



Survival Times of Supramassive Neutron Stars Resulting from Binary Neutron Star Mergers

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Abstract

A binary neutron star (BNS) merger can lead to various outcomes, from indefinitely stable neutron stars, through supramassive neutron stars (SMNSs) or hypermassive neutron stars supported only temporarily against gravity, to black holes formed promptly after the merger. Up-to-date constraints on the BNS total mass and the neutron star equation of state suggest that a long-lived SMNS may form in $\sim 0.45\text{--}0.9$ of BNS mergers. A maximally rotating SMNS needs to lose $\sim (3\text{--}6) \times 10^{52}$ erg of its rotational energy before it collapses, on a fraction of the spin-down timescale. An SMNS formation imprints on the electromagnetic counterparts to the BNS merger. However, a comparison with observations reveals tensions. First, the distribution of collapse times is too wide and that of released energies too narrow (and the energy itself too large) to explain the observed distributions of internal X-ray plateaus, invoked as evidence for SMNS-powered energy injection. Second, the immense energy injection into the blast wave should lead to extremely bright radio transients, which previous studies found to be inconsistent with deep radio observations of short gamma-ray bursts (GRBs). Furthermore, we show that upcoming all-sky radio surveys will constrain the extracted energy distribution, independently of a GRB jet formation. Our results can be self-consistently understood, provided that most BNS merger remnants collapse shortly after formation (even if their masses are low enough to allow for SMNS formation). This naturally occurs if the remnant retains half or less of its initial energy by the time it enters solid-body rotation.

Unified Astronomy Thesaurus concepts: [Gamma-ray bursts \(629\)](#); [Neutron stars \(1108\)](#); [Gravitational waves \(678\)](#)

1. Introduction

The electromagnetic (EM) appearance of binary neutron star (BNS) mergers depends strongly on the nature and evolution of the post-merger remnant, which in turn depends on the component masses and the equation of state (EOS) of matter in the deep interior of neutron stars (NSs; Shibata & Hotokezaka 2019). Numerical simulations of the gravitational wave (GW) driven dynamical merger process show that the initial remnant is supported against gravitational collapse by strong differential rotation and partially by thermal pressure (Shibata & Taniguchi 2006; Baiotti et al. 2008; Sekiguchi et al. 2011; Hotokezaka et al. 2013; Kaplan et al. 2014; Kiuchi et al. 2014). Subsequently, the system evolves on the viscous timescale that is roughly $\alpha^{-1} \lesssim 100$ times longer than the rotational period of ~ 1 ms, where the Shakura & Sunyaev (1973) dimensionless viscosity parameter is found to be $\alpha \gtrsim 10^{-2}$ in the outer envelope of the remnant NS as given by magnetohydrodynamic (MHD) turbulence (Kiuchi et al. 2018). However, simulations have not been able to capture the full range of length scales and physical processes needed to understand the transport of angular momentum by, e.g., Kelvin–Helmholtz and magnetorotational instabilities (e.g., Kiuchi et al. 2014; Ciolfi et al. 2019). A simpler approach is to carry out (two-dimensional) viscous hydrodynamic simulations, under the assumption that subgrid MHD processes operate efficiently to generate a macroscopic viscosity (e.g., Radice 2017; Shibata et al. 2017b; Fujibayashi et al. 2018). It is found that the outer envelope viscously spreads into a torus, which contains $\sim 0.1 M_{\odot}$ and a large fraction of the angular momentum. However, the evolution of the rotational profile of the NS (e.g., how it approaches uniform rotation) and the share of angular momentum between the NS and the torus are highly uncertain, as

they depend sensitively on the choice of viscosity prescriptions. On longer timescales ~ 1 s, neutrino cooling removes thermal energy ($\sim 0.05 M_{\odot} c^2$), increases the central density of the NS, and may cause marginally stable systems to collapse. If at the end of this phase the NS has a sufficiently low mass and sufficiently high angular momentum, it will likely settle into uniform rotation and become a supramassive NS (SMNS), supported against gravity by its fast rotation.

Observations of NSs near two solar masses in a number of sources (Demorest et al. 2010; Antoniadis et al. 2013; Cromartie et al. 2020) suggest that the pressure above nuclear saturation density of 2.8×10^{14} g cm $^{-3}$ must be sufficiently high such that the maximum mass of nonrotating NSs, M_{max} , is greater than $2 M_{\odot}$.⁴ Centrifugal support due to uniform rotation allows the maximum mass to be up to about 20% higher than that of the nonrotating spherical configuration (e.g., Cook et al. 1994; Breu & Rezzolla 2016). This means that a fraction of BNS merger remnants, at least the ones⁵ $\lesssim 2.4 M_{\odot}$ (and possibly even higher-mass ones), could be spinning sufficiently rapidly as SMNSs, which undergo secular spin-down on longer timescales $\gg 1$ s.

Magnetic spin-down from a long-lived ($\gg 1$ s) SMNS or stable NS provides a powerful source of energy injection, which has an important impact on the EM counterparts of BNS

⁴ It has been argued that EM observations of GW170817 place an upper limit of $M_{\text{max}} \lesssim 2.3 M_{\odot}$ (Granot et al. 2017; Margalit & Metzger 2017; Shibata et al. 2017a; Rezzolla et al. 2018).

⁵ For instance, the PSR J1946+2052 BNS system (total mass $2.5 \pm 0.04 M_{\odot}$; Stovall et al. 2018) is expected to produce an SMNS, after accounting for mass loss of a few percent M_{\odot} or more due to baryonic kilonova ejecta (e.g., Radice et al. 2018b) and then $\sim 0.1 M_{\odot}$ from GW and neutrinos (Hotokezaka et al. 2013; Bernuzzi et al. 2016).

mergers. For instance, the baryonic ejecta may be strongly heated by the nonthermal radiation from the pulsar wind nebulae and produce a UV–optical transient that is much brighter than the traditional radioactive-decay-powered kilonova/macronova (Kasen & Bildsten 2010; Yu et al. 2013; Metzger & Piro 2014). The nonthermal radiation in the nebula may escape the ejecta when the bound-free optical depth is less than unity, generating X-ray emission at the level of the spin-down luminosity lasting for a spin-down time or until the SMNS collapses into a black hole (BH; Zhang 2013; Metzger & Piro 2014; Murase et al. 2018). It has also been proposed that the long-lasting plateaus seen in the X-ray light curve of some short gamma-ray bursts (GRBs) are produced by the nebula emission (Rowlinson et al. 2010; Dall’Osso et al. 2011; Metzger et al. 2011). On the other hand, the ejecta acquires a large kinetic energy comparable to the rotational energy of SMNS, and when decelerated by the surrounding medium, it produces bright multiband afterglow emission (Gao et al. 2013; Metzger & Bower 2014).

