Detecting polarized light from self-luminous exoplanets has the potential to provide key information about rotation, surface gravity, cloud grain size, and cloud coverage. While field brown dwarfs with detected polarized emission are common, no exoplanet or substellar companion has yet been detected in polarized light. With the advent of high contrast imaging spectro-polarimeters such as GPI and SPHERE, such a detection may now be possible with careful treatment of instrumental polarization. In this paper, we present 28 minutes of \(H\)-band GPI polarimetric observations of the benchmark T5.5 companion HD 19467 B. We detect no polarization signal from the target, and place an upper limit on the degree of linear polarization of \(p_{\text{C,L90.73\%}} \leq 2.4\%\). We discuss our results in the context of T dwarf cloud models and photometric variability.

**Key words:** brown dwarfs – stars: individual (HD 19467) – techniques: high angular resolution – techniques: polarimetric

1. INTRODUCTION

Recent imaging spectroscopy of directly imaged planets such as \(\beta\) Pic b, HR 8799 bcd, and 51 Eri b (Ingraham et al. 2014; Chilcote et al. 2015; Macintosh et al. 2015) has demonstrated that this technique will soon become routine. At the same time, these early studies have underscored the challenges of fitting atmospheric models based on field brown dwarf spectra to exoplanets with comparatively low masses and surface areas. In the modern era of exoplanet astronomy, at least 10 years of theoretical work have been devoted to the polarization of reflected starlight by a close-in, directly imaged exoplanet (Schmid et al. 2006; Stamm 2008; Buenzli & Schmid 2009). In this paper, we address a separate regime of exoplanet polarization: scattering by grains in the atmospheres of cloudy, self-luminous exoplanets, which induces the polarization of thermally emitted radiation in the near-infrared (Sengupta & Marley 2009; de Kok et al. 2011; Marley & Sengupta 2011). While Rayleigh scattering in the atmospheres of cloud-free exoplanets can polarize visible wavelength radiation, we concentrate on the case of approximately micron-sized dust grains that polarize infrared radiation, where young, self-luminous exoplanets emit the bulk of their radiation.

A perfectly spherical, uniformly cloudy planet, however, would have zero disk-integrated polarization. In order to produce a non-zero polarization signature when the planet is viewed as a point source, the clouds must be nonuniformly distributed (e.g., patchy or banded) and/or the body must be oblate (Basri 2000; Sengupta & Krishan 2001). Both of these characteristics have been invoked to explain the observed polarization of brown dwarfs in the field. Time-varying polarimetric signals indicate evolving or rotating nonuniform cloud distributions, while comparisons of fast and slow brown dwarf rotators show that oblate bodies are more likely to
Table 1

<table>
<thead>
<tr>
<th>HD 19467 A Properties</th>
<th>Value</th>
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<tbody>
<tr>
<td>J</td>
<td>5.801 ± 0.020</td>
</tr>
<tr>
<td>H</td>
<td>5.447 ± 0.036</td>
</tr>
<tr>
<td>K</td>
<td>5.401 ± 0.026</td>
</tr>
<tr>
<td>Mass (M_\odot)</td>
<td>0.95 ± 0.02</td>
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<tr>
<td>Radius (R_\odot)</td>
<td>1.15 ± 0.03</td>
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<tr>
<td>Luminosity (L_\odot)</td>
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<tr>
<td>T_{eff} (K)</td>
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<tr>
<td>SpT</td>
<td>G3V</td>
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<tr>
<td>d (pc)</td>
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<tr>
<td>Age, multiple techniques (Gyr)</td>
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<tr>
<td>(Fe/H)</td>
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<table>
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<tr>
<th>HD 19467 B Properties</th>
<th>Value</th>
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<tbody>
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</tr>
<tr>
<td>H</td>
<td>17.90 ± 0.11</td>
</tr>
<tr>
<td>K</td>
<td>17.97 ± 0.09</td>
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<tr>
<td>Mass (M_\odot)</td>
<td>≥51.9^{+0.36}_{−0.30}</td>
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<tr>
<td>T_{eff} (K)</td>
<td>978^{+38}_{−43}</td>
</tr>
<tr>
<td>SpT</td>
<td>T5.5 ± 1</td>
</tr>
<tr>
<td>Separation (AU, as)</td>
<td>51.1 ± 1.0, 1°65</td>
</tr>
</tbody>
</table>


produce observable polarimetric signals than spherical bodies (Ménard et al. 2002; Zapatero Osorio et al. 2005, 2011; Goldman et al. 2009; Tata et al. 2009; Miles-Páez et al. 2013). For example, Miles-Páez et al. (2013) found that 40 ± 15% of rapidly rotating (v sin i > 30 km s⁻¹) M7–T2 dwarfs are linearly polarized in the Z and J bands, with linear degrees of polarization of 0.4%–0.8%. The fastest rotators (v sin i > 60 km s⁻¹) were more frequently polarized, and had larger detected polarizations compared to moderate rotators (v sin i = 30–60 km s⁻¹). Furthermore, polarimetry in different broad wavelength bands has provided a diagnostic of grain sizes (Zapatero Osorio et al. 2005).

