) on \( AB \) that are \( \varepsilon \)-close to \( \rho_{AB} \) in purified distance [49]. Now, the crucial point is that \( H^\varepsilon_{\text{min}} \) and \( H_2 \) are equivalent in the following sense: it holds for any bipartite quantum state \( \rho_{AB} \) and \( \varepsilon > 0 \) that (see, e.g., Lemma A.25 in [50])

\[
H_{\text{min}}(A|B) \leq H_2(A|B) \leq H^\varepsilon_{\text{min}}(A|B) + \log \frac{2}{\varepsilon^2}.
\]

(C11)

By combining (C11) with our main result (6), we obtain the uncertainty and certainty relation for the smooth conditional min-entropy as given in (12) and (13). We note that similar uncertainty relations have been derived in [18,51], and were used to analyze security in the noisy storage model.
APPENDIX D: EXTENSIONS OF MAIN RESULT

1. Complex projective 2-designs

We have seen in Appendix A that the proof of our uncertainty equality (6) crucially relies on the fact that a full set of MUBs generates a complex projective 2-design. In general, a complex projective 2-design is a set \(|\{\psi_y\}_{y \in Y}|\) of vectors \(|\psi_y\rangle|\) lying in a Hilbert space \(\mathcal{H}_A\) such that

\[
\frac{1}{|Y|} \sum_{y \in Y} |\psi_y\rangle\langle\psi_y|^{\otimes 2} = \frac{1}{d_A(d_A + 1)} (\mathbb{I}_{AA'} + F_{AA'}), \tag{D1}
\]

where \(F_{AA'}\) denotes the swap operator, and \(A'\) is a copy of \(A\). It turns out that there are other “informationally equivalent” measurements that generate a complex projective 2-design. As an example, we mention SIC-POVMs, such as the four states forming a tetrahedron on the Bloch sphere for qubits.

**Corollary 2.** Let \(\{\frac{1}{\sqrt{d_A}}|\psi_y\rangle|\langle\psi_y|\}_{y \in Y}\} \) be a SIC-POVM on some Hilbert space \(\mathcal{H}_A\). Then, we have for any bipartite quantum state \(\rho_{AB}\) that

\[
H_2(K|B) = \log(d_A(d_A + 1)) - \log(2^{-H_2(A|B)} + 1), \tag{D2}
\]

where

\[
\rho_{KB} = \sum_{k=1}^{d_A} |k\rangle\langle k| \otimes \text{Tr}_A \left[ \frac{1}{d_A} |\psi_k\rangle\langle\psi_k| \otimes \mathbb{1}_B \right] \tag{D3}
\]

is a classical-quantum state with \(|k\rangle\rangle\) an orthonormal basis on \(\mathcal{H}_K\).

Notice that the \(d_A\)-dependent term on the r.h.s. of (D2) is slightly different from the corresponding term appearing in our main result (6), and indeed (D2) implies that \(\log d_A \leq H_2(K|B) \leq 2 \log d_A\) for SIC-POVMs. Nevertheless, the proof of (D2) is identical to the proof of (6), with the appropriate version of (D1) substituted into the proof.

In addition, so-called unitary 2-designs are closely related to complex projective 2-designs. A set \(\{U_y\}_{y \in Y}\) (of size \(|Y|\)) of unitaries \(U_y\) on some Hilbert space \(\mathcal{H}_A\) forms a unitary 2-design if

\[
\frac{1}{|Y|} \sum_{y \in Y} (U_y \otimes U_y^\dagger)^{\otimes 2} = \int_{U(d_A)} (U \otimes U^\dagger)^{\otimes 2} dU, \tag{D4}
\]

where the integration is over all unitaries with respect to the Haar measure. Examples of unitary 2-designs are the full unitary group, or the Clifford group for qubit systems. In fact, unitary 2-designs generate complex projective 2-designs.

**Lemma 4.** Let \(\{U_{\theta}\}_{\theta \in \Theta}\) be a unitary 2-design on some Hilbert space \(\mathcal{H}_A\). Then, we have

\[
\frac{1}{d_A} \sum_{\theta \in \Theta} \sum_{k=1}^{d_A} (U_{\theta}|k\rangle\langle k|U_{\theta}^\dagger)^{\otimes 2} = \frac{1}{d_A(d_A + 1)} (\mathbb{I}_{AA'} + F_{AA'}), \tag{D5}
\]

where \(|k\rangle\rangle\) denotes some orthonormal basis of \(\mathcal{H}_A\).

Hence, our main result also holds for unitary 2-designs.

**Corollary 3.** Let \(\{U_{\theta}\}_{\theta \in \Theta}\) be a unitary 2-design on some Hilbert space \(\mathcal{H}_A\). Then, we have for any bipartite quantum state \(\rho_{AB}\) that

\[
H_2(K|B\Theta) = \log(d_A + 1) - \log(2^{-H_2(A|B\Theta)} + 1), \tag{D6}
\]

where

\[
\rho_{KB\Theta} = \frac{1}{|\Theta|} \sum_{\theta,k} (|\theta_k\rangle\langle\theta_k| \otimes \mathbb{1}_B) \rho_{AB} (|\theta_k\rangle\langle\theta_k| \otimes \mathbb{1}_B) \otimes |\theta\rangle\langle\theta|_\Theta, \tag{D7}
\]

and \(|\theta_k\rangle = U_{\theta}|k\rangle\) for some orthonormal basis \(|k\rangle\rangle\) of \(\mathcal{H}_A\).

2. More general entropies

Our main result (6) is in terms of the conditional Rényi 2-entropy. However, we can also prove it in terms of a more general continuous family of conditional 2-entropies. For \(\nu \in [0,1]\) and bipartite quantum states \(\rho_{AB}\), we define

\[
H_{2,\nu}(A|B) = -\log \text{Tr}[\rho_{AB}^{\nu}], \tag{D8}
\]

where

\[
\rho_{AB,\nu} = (\mathbb{1}_A \otimes \rho_B^{(-1-\nu)/4}) \rho_{AB} (\mathbb{1}_A \otimes \rho_B^{(-1+\nu)/4}). \tag{D9}
\]

It is easily seen that \(\nu = 0\) corresponds to the usual definition (A2) in the main text. We state the generalization of our uncertainty equality (6) for a full set of MUBs, but note that it also holds for all other “informationally equivalent” measurements (cf. Appendix D1).

**Corollary 4.** Let \(\{\theta\}_{\theta \in \Theta}\) be a complete set of MUBs on some Hilbert space \(\mathcal{H}_A\), and denote \(\Theta = \{|\theta_k\rangle\}_{k=1}^{d_A}\). Then, we have for any bipartite quantum state \(\rho_{AB}\) that

\[
H_{2,\nu}(K|B\Theta) = \log(d_A + 1) - \log(2^{-H_{2,\nu}(A|B\Theta)} + 1), \tag{D10}
\]

where

\[
\rho_{KB\Theta} = \frac{1}{d_A + 1} \sum_{\theta,k} (|\theta_k\rangle\langle\theta_k| \otimes \mathbb{1}_B) \otimes |\theta\rangle\langle\theta|_\Theta. \tag{D11}
\]

The proof is obvious by just taking the one for the conditional Rényi 2-entropy, and replacing \(\rho_{AB}\) with \(\rho_{AB,\nu}\).

It is worth noting that (D10) applies to the variant (used in, e.g., [52,53]),

\[
H_{2,1}(A|B) = -\log \text{Tr} \left[ \rho_{AB}^2 (\mathbb{1}_A \otimes \rho_B^{-1}) \right]. \tag{D12}
\]