In this paper, we study the distributions of the survival time and the emitted energy from SMNSs prior to the collapse, crucial ingredients for determining the EM counterparts of such systems (see, e.g., Ravi & Lasky 2014). The goal is to make predictions based on known information (Galactic BNS statistics, LIGO observations, current EOS constraints; Sections 2 and 3) and then compare with observations (Section 4). We will show that these different components, brought together, reveal a tension. The implications that could provide insights into the early stages of the merger remnant’s evolution and its stability are discussed in Section 5.

2. Method

As we are interested in systems surviving for timescales longer than the GRB prompt duration, we focus on cold and uniformly rotating NSs, assuming that the differential rotation has subsided (on timescale of ~ 0.1 s) and neutrino cooling has ended (on timescale of ~ 1 s). We apply realistic EOSs using the rms code (Stergioulas & Friedman 1995)⁶ to simulate asymmetric models of uniformly rotating cold NSs⁷ and consider different energy-loss mechanisms. The latter is typically dominated by dipole spin-down, which in turn depends on the magnetic field strength on the merger remnant’s surface.

Our calculation proceeds as follows. We consider first the observed sample of 11 Galactic binary systems with well-determined individual gravitational masses (listed in Table 1) to simulate (gravitational) chirp masses and secondary-to-primary mass ratios: $M_{\text{ch}}, q \equiv M_2/M_1 \leq 1$ according to observations.⁸ The observed sample can be described by independent distributions. M_{Ch} is fit by a normal distribution with $\mu_{M_{\text{Ch}}} = 1.175M_{\odot}$,

⁶ <http://www.gravity.phys.uwm.edu/rms/>

⁷ To avoid models that are unstable against radial perturbations, we only use models that have a central energy density below a critical value defined by the requirement that it leads to the maximum mass of a nonrotating star (Stergioulas & Friedman 1995).

⁸ The cosmological distribution of BNS masses may be different between the Galactic population and the cosmological one. For example, it is reasonable to expect that the NS masses could be sensitive to the metallicity, which for cosmological events would span a wider range than for the relatively young Galactic BNS population. However, this will tend to widen the distribution of survival times and therefore strengthen our results discussed below. Taking the Galactic distribution as a proxy is thus a conservative choice for the purposes of this analysis.

Table 1
Galactic Binary Neutron Stars with Well-determined Individual Masses

System	$M_1 (M_{\odot})$	$M_2 (M_{\odot})$	References
J0737–3039	1.338	1.249	Kramer et al. (2006)
J1906+0746	1.323	1.291	Lorimer et al. (2006)
J1756–2251	1.341	1.23	Faulkner et al. (2005)
B1913+16	1.44	1.389	Weisberg et al. (2010)
B1534+12	1.346	1.333	Stairs et al. (2002)
J1829+2456	1.306	1.299	Champion et al. (2005)
J1518+4904	1.41	1.31	Janssen et al. (2008)
J0453+1559	1.559	1.174	Martinez et al. (2015)
J1913+1102	1.62	1.27	Lazarus et al. (2016)
J1757–1854	1.3946	1.338	Cameron et al. (2018)
J0509+3801	1.46	1.34	Lynch et al. (2018)

Note. To be consistent with the notation adopted in Section 2, we denote by M_1 the more massive of the NSs in the binary. This should not be confused with a standard notation in binary pulsar literature, by which M_1, M_2 are used to distinguish the observed pulsar from its companion.

$\sigma_{M_{\text{Ch}}} = 0.044M_{\odot}$. The parameter $\tilde{q} = (1 - q)/q$ can be fit with an exponential distribution with $\lambda_{\tilde{q}} = 0.0954$. This description ensures that $0 \leq q \leq 1$. M_{ch}, q are used to calculate M_1, M_2 according to

$$M_1 = M_{\text{Ch}} q^{-3/5} (1 + q)^{1/5}, \quad M_2 = qM_1. \quad (1)$$

While the directly measured quantity for an individual NS is its gravitational mass, it is useful to consider the equivalent baryonic mass, as the total baryonic mass is conserved during the merger. The gravitational masses M_1, M_2 are converted to baryonic masses $M_{1,0}, M_{2,0}$ using the assumed EOS, under the assumption of zero spin for the individual NSs (this is consistent with the rotation frequencies of Galactic BNS pulsars, which are well below breakup). During the merger, some of the mass is ejected in the form of dynamical ejecta and disk winds. We use the estimates for the (baryonic) mass of the ejecta, $M_{\text{ej},0}$, as a function of M_{ch}, q given by Margalit & Metzger (2019) and Coughlin et al. (2019) based on fits to numerical relativity simulations. The baryonic mass of the remnant is then simply given by $M_0 = M_{1,0} + M_{2,0} - M_{\text{ej},0}$.

For a given EOS, we find the maximum baryonic mass of a nonrotating star, $M_{\text{max},0}$, and of a star rotating at the mass-shedding limit, $M_{\text{th},0}$. For a given M_0 , there are three possibilities. First, $M_0 > M_{\text{th},0}$. This leads either to a hypermassive NS (HMNS), supported only by differential rotation and/or thermal pressure, or, for still higher masses, to a prompt collapse. In either case, the result is a very short survival time (assumed below to be ~ 0.1 s). The second possibility is $M_0 < M_{\text{max},0}$. In this case the NS is infinitely stable. The third case is obtained for $M_{\text{max},0} < M_0 < M_{\text{th},0}$. This is an interesting case, resulting in a finite survival time that we describe in more detail next.