These field observations set the stage for exoplanet and brown dwarf companion polarimetry. Because models and field dwarf observations agree that the cloud-induced degree of linear polarization is generally p ≤ 1%, the observational challenge is to reach the companion-to-star contrast ratio and absolute polarimetric accuracy needed to detect such small signals. SPHERE (Beuzit et al. 2008) and GPI (Macintosh et al. 2008, 2014) are the first spectro-polarimeters capable of achieving contrasts <10⁻³ at separations <1″ and an absolute accuracy in the degree of linear polarization of p < 0.1% in the near-infrared (Wiktowicz et al. 2014). These instruments are poised to make the first detections of polarized light from substellar companions, providing a powerful new tool for atmospheric characterization.

In order to assess GPI’s accuracy in linear polarization for point sources, we observed the benchmark T dwarf HD 19467 B for 28 minutes of integration time on 2015 February 1st. HD 19467 B is unique among substellar companions in that it is the only T dwarf with a solar-analog primary to be detected both as a long-term trend in RV measurements and by direct imaging (Crepp et al. 2012). Recently, Crepp et al. (2015) determined a spectral type of T5.5 ± 1 and an effective temperature of T_{eff} = 978^{+43}_{−38} K (see Table 1 below) using the Project 1640 integral field spectrograph at the Palomar Observatory (Hinkley et al. 2011). While mid T dwarfs are generally thought to be cloudless, HD 19467 B was the only brown dwarf companion or exoplanet meeting GPI’s observability requirements (I < 9 parent star and planet–star separation <2″0) at the time of the pathfinder experiment.

We describe our observational methods and Stokes parameter extraction in Section 2. In Section 3, we measure the degree of linear polarization at the location of the companion and empirically estimate GPI’s polarimetric point source sensitivity. In Section 4, we place our results in the context of field T dwarf observations and discuss our upcoming GPI campaign for exoplanet polarimetry.

2. OBSERVATIONS AND DATA REDUCTION

We briefly summarize GPI’s polarimetric mode here; for details, see Macintosh et al. (2014), Wiktowicz et al. (2014), and Perrin et al. (2015). In polarimetry mode, a Wollaston prism replaces the integral field spectrograph’s dispersing prism, and an achromatic half waveplate is inserted between the coronagraph’s focal plane and the Lyot mask. In an observing sequence, the waveplate is rotated after each exposure in steps of 22°5. GPI operates in angular differential imaging (ADI) mode, allowing the sky to rotate with respect to the telescope pupil. The Stokes datacube [x, y, (I, Q, U, V)] describing the astronomical polarization is extracted from the raw data by inverting the Mueller matrix whose elements represent the polarization induced by the instrument and sky rotation. A detailed description of the Stokes cube extraction can be found in Perrin et al. (2015).

The observing sequence consisted of 28 60 s exposures in the H band, where each sequence of four exposures cycled through the waveplate angles 0°, 22°5, 45°0, and 67°5. The exposures were taken from Modified Julian Day 57054.0536728 to 57054.0773418 and the airmass ranged from 1.21 to 1.32. The total field rotation was 4°. The observations were taken under Gemini program number GS-2014B-Q-503.

In this study, the Stokes datacube was constructed from the raw data using a modified version of the publicly available GPI pipeline v1.2.1 (Maire et al. 2010; Perrin et al. 2014). Modifications, which will be released in a future version of the pipeline, included improved flat fielding and instrumental polarization subtraction. The latter was achieved by measuring the fractional polarization inside the coronagraphic mask, which was assumed to contain only diffraacted starlight affected by instrumental polarization, on each polarization difference cube. The instrumental polarization was then subtracted from the image as a whole, by multiplying the measured fractional polarization by the total intensity at each spatial location. This method was introduced by Millar-Blanchaer et al. (2015), who found similar instrumental polarization levels as those measured using the same data set by Wiktowicz et al. (2014). The method used in Wiktowicz et al. (2014) to estimate the instrumental polarization measures the fractional polarization in each frame using aperture photometry on the occulted point-spread function (PSF), and fits an instrumental polarization model that leverages the field rotation within their data set to distinguish between an astrophysical source and the instrumental polarization. The method used here and in Millar-Blanchaer et al. (2015) has the advantage of operating on each polarization datacube individually and, therefore, this method does not rely on sky rotation. While promising for point source
polarimetry data, techniques such as LOCI or the Proportional Counter Array (PCA) (Equation (1)) that take greater advantage of the sky rotation to reduce instrumental polarization are beyond the scope of this paper. Section 3 briefly describes how our results could be improved by these techniques.

Spurious pixels in the Stokes cube were replaced with values obtained by interpolation over pixels with counts greater than three standard deviations from the mean, and the detector’s gain of $3.04 \text{e}^{-/\text{ADU}}$ was applied to convert the raw counts to electrons (this gain is reported in the FITS headers of all GPI data cubes). The final reduced Stokes $I$, $Q$, and $U$ images are shown in Figure 1. The four bright areas in the corners of the Stokes $I$ frame (Figure 1(a)) are satellite spots used for photometric and astrometric calibration in GPI’s imaging spectroscopy mode.

HD 19467 B is readily visible on the righthand side of the Stokes $I$ frame, but is not apparent in the Stokes $Q$ or $U$ frames. In the next section, we will calculate the companion’s signal-to-noise ratio ($S/N$) in each Stokes frame, and comment on the degree of linear polarization at the companion’s location.

### 3. POLARIMETRIC ANALYSIS

A linearly polarized companion would produce a signal in the Stokes $Q$ and/or $U$ frames at the same location as the companion’s signal in the Stokes $I$ frame. In order to determine whether we detect polarized radiation from HD 19467 B, we must calculate the $S/N$ in an aperture at the companion’s location in each of the Stokes frames.

In order to choose the optimal aperture size, we first estimate the companion’s full width at half maximum (FWHM) in the Stokes $I$ frame by fitting the sum of a 2D Gaussian distribution and a plane to an $11 \times 11$ pixel ($\approx 3 \times 3$ FWHM) window around the companion’s PSF. The plane component was included to account for the shape of the parent star’s halo at the companion’s location. The FWHM is found to be 3.44 pixels, or $0''049$, which is consistent with the diffraction limit of $\lambda/D = 0''041$ in the $J$ band.

The optimal aperture size for photometry will maximize the companion’s $S/N$ in the Stokes $I$ frame. The “signal” is the difference of the sum of the counts inside the companion’s aperture and the contribution from the parent star’s residual

Figure 1. Reduced Stokes images with the ring of comparison apertures superimposed (the white arrow indicates the companion in Stokes $I$). The companion’s $S/N$ ($S/N$ is 7.4 in Stokes $I$, but $S/N < 1.0$ in Stokes $Q$ and $U$. Hence, no polarized radiation is detected from the companion.

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halo at the companion’s separation. This halo contribution is found by constructing a ring of apertures around the parent star at the same separation as the companion. These comparison apertures, shown in Figure 1, do not form a complete ring because the parent star was offset from the detector’s center to allow for more sky rotation of the companion. We also deleted those apertures that fall within an FWHM of the bright astrometric spots. Despite these removals, the effect of small sample statistics is negligible here (Mawet et al. 2014). For each aperture size, the total number of apertures is modified to prevent them from overlapping. We then sum the flux in each of these comparison apertures. A histogram of the Stokes $I$ aperture sums is shown in Figure 2(a). The histogram is asymmetric due to the competing effects of the modified Rician statistics governing speckle noise and the whitening of those statistics after ADI reduction. We take the parent star’s halo contribution to the flux inside the companion’s aperture to be the mean of the comparison apertures sums, $\mu_I$, and the noise to be the standard deviation of the comparison aperture sums, $\sigma_I$.

The $S/N$ is therefore

$$S/N = \frac{I_c - \mu_I}{\sigma_I} \tag{1}$$

where the $c$ subscript denotes the sum of the counts inside the companion’s aperture ($I_c = 26127.4e^-$). The signal-to-noise reached a maximum of $S/N_I = 7.4$ for an aperture diameter of $1 \times$ FWHM. The “aper” aperture photometry tool provided by the IDL Astronomy User’s Library was used to compute all aperture sums.