For $M_{\text{max},0} < M_0 < M_{\text{th},0}$ we construct NS models with the specified EOS such that they have a constant baryonic mass, M_0 , and different rotation rates. We also calculate the maximum extractable energy $E_{\text{ext}} = E_{\Omega, \text{max}}(M_0) - E_{\Omega, \text{min}}(M_0)$ (see also Metzger et al. 2015a), which is the rotational energy that the NS can lose before it is forced to collapse ($E_{\Omega, \text{max}}(M_0)$ is the rotational energy of a maximally rotating NS with baryonic mass M_0 and $E_{\Omega, \text{min}}(M_0)$ is the minimum rotational energy required for this NS to support itself against collapse). An example of a track with constant baryonic mass in the plane of gravitational mass and rotational energy is shown in Figure 1. As a limiting case we

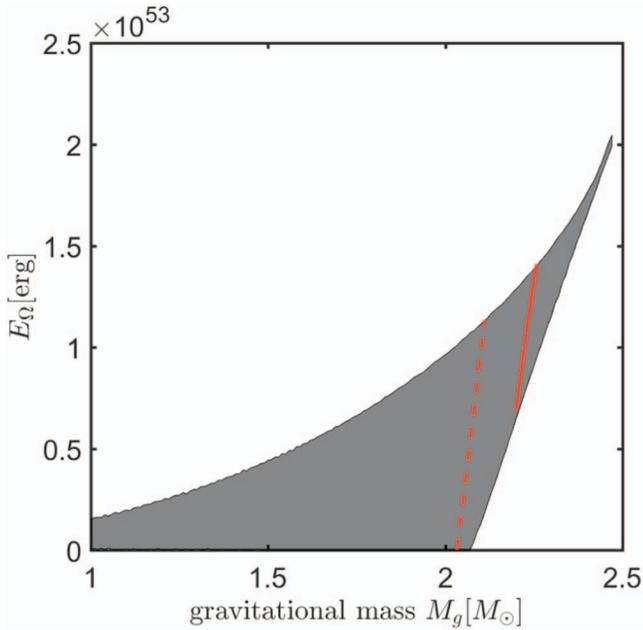


Figure 1. The shaded region depicts allowed solutions (confined by the energy at the mass-shedding limit from above and by the minimum required energy for solid rotation from below) for cold uniformly rotating NSs in the plane of gravitational mass and NS rotational energy. The red solid (dashed) line represents a constant baryonic mass of $M_0 = 2.6 M_\odot$ ($M_0 = 2.4 M_\odot$), corresponding to a gravitational mass of $M_g = 2.26 M_\odot$ ($M_g = 2.11 M_\odot$) at the mass-shedding limit. Results shown here are for the SLy EOS (Douchin & Haensel 2001).

assume first that the remnant begins maximally rotating (i.e., at the mass-shedding limit; Giacomazzo & Perna 2013). Although possibly unrealistic, this is a constructive limit, as lower initial rotation speeds will lead to a quicker collapse and less SMNSs. This second possibility, that the remnant loses a significant amount of its rotational energy while it is differentially rotating, is explored in Section 3.1, in which we consider an SMNS that enters the cold uniform rotation stage with its rotational energy reduced to $\leq 0.5E_{\Omega, \max}(M_0)$. Such a situation is in line with the general relativistic magnetohydrodynamics (GRMHD) simulations by Ciolfi et al. (2019), which suggest that the rotational energy at this stage is $\lesssim 0.1E_{\Omega, \max}(M_0)$.

The remnant then spins down according to magnetic dipole radiation, \dot{E}_D , and gravitational quadrupole radiation, \dot{E}_G ,

$$\dot{E}_\Omega = I\Omega\dot{\Omega} + 0.5I\Omega^2 = \dot{E}_D + \dot{E}_G \quad (2)$$

$$\dot{E}_D = -\frac{B_p^2 R^6 \Omega^4}{6c^3} \quad (3)$$

$$\dot{E}_G = -\frac{32I^2 \epsilon^2 G \Omega^6}{5c^5}. \quad (4)$$

Here I is the NS moment of inertia, Ω is its spin frequency, B_p is the surface strength of the magnetic field (assumed to be comparable to the poloidal field strength; see Reisenegger 2001), we have assumed an aligned rotator for \dot{E}_D , and ϵ is the fractional deformation of the NS. The latter can be dominated by different physical effects. One specific deformation mechanism is due to the magnetic field and given by

$$\epsilon = \beta \frac{R^4 B_\phi^2}{GM^2}, \quad (5)$$

where M is the gravitational mass of the NS remnant, B_ϕ is the volume-averaged magnetic field (which we have assumed to be dominated by the toroidal field, which can be somewhat greater than B_p), and $\beta \ll 1$. Requiring that the NS interior is stable puts a limit on the field ratio, which can be written as (Akgün et al. 2013)⁹

$$\frac{B_\phi}{B_p} \lesssim 10 \left(\frac{M}{2M_\odot} \right)^{1/2} \left(\frac{R}{10 \text{ km}} \right)^{-1} \left(\frac{B_p}{10^{16} \text{ G}} \right)^{-1/2}. \quad (6)$$

Therefore, we take $B_\phi = 10B_p$, as well as $\beta = 0.01$ for our canonical calculation. For this choice we find that the magnetic dipole radiation dominates the spin-down. Indeed, taking into account the stability condition above, we find

$$\frac{|\dot{E}_G|}{|\dot{E}_D|} \lesssim \beta^2 I_{45.5}^2 \left(\frac{M}{2.5M_\odot} \right)^{-2} \left(\frac{R}{10 \text{ km}} \right)^{-2} \left(\frac{P}{0.6 \text{ ms}} \right)^{-2}, \quad (7)$$

where $I_{45.5} = \frac{I}{10^{45.5} \text{ g cm}^2}$. This equation shows that even for $\beta = 1$ and rapid initial rotations, stability of the magnetic field configuration implies that GW losses are comparable or subdominant to dipole EM losses. We discuss the implications of deviations from these limitations in Section 3.

The values of R , M , and I depend in general on both the (fixed) M_0 and the (evolving) spin rate and are estimated directly from the rns models at each time step. Ω is evolved according to Equation (2) until the amount of extracted energy equals E_{ext} and the NS collapses. The time elapsed by this point is denoted t_{survive} . This calculation is repeated 10^4 times (each time drawing different parameters from the chirp mass and mass ratio distributions), in order to obtain the distribution of t_{survive} , E_{ext} values consistent with Galactic BNS systems.

3. Results

In Figure 2 we show the distribution of extracted energies and survival times for different EOSs and different surface magnetic field strengths. We consider in particular the SLy EOS (Douchin & Haensel 2001), which is consistent with available observational constraints on the mass–radius curve of NSs (Coughlin et al. 2019). As a comparison case, we consider also the WFF2 EOS (Wiringa et al. 1988). The maximum masses of nonrotating NSs with these EOSs are $M_{\text{max}} = 2.05$ (SLy) and $M_{\text{max}} = 2.2$ (WFF2). These EOSs therefore roughly bracket the allowed range of maximum masses allowed by observations. A large fraction ($\sim 45\%$ – 90%) of the merger remnant population has baryonic masses in the range $M_{\text{max},0} < M_0 < M_{\text{th},0}$, which, in case the remnants begin as maximally rotating, correspond to formation of SMNSs and finite survival times. The median survival time under these assumptions is 80 s (330 s) for $B_p = 10^{15}$ G and SLy (WFF2) (0.9 s (3.5 s) for $B_p = 10^{16}$ G and SLy (WFF2)). Approximately these times are $\sim 0.35\tau_{D,0}$ (where $\tau_{D,0}$ is the initial magnetic dipole spin-down time). This reflects the fact that the NS typically needs to lose ~ 0.35 of its rotational energy before collapsing, and for $t \ll \tau_{D,0}$ the evolution of the rotational energy is approximately $E_\Omega \approx E_{\Omega,0}(1 - t/\tau_{D,0})$ (assuming GW quadrupole radiation to be negligible, which is found to be the case in these calculations; see Equation (7)).