To calculate the $S/N$ in the Stokes $Q$ and $U$ frames, we use the same comparison aperture size and locations as in the Stokes $I$ frames. The histograms of the aperture sums in the Stokes $Q$ and $U$ frames are shown in Figures 2(b), (c). We take the parent star’s halo contribution to the flux inside the companion’s aperture in the $Q$ and $U$ frames to be the means of the aperture sums, $\mu_Q$ and $\mu_U$, and the noise terms to be the standard deviations $\sigma_Q$ and $\sigma_U$ of the aperture sums. Following Equation (1), we find that $Q_c = -99.0$ and $U_c = 41.7$, while...
compute the PDF of $Q$ and $U$ to be Gaussian distributions with means and standard deviations matching those of the $Q$ and $U$ aperture sums via maximum likelihood estimation. We compute the PDF of $\sqrt{Q^2 + U^2}$ using the formalism of Aalo et al. (2007), which considers the most general case of the PDF of $R = \sqrt{X_e^2 + X_s^2}$ where $X_e$ and $X_s$ are correlated real Gaussian random variables with means $\mu_e$, $\mu_s$ and standard deviations $\sigma_e$, $\sigma_s$. Aalo et al. (2007) first rotate $(X_e, X_s)$ through the angle $\phi$, chosen such that the new coordinates $(Y_1, Y_2)$ are uncorrelated:

$$Y_1 = X_e \cos \phi + X_s \sin \phi$$

$$Y_2 = -X_e \sin \phi + X_s \cos \phi$$

where $\rho$ is the correlation coefficient between $X_e$ and $X_s$. The full derivation of the PDF of $R$ is beyond the scope of this paper, but we quote the result here and refer to Aalo et al. (2007) for a more detailed treatment. The final PDF is given by

$$f_R(r) = \frac{r}{2\sigma_e\sigma_s} \exp \left[ -\frac{1}{2} \left( \frac{r^2}{2\sigma_e^2} + \frac{r^2}{2\sigma_s^2} + \frac{\mu_e^2}{\sigma_e^2} + \frac{\mu_s^2}{\sigma_s^2} \right) \right]$$

$$\sum_{n=0}^{\infty} \frac{\varepsilon_n I_n \left( \frac{r}{2\sigma_e} \right) \left( \frac{1}{\sigma_e^2} - \frac{1}{\sigma_s^2} \right)}{\varepsilon_{n+1} I_{n+1} \left( \frac{r}{2\sigma_s} \right) \left( \frac{1}{\sigma_e^2} - \frac{1}{\sigma_s^2} \right)} \left\{ \frac{\mu_e^2}{\sigma_e^2} + \frac{\mu_s^2}{\sigma_s^2} \right\}$$

$$\sum_{k=0}^{n} \frac{\delta_k C_k \left( \frac{\mu_e^2}{\sigma_e^2} \right)^2 - \left( \frac{\mu_s^2}{\sigma_s^2} \right)^2}{\left( \frac{\mu_e^2}{\sigma_e^2} + \frac{\mu_s^2}{\sigma_s^2} \right)^{n-k}} \left( 2(\mu_1\mu_2 \sigma_1^2 \sigma_2^2) \right)^k$$

(4)

where $\mu_1$, $\mu_2$ and $\sigma_1$, $\sigma_2$ are the mean and standard deviations of $Y_1$ and $Y_2$, $\varepsilon_{n=0} = 1$ and $\varepsilon_{n=0} = 2$, $\delta_{k=0} = 0$ and $\delta_{k=0} = 2(-1)^{k/2}$. $C_k$ is the binomial coefficient, and $I_n$ is the $n$th order modified Bessel function of the first kind. We find that Equation (4) gives consistent results to within machine precision after five terms.

We find that the PDF of $\sqrt{Q^2 + U^2}$ is negligibly affected by the assumption that $U$ and $Q$ are uncorrelated. The PDF is fit by a Hoyt distribution, which is equivalent to Equation (4) for the special case of $\mu_Q = \mu_U = 0$.

To find the PDF of $p = \sqrt{Q^2 + U^2} / I$, we first assume that $\sqrt{Q^2 + U^2}$ and $I$ are uncorrelated. The PDF of $I$ represents the distribution of companion intensity values, and is therefore taken to be the counts in the companion’s aperture, $I_c$, minus the distribution of counts in the comparison apertures. The comparison apertures’ Stokes $I$ distribution is influenced by both the modified Ricean distribution governing speckle statistics and the whitening effects of ADI. Hence, we take $p(i)$ to be the skewed Gaussian distribution fit to the histogram of $I_c$—aperture $I$ sums shown in Figure 2(a). Because the width, $\sigma_r$, of Figure 2(a) is $>10$ times larger than $\sqrt{I_c}$, the contribution of the companion’s poisson noise to $p(i)$ is neglected. For $R = \sqrt{Q^2 + U^2}$, the CDF of $p = R/I$ is the probability that $R/I$ is less than a given value of $p$, or

$$F_p(p) = P(R/I < p)$$

(5a)

$$F_p(p) = \int_{0}^{p} \int_{r=-\infty}^{\infty} f_R(r, i) dr di$$

$$+ \int_{r=-\infty}^{p} \int_{i=-\infty}^{\infty} f_R(r, i) dr di.$$

(5b)

Differentiating with respect to $p$ gives the final PDF of the linear polarization fraction:

$$f_p(p) = \int_{-\infty}^{\infty} |l| f_R(lp) f_i(i) di.$$  (6)

The calculated values of $f_p(p)$ and several fitted distributions are shown Figure 3. We find that $f_p(p)$ is best fit by a Hoyt distribution. Table 2 lists the upper limits to the linear polarization fraction, corresponding to three representative confidence intervals calculated using the fitted Hoyt
distribution. We emphasize that our analysis described in this section is distinct from that of disk polarimetry, which benefits from the assumption that light scattered by a disk is polarized in the direction perpendicular to the direction toward the central star. To our knowledge, this work presents the first analysis of point source polarimetric precision using a high contrast, integral field polarimeter.

We now return to the question of how our limiting polarization fraction would be affected by greater sky rotation and algorithms such as PCA (Soummer et al. 2012) and LOCI (Lafrenière et al. 2007) that help attenuate quasi-static speckles caused by instrumental effects. The shape of the polarization fraction’s PDF is governed by the PDFs of the Stokes $I$, $Q$, and $U$ histograms shown in Figure 2. The width of the Stokes $I$ PDF is larger than expected based on photon noise alone—the standard deviation of the aperture values is $1479.6\mu$ , while the square root of the mean is $104.7\mu e^-$. This extra width is primarily due to speckle noise, which increases the distribution’s standard deviation and skewness (Marois et al. 2008a). Because speckles are mostly unpolarized, however, their flux is attenuated in the Stokes $Q$ and $U$ frames. Visual inspection of the polarized channels in Figure 1 confirm that speckles, and hence speckle noise, are not present at the companion’s separation. Indeed, Perrin et al. (2015) demonstrate that in GPI’s polarimetric mode, the polarized intensity, $\sqrt{Q^2 + U^2}$, at HD 19467 B’s separation of $1''65$ is dominated by photon noise (see also Oppenheimer et al. 2008 and Hinkley et al. 2009). Hence, greater sky rotation and PSF subtraction techniques would reduce the contribution of speckle noise to the PDF of Stokes $I$, but would not significantly affect the PDFs of Stokes $Q$ and $U$. To assess the contribution of non-photon noise to our $p$ upper limits, we replace the PDF of Stokes $I$ values shown in Figure 2(a) with a poisson distribution of $\mu = \mu_1$. The resulting $p$ upper limits are 0.9%, 1.8%, and 2.7%, for the confidence intervals of 68.27%, 99.73%, and 99.9999%, respectively. Speckle reduction techniques would therefore provide some improvement to our limiting polarization fraction, but our assessment is dominated by the noise in the polarized channels.

4. DISCUSSION

Recent observations of photometric variability outside the $L$/$T$ transition hint at the presence of cloud variability that might lead to a non-zero polarization signatures in a T5.5 dwarfs such as HD 19467 B: Radigan et al. (2014) detected J-band 1.6% peak-to-peak variability in a red T6.5 dwarf, and 0.6%–0.9% variability in three additional T dwarfs later than T3.5 without remarkably red colors. Photometric monitoring at 3–5$\mu$m with Spitzer revealed that 19%–62% of T0–T8 dwarfs vary with peak-to-peak amplitudes $>0.4\%$, with T0–T3.5 objects in the $L$/$T$ transition showing no higher incidence of variability than later type T dwarfs (Metchev et al. 2015). The source of this variability may be due to variations in cloud coverage and thicknesses, or “patchy” clouds. While it has recently been suggested that temperature variations driven by atmospheric changes below the cloud layer may also contribute to photometric variability (e.g., Robinson & Marley 2014), Apai et al. (2013) and Radigan et al. (2012) have shown that temperature fluctuations alone cannot reproduce the observed amplitudes of variability.