⁹ We note that there is some uncertainty in the exact limit depending on the assumed structure of the magnetic field and on the EOS. However, a significant increase in the volume-averaged B_ϕ relative to the limit in Equation (6) is needed in order to affect our conclusions below.

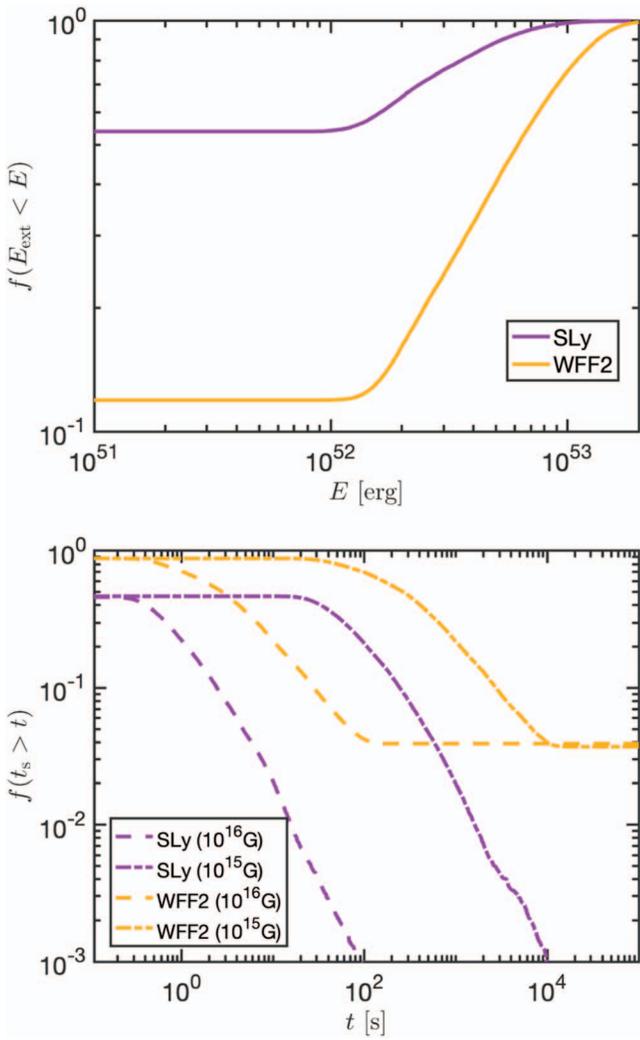


Figure 2. Cumulative distribution of the energies extracted (top) and survival times (bottom) of BNS merger remnants before they collapse to BHs. Results are calculated under the assumption that the merger remnant is born rotating at the mass-shedding limit and shown for different EOSs and, in the bottom panel, for different surface field strengths.

As mentioned above, the merger remnant must lose a large fraction of its initial rotational energy, with a median loss of $\sim 3 \times 10^{52}$ erg for the SLy EOS ($\sim 6 \times 10^{52}$ erg for the WFF2 EOS) before collapsing and with narrow deviations around those values ($\sigma_{\log_{10} E_{\text{ext}}} \approx 0.24$ in both cases). This huge amount of energy is much larger than that of the (collimation-corrected) GRB jet or that of subrelativistic ejecta powering the kilonova emission. As a result, a large fraction of this energy could be absorbed by the ejecta and dominate its kinetic energy budget at late times. Such large amounts of kinetic energy can be seen as strong radio emitters on timescales of years to tens of years, as addressed in more detail in Section 4.2.

Interestingly, even for a fixed magnetic field strength across different systems, the distribution of t_{survive} for SMNSs is very wide, with $\sigma_{\log_{10} t_{\text{survive}}} \approx 0.5$. Any spread in the surface field strength of the merger remnant (which is very natural) would only cause the distribution of t_{survive} to be much wider still. We return to this point in Section 4.1.

If B_{ϕ}/B_p and/or β are much greater than our canonical choices described in Section 2, GW radiation may become significant enough to dominate the spin-down (note that, as

shown in Equation (7), this may lead to an unstable magnetic field configuration). The time to collapse in this situation will be shorter than without GW emission. Nonetheless, the collapse time distribution (in log space) is wider than with dipole spin-down only. This is because, even for a single magnetic field value, there is a range of masses resulting in an SMNS, each corresponding to a different energy that should be lost before collapse. The distribution of extracted energies prior to collapse depends sensitively on $M_{\text{th}} - M$ and is independent of the energy-loss mechanism. As the energy that needs to be removed before collapse is typically a fraction of the initial rotational energy, the collapse time is typically a fraction of the spin-down time. For GW emission, the latter has a stronger dependence on the initial period as compared with the dipole case ($\tau_{G,0} \propto P^4$ rather than $\tau_{D,0} \propto P^2$) and may also have a dependence on the mass (depending on what sets the value of ϵ ; see Section 2). This means that even for all other parameters being fixed, the variation in the spin-down time and time to collapse will be comparable (and, in fact, slightly greater) in the case where losses are dominated by GW emission. Furthermore, in case the two energy-loss mechanisms both play a significant role in spin-down, their spin-down timescales depend differently on the various parameters, causing a further widening of the collapse time distribution. In that aspect, the analysis including dipole losses only is conservative.

3.1. Slower Initial Rotations and Fallback Accretion

As mentioned in Section 2, GRMHD simulations point toward the possibility that the merger remnant loses a significant fraction of its initial rotation energy during the differential rotation phase (Kiuchi et al. 2018; Ciolfi et al. 2019). The energy lost at this phase is mostly converted to internal energy of the remnant. Following the results of Ciolfi et al. (2019), we consider here the possibility that the merger remnant enters the cold uniform rotation phase with a rotational energy of $\leq 0.5E_{\Omega, \text{max}}(M_0)$. We note that the physical processes responsible for the angular momentum transport in the differential rotation phase are still highly uncertain. Radice et al. (2018a) argued that the total angular momentum of the merger remnant often exceeds the mass-shedding limit for SMNS (favoring the $E_{\Omega} = E_{\Omega, \text{max}}$ prescription considered earlier), but their simulations did not include an explicit treatment of angular momentum transport after the GW-driven dynamical merger phase.

We show in Figure 3 the distributions of energies extracted and survival times prior to collapse for this case of slower initial rotation. The main difference compared to the case in which the merger remnant is born rotating at the mass-shedding limit is the fraction of systems that end up as SMNSs. This fraction is 1.5% (15%) for the SLy (WFF2) EOS. The implication is that, depending on the EOS, considering realistic estimates for the angular momentum loss during the differential rotation phase, it is possible that only a very small fraction, and perhaps even none of the merger remnants, result in long-lived NSs. Indeed, if the remnant enters the solid-body rotation with even lower energy, for example, with $0.1E_{\Omega, \text{max}}(M_0)$, then only 0.07% (3%) of systems for the SLy (WFF2) EOS become long-lived remnants. Furthermore, these long-lived remnants would only lose a small amount of rotational energies, $\lesssim 10^{52}$ erg, before they collapse.

The survival time and extracted energy distributions can also be modified in the presence of significant fallback accretion onto the newly born strongly magnetized NS—or magnetar

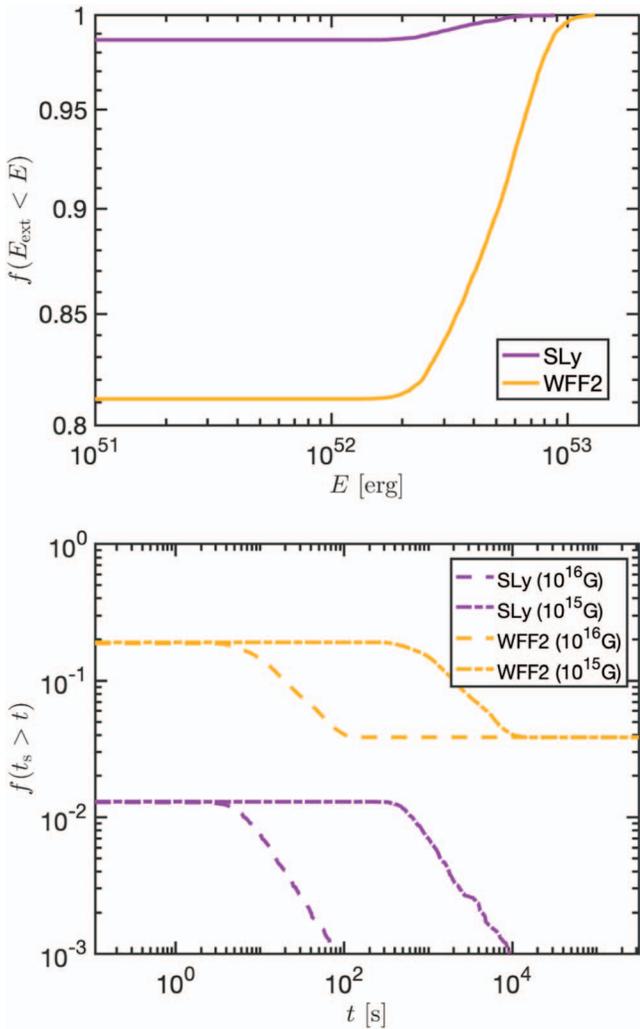


Figure 3. Same as Figure 2, but assuming that the NS merger remnant enters the cold uniform rotation phase with a rotational energy equaling $0.5E_{\Omega, \text{max}}(M_0)$ (note the different scale for the energy plot as compared to Figure 2).

(Metzger et al. 2018). In particular, the magnetar may transfer some of its angular momentum to the fallback disk and, as a result, spin down to the point of collapse after having released a smaller amount of its initial rotational energy. Metzger et al. (2018) have found that this can decrease the amount of energy released prior to collapse by up to a factor of a few. Similar to the case of slow initial rotation, this will lead to a faster collapse relative to the case of fast initial rotation with no fallback accretion.

4. Comparison with sGRBs and Implications

4.1. Can Magnetars Power the Observed Plateaus?

X-ray afterglows of short Gamma Ray Bursts (sGRBs) sometimes exhibit a “plateau” phase, where the emission is almost steady or declining very slowly with time. Previous studies (Zhang & Mészáros 2001; Rowlinson et al. 2010; Dall’Osso et al. 2011; Metzger et al. 2011; Lü et al. 2015; Rezzolla & Kumar 2015; Stratta et al. 2018) have interpreted these as possible evidence of energy injection into the GRB jet or into the surrounding post-merger medium with a duration comparable to the observed plateau (although see Eichler & Granot 2006; Granot et al. 2006;

Ioka et al. 2006; Genet et al. 2007; Shen & Matzner 2012; Beniamini et al. 2020a; Oganessian et al. 2020, for other interpretations). These studies pointed to a magnetar’s spin-down as a possible source of this energy injection. Our results shed light on the viability of this interpretation.

Two types of plateaus are observed in sGRBs. The first are “external plateaus.” These are plateaus in which the light curve smoothly and gradually transitions from a flat temporal evolution to a declining one. More quantitatively, these are cases where the plateau declines on a timescale Δt such that $\Delta t/t \sim 1$ (where t is the time since the GRB trigger or the end of the plateau). These plateaus are dubbed external, since their low level of variability can be reproduced by emission from the external shock (the same region from which the standard afterglow signal is observed). As such, it is not possible to separate by these light curves between a scenario where energy injection ended abruptly but the energy was then reprocessed at the external shock and a situation where the energy injection itself was simply slow to fade at the end of the plateau phase. Furthermore, as mentioned above, such plateaus do not necessarily require any energy injection whatsoever.

The second type of plateaus are “internal plateaus,” in which the emission quickly declines at the end of the plateau (such that $\Delta t/t \ll 1$ with the same definitions as above). In these cases, the rapid variability strongly suggests energy injection, as well as an emission radius well below the external shock. In the context of magnetar energy injection, the source of the abrupt cutoff is most naturally associated with the collapse of an unstable magnetar to a BH.

Gompertz et al. (2020) study a sample of Swift-detected sGRBs with known redshifts. Only 5/22 of the bursts in the sample with an inferred $>1/2$ probability of being noncollapsars (or 9/39 of their full sample), exhibited an internal plateau. This is low, as compared with the fraction $\approx 0.45\text{--}0.9$ of long-lived SMNSs expected to result from NS mergers found above. Furthermore, the (source-frame) durations of these internal plateaus are tightly clustered, with $\langle \log_{10} t_{\text{IXP}} [\text{s}] \rangle = 2.15$, $\sigma_{\log_{10}(t_{\text{IXP}})} = 0.16$. As mentioned in Section 3, this is in contradiction with even the most conservative estimates for the deviation in t_{survive} , which is expected to span a wide range of survival times (this is true also in the case where the merger remnant enters the uniform rotation phase with a slower angular velocity and in the case where it undergoes significant fallback accretion early on). This is demonstrated in Figure 4, where we show the survival time as a function of the remnant’s dipole field strength and gravitational mass (measured immediately after collapse), under the assumption that the merger remnant is initially rotating at the mass-shedding limit. The resulting survival times span over five orders of magnitude, while the durations of internal plateaus all reside in a narrow strip within this plane. This makes the association of these plateaus with spin-down of SMNS extremely fine-tuned. It is also worthwhile to stress that sGRBs with internal plateaus span a range of prompt gamma-ray energies, durations, and redshifts consistent with the rest of the sGRB population (see Gompertz et al. 2020), suggesting that observational selection effects are unlikely to play a significant role in resolving this apparent contradiction. Finally, it is interesting to consider also the total energies released in the X-ray band during the observed internal X-ray plateaus (IXPs). We find $\langle \log_{10} E_{\text{IXP, iso}} [\text{erg}] \rangle = 49.5$, $\sigma_{\log_{10}(E_{\text{IXP}})} = 0.9$. Taking into account the typical beaming of sGRBs (with a jet opening angle of $\theta_0 \approx 0.1$; see Beniamini et al. 2019; Nakar 2020), the collimation-corrected energies corresponding to the values above

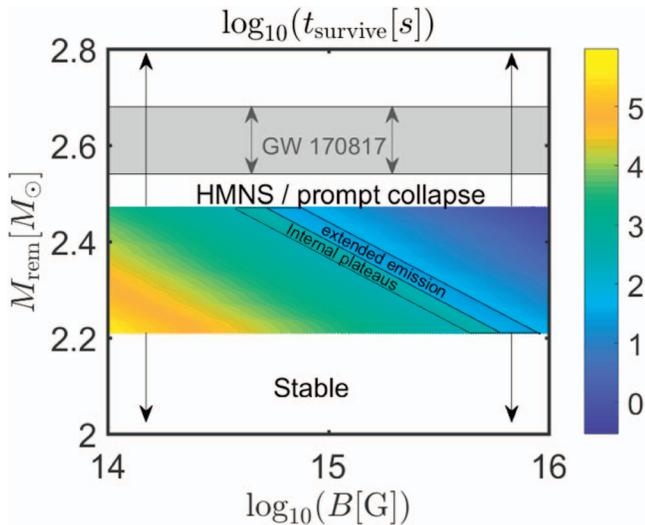


Figure 4. Survival time of a magnetar NS merger remnant as a function of the dipole field strength, B_p , and the gravitational mass of the remnant as it enters the phase of cold uniform rotation, M_{rem} (this is larger than the final gravitational mass, by the time the remnant has spun down). At large masses the magnetar promptly collapses to a BH, whereas at lower masses the magnetar is indefinitely stable. Finite survival times are possible in between and are very sensitive to both B_p and M_{rem} . As a comparison, the durations of all SGRBs with “internal plateaus” span a narrow strip in this parameter space, denoted by a diagonal shaded region. Also shown in comparison is the remnant mass of GW170817, which favors a rapid collapse. We assume that the remnant lost 0.1–0.2 M_{\odot} owing to GW emission, neutrinos, and baryonic ejecta during the merger. Results in this plot are calculated according to the procedure described in Section 2 and for the SLy EOS.

are approximately two orders of magnitude lower. We note, however, that this correction does not apply if the X-rays are produced by a roughly isotropic component injected by the merger remnant (see Metzger & Piro 2014). Altogether, the energies observed in IXPs are approximately three to five orders of magnitude below the typical energy release expected from an SMNS before collapse (see Figure 2). Furthermore, the large spread in plateau energies is also not expected in this scenario (in contrast with the survival time, the energy release is independent of the magnetic field strength and is expected to be quite narrowly distributed). We conclude that the observed plateau data are not naturally explained by energy injection from an SMNS merger remnant.

An additional emission feature seen in $\sim 15\%$ – 20% of sGRBs is the “extended emission” (EE; Lazzati et al. 2001; Gehrels et al. 2006; Norris et al. 2010), a prolonged feature of soft γ -rays lasting ~ 100 s after the initial prompt hard spike. Similar to IXPs, the EE terminates on a timescale that is very short relative to their overall duration (and indeed exhibits significant variability during their activity) and may therefore be an indication of SMNS collapse. 7/39 GRBs in the Gompertz et al. (2020) sample exhibit EE. Their (source-frame) durations are $\langle \log_{10} t_{\text{EE}} [\text{s}] \rangle = 1.85$, $\sigma_{\log_{10}(t_{\text{EE}})} = 0.16$. As for the IXPs, this distribution is much narrower than naturally expected from SMNS collapse. Furthermore, if such an association is true, EE sGRBs should result in extremely bright radio remnants (as will be discussed in Section 4.2). Fong et al. (2016) have conducted a specific search in radio for EE sGRBs, and their search yielded only upper limits. In particular, for the EE sGRB, 050724, the ejecta energy is constrained to be $< 10^{52}$ erg, much below the energies associated with long-lived NS remnants. In addition, the radio search of Ricci et al. (2021) limits the released energy of

three of the other EE sGRBs in the Gompertz et al. (2020) sample: $E_{060614} < 5 \times 10^{52}$ erg, $E_{061006} < 4.5 \times 10^{52}$ erg, $E_{150424A} < 3 \times 10^{52}$ erg.

Finally, if the merger remnants enter the solid-body rotation phase with significantly slower rotations than the mass-shedding limit, then only a small fraction of remnants produce long-lived systems. For example, if they retain $\leq 10\%$ of their initial energy (Ciolfi et al. 2019), then $< 3\%$ of BNS mergers lead to long-lived remnants (see Section 3.1), much less than the occurrence rate of internal plateaus and EE sGRBs. In such a situation the bulk of plateaus/EEs cannot be explained by collapses of SMNS remnants.

4.2. EM Signatures of Magnetar-boosted Outflows

Energy ejected by the magnetar prior to the point of collapse will eventually catch up with the (roughly isotropic) ejecta expanding away from the merger remnant. This energy could then reenergize the ejecta¹⁰ and may significantly overwhelm the initial kinetic energy of the ejecta.

Depending on the timescale of energy injection relative to the diffusion time, this process may lead to a magnetar-boosted kilonova (Kasen & Bildsten 2010; Yu et al. 2013; Metzger & Piro 2014). However, the effect of this energy injection on the radio light curve is more generic. The peak of the radio light curve from the merger ejecta occurs on a timescale of years to tens of years, when the mildly relativistic ejecta has been decelerated by the external medium (Nakar & Piran 2011; Piran et al. 2013; Piro & Kulkarni 2013; Hotokezaka et al. 2018b; Radice et al. 2018b; Kathirgamaraju et al. 2019). This timescale is longer than t_{survive} for any reasonable value of the magnetic field (which could account for the production of a GRB in the earlier stages). Furthermore, the observed signal depends on the (narrowly distributed) kinetic energy of the ejecta and is independent of the specific time at which energy was added to the ejecta. As a result, the radio counterpart is rather robust to the uncertainties in the merger outcome. The flux and duration of the peak are given by

$$F_{\nu, \text{pk}} = 200 \epsilon_{e,-1}^{p-1} \epsilon_{B,-3}^4 n_0^4 M_{\text{ej},-1}^4 E_{51}^{4-5p} \nu_9^2 d_{26}^{-2} \mu\text{Jy} \quad (8)$$

$$t_{\text{pk}} = 3.5 n_0^{-1/3} E_{51}^{-1/2} M_{\text{ej},-1}^{5/6} \text{yr}, \quad (9)$$

where E is the energy of the blast wave; n is the external density; d is the distance of the explosion; ϵ_e , ϵ_B are the fractions of the shock energy, deposited in relativistic electrons/magnetic fields, respectively; p is the index of the shocked electrons’ power law energy distribution; and M_{ej} is the total ejecta mass. The numerical coefficients in Equation (8) depend in general on p , α (where α describes the distribution of velocities in the ejecta, $E(>\beta\Gamma) \propto (\beta\Gamma)^{-\alpha}$) and are estimated here for $p \approx 2.2$, $\alpha \approx 4$ (e.g., Nakar & Piran 2017; Kathirgamaraju et al. 2019). This choice of α corresponds to a steep energy profile, meaning that the results are weakly dependent on its exact value, and deriving the same expressions assuming that a single velocity to the ejecta would only have introduced an order-unity change. We also employ the convention $q_X \equiv q/10^X$ in cgs units (except for M_{ej} , which is in units of M_{\odot}). With the large values of extracted energies given in

¹⁰ The extent to which this happens depends on how efficiently the injected energy is absorbed by the ejecta (see, e.g., Metzger & Piro 2014).

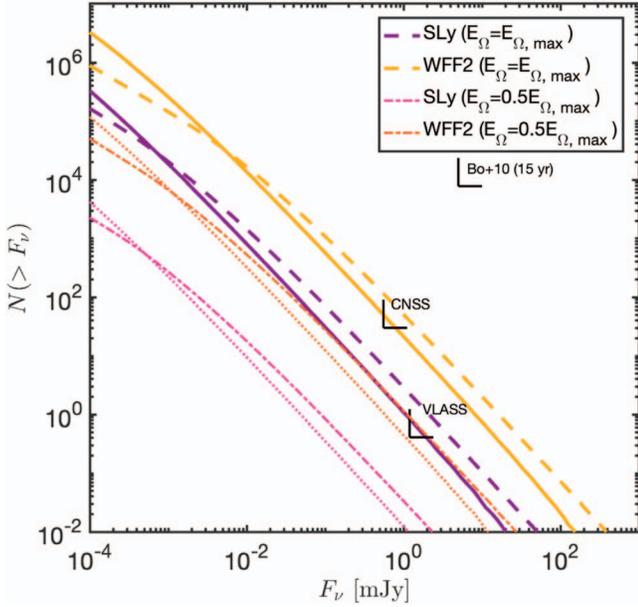


Figure 5. All-sky number of radio sources above a given flux threshold. Results are shown for observations at 3 GHz and for $\epsilon_e = 10^{-1}$, $\epsilon_B = 10^{-3}$. Solid (dotted) lines depict an external density $n = 10^{-2}$ (10^{-3}) cm^{-3} for the entire population, while dashed (dotted-dashed) lines show the potential contribution assuming that a small fraction of the BNS mergers, taken here as 5%, occur at an external density of $n = 1 \text{ cm}^{-3}$. The extracted energy and ejecta mass distributions correspond to the two EOSs explored in this work, assuming that the remnant enters the phase of cold uniform rotation with a rotational energy at the mass-shedding limit (and half that for dotted, dashed-dotted curves). For comparison we show sensitivity limits of different (planned) surveys (Bower et al. 2010; Mooley et al. 2016; Lacy et al. 2020).

Section 3, we can expect a large number of such bright radio transients.

Previous studies have considered radio follow-up observations of known sGRBs years after the bursts, and limits have been put on the kinetic energies of the ejecta in those bursts (Metzger & Bower 2014; Fong et al. 2016; Horesh et al. 2016; Ricci et al. 2021). Ricci et al. (2021) found that for ejecta masses $M_{\text{ej}} < 10^{-2} M_{\odot}$ ($M_{\text{ej}} < 5 \times 10^{-2} M_{\odot}$), extracted energies $> 5 \times 10^{52}$ erg ($> 10^{53}$ erg) can be ruled out in all of the 17 bursts studied. If sGRBs require a BH central engine, then it is not surprising that the ejecta kinetic energy is much below 3×10^{52} erg. However, if there is a long-lived SMNS in a large fraction of sGRBs, we would have expect larger energies (see Figure 5).

An independent approach would be to look for bright radio transients in a blind survey (Metzger et al. 2015b). We calculate the number of sources (all-sky) above a given flux, resulting from mergers with different EOSs and with extracted energy and ejecta mass distributions following our results in Section 3 as

$$N(>F_\nu) = \int \int \frac{d\mathcal{R}(z)}{dM_{\text{ej}}} \frac{t(F_\nu|M_{\text{ej}}, z)}{1+z} \frac{dV}{dz} dM_{\text{ej}} dz, \quad (10)$$

where $d\mathcal{R}(z)/dM_{\text{ej}}$ is the comoving rate of mergers with ejecta mass M_{ej} and $t(F_\nu|M_{\text{ej}}, z)$ is the duration over which a merger with ejecta mass M_{ej} and from redshift z will reside above a flux F_ν . The factor of $1+z$ in the denominator is in order to convert from the comoving to the observed rates, and dV/dz is the change in a comoving volume element with the redshift. The redshift

dependence of the merger rate is obtained by convolving the cosmic star formation rate (Madau & Dickinson 2014) with the delay time distribution between binary formation and merger, found from Galactic BNSs (Beniamini & Piran 2019). The normalization for the rate of mergers is taken as $\mathcal{R} = 320 \text{ Gpc}^{-3} \text{ yr}^{-1}$, in line with the most recent constraints from LIGO-VIRGO (The LIGO Scientific Collaboration et al. 2021). Finally, we have taken advantage of the fact that for a given EOS the extracted energy is to a good approximation dictated uniquely by the ejecta mass (roughly $E \propto M_{\text{ej}}^{3.2}$ for SLy and $E \propto M_{\text{ej}}^{1.2}$ for WFF2 for remnants that are initially rotating at the mass-shedding limit; see Appendix). In both cases the scaling holds above a minimum M_{ej} for which the production of an SMNS is possible; see Section 3).

In Figure 5 we plot the results for the all-sky rates. We assume the merger remnant to be initially spinning at the mass-shedding limit. We also take relatively conservative choices for the values of the microphysical parameters, $\epsilon_{e,-1} = \epsilon_{B,-3} = 1$, and the external density, $n_0 = 10^{-2}$. We note that since sGRBs result from BNS mergers (which themselves are delayed relative to star formation), they occur in lower external densities than IGRBs. Nonetheless, O’Connor et al. (2020) have recently studied sGRB afterglows and found that the majority of sGRBs take place at environments with $n \gtrsim 10^{-2.5} \text{ cm}^{-3}$ (consistent also with the relatively short delay times between binary formation and merger inferred from Galactic BNSs; Beniamini & Piran 2019), and some fraction at even much greater densities. With this in mind, we consider also the contribution from a 5% subpopulation of BNS mergers that take place at greater external densities $n \approx 1 \text{ cm}^{-3}$. At the high flux end, the curves in Figure 5 follow to a good approximation the scaling $N(>F_\nu) \propto F_\nu^{-3/2}$ expected for standard candles in Euclidean geometry. We compare the resulting distributions with the planned sensitivities of the PiGSS, CNSS, and VLASS radio surveys (Bower et al. 2010; Mooley et al. 2016; Lacy et al. 2020). Our results suggest that if BNS mergers enter the cold uniform rotation phase with a rotational energy close to that of the mass-shedding limit, then their radio counterparts should be detectable by the VLASS and potentially also the CNSS surveys. To demonstrate the importance of the initial energy of the remnant as it enters the cold uniform rotation phase, we also plot in Figure 5 the results for the case in which the remnant enters the solid-body rotation with $E_\Omega = 0.5E_{\Omega,\text{max}}(M_0)$. Due to the lower extracted energies and the overall smaller fraction of long-lived remnants, this modest change in the initial energy corresponds to a reduction of $N(>F_\nu)$ by a factor of ~ 30 – 60 . Reducing the initial energy even further, $E_\Omega = 0.1E_{\Omega,\text{max}}(M_0)$, corresponds to a decrease in $N(>F_\nu)$ by a factor of 5000 compared to the results for the mass-shedding limit. Clearly, constraining the all-sky number of radio sources is a promising avenue toward testing the nature of the remnants of BNS mergers.

At times greater than t_{pk} , the kilonova ejecta’s velocity becomes dependent only on the blast wave energy and not on its mass. Thus, once the ejecta slows down to Newtonian velocities, the emission becomes very similar to that of a supernova remnant. On the one hand, this is a drawback, as simply by virtue of their rates there are $\sim 10^3$ times more “garden-variety” supernova remnants than there are kilonova (or magnetar-boosted kilonova) remnants. However, these older kilonova remnants are also several orders of magnitude more common than the years-old kilonova afterglow transients

mentioned above. This means that there could be many such sources even in our own Galaxy or in the Local Group (the latter may be preferable, as the remnants will cover a smaller area of the sky and their distance can be well determined independently of their angular size). This could be extremely constraining regarding the fate of BNS mergers, provided that these remnants can be reliably identified. A full exploration of this idea is deferred to a future work. That being said, we briefly illustrate here the viability of such an endeavour. Consider a remnant that is $t = 10^5$ yr old. Given the Galactic BNS merger rate of $\sim 30 \text{ Myr}^{-1}$ (Hotokezaka et al. 2018a) and the mass of M31, relative to our Galaxy, there should be several such sources in M31. Assuming an overall energy in the blast wave of $\sim 3 \times 10^{52}$ erg (typical of an SMNS remnant; see Section 3) and an interstellar medium density of 0.1 cm^{-3} , these sources should be in the Sedov–Taylor phase (rather than the later “radiative” phase; see, e.g., Barniol Duran et al. 2016 and references therein). The integrated synchrotron flux can then be calculated according to the “deep Newtonian” formulation (Sironi & Giannios 2013). At 1 GHz, and taking $\epsilon_e = 0.1$, $\epsilon_B = 0.01$, we find $F_\nu = 5 \text{ mJy}$. The radius of this remnant is approximately 100 pc, corresponding to an angular size of ~ 0.3 . The surface brightness is therefore $12 \text{ mJy arcmin}^{-2}$, making it potentially detectable by several existing and planned radio surveys such as NVSS, SUMSS, WODAN, and EMU (Intema et al. 2017). The main challenge of such a search would be to reliably infer the energy, independently of n , ϵ_e , ϵ_B . If this can be done, then a remnant with an estimated energy $\gtrsim 3 \times 10^{52}$ erg would be “smoking gun” evidence of a BNS remnant that produced a long-lived magnetar. Conversely, if the existence of such energetic remnants can be ruled out, it would favor remnants that collapse early on to form BHs.

5. Conclusions and Discussion

We have explored in this work the expected outcome of binary NS–NS mergers as informed by the Galactic BNS population, numerical relativity merger simulations, and current constraints on the NS EOS. We assume that an NS merger remnant can cool down and lose differential rotation within the first ~ 0.3 –1 s after the merger. Using models of cold and uniformly rotating NSs, we calculate the evolution of the merger remnants after this initial phase (we return to the validity of this assumption below). We find that a significant fraction of mergers (0.45–0.9) are expected to end up as SMNSs, which would survive for finite times before collapsing. The survival time is typically dominated by the dipole spin-down time (the mean survival time is roughly 35% of the spin-down time, corresponding to the mean fraction of rotational energy that needs to be lost before the NS collapses), and its value strongly depends on the final remnant mass and dipole field strength. Even for a fixed dipole field strength between merger remnants, the scatter in the survival time distributions is rather large, with $\sigma_{\log_{10} t_{\text{survive}}} = 0.5$. If an SMNS is formed, a large amount of energy, $\sim 10^{52}$ – 10^{53} erg, is extracted from the NS before it becomes unstable and undergoes collapse