The results of these photometric surveys suggests that even outside the $L$/$T$ transition, T dwarfs commonly have time-varying cloud and spot weather patterns. These variations may produce polarized intensity: de Kok et al. (2011) show that a fixed hotspot on the surface of an otherwise uniform cloudy dwarf produces a higher amplitude of polarimetric variability as a function of time than flux variability. The difficulty of detecting a linear degree of polarization of less than 1.0%, however, has prevented observers from testing this theoretical link between photometric and polarimetric variability. For example, SIMP J013656.57+$093347.3$ is a T2.5 dwarf with periodic large amplitude (50 mmag) variability, which is explained by invoking cool dusty cloud patches against a warmer clear background (Artigau et al. 2006, 2009). However, Zapatero Osorio et al. (2011) find no polarization and place an upper limit of $p < 0.9\%$ on the $J$-band degree of linear polarization.

In fact, only two T dwarfs have published near-infrared polarimetric observations: the aforementioned SIMP J013656.57+$093347.3$ T2.5 dwarf observed by Zapatero Osorio et al. (2011), and 2MASS J12545393–0122474, a T2 dwarf observed by Miles-Páez et al. (2013) with a linear degree of polarization of $p = 0.00\% \pm 0.34\%$. Our observations of HD 19467 B constitute the third polarimetric observation of a T dwarf, and the third null result. We also note that our upper limit of $p_{CL,99.73\%} \leq 2.4\%$ is within a factor of a few of the previously mentioned T-dwarf upper limits, demonstrating that high contrast, integral field polarimeters are approaching the performance of direct polarimetric imaging modes. While these null results could be due to unfavorable viewing angles or insufficient detection limits, it is also possible that these T dwarfs are simply cloudless, and hence would not polarize infrared radiation. Multiple scattering polarization models for cloudless T dwarfs indicate negligible polarization signals at wavelengths longer than 6$\mu$m at a range of inclinations and rotational velocities (Sengupta & Marley 2009). These results are consistent with non-detections of near-infrared T dwarf polarization.

Clearly, more targets must be observed at higher polarimetric precisions in order to draw meaningful conclusions about the cloud properties of brown dwarfs and exoplanets. Our upper limit of $p_{CL,99.73\%} \leq 2.4\%$ is within a factor of a few of the predicted $p \leq 1.0\%$ signature of a cloudy, oblate body (Marley & Sengupta 2011), suggesting that GPI is capable of detecting polarized radiation from substellar companions given sufficient integration times to reduce photon noise in the polarized channels. To this end, our group is actively pursuing a GPI program to observe several exoplanet and brown dwarf companions at the predicted $p \leq 1.0\%$ level. Observing multiple targets will reduce the risk of non-detections resulting from unfavorable viewing angles, and may shed light on the diversity of low-mass polarimetric properties.

5. CONCLUSION

We observed the T5.5$\pm1$ dwarf HD 19467 B in the $H$ band for 28 minutes on 2015 February 1st using the Gemini Planet Imager’s polarimetry mode. We detect no polarization signal from the target and place an upper limit on the degree of linear polarization of $p_{CL,99.73\%} \leq 2.4\%$. Because this limit is larger than the predicted $p \leq 1.0\%$ signature of a cloudy, oblate body, we cannot constrain the atmospheric properties of HD 19467 B from this measurement. Our method for analyzing point source
polarimetry data, however, will be applied to our upcoming GPI survey for which we expect to reach \( p \leq 1.0\% \) for multiple exoplanet and brown dwarf companions.

The future of exoplanet polarimetry is promising. Because the breakup of clouds usually associated with the L/T transition occurs at lower temperatures for lower surface gravity objects, exoplanet polarimetry signals will likely benefit from the surface asymmetries introduced by patchy clouds. Indeed, Radigan et al. (2014) show that HR 8799 c falls near the highest amplitude photometric variables in NIR color–magnitude diagrams, a region populated by L/T transition objects.

With the advent of modern high contrast spectro-polarimeters such as GPI and SPHERE, we are entering a new era of complementary photometric and polarimetric observations of exoplanets and brown dwarf companions. Future exoplanet polarimetric detections have the power to inform cloud particle size distributions at different pressures and corroborate the interpretations of L and T photometric survey results. Brown dwarf and exoplanet atmosphere models are currently limited by our understanding of cloud physics and its effects on observables; polarimetry is an as-yet unexploited tool to fill in these gaps.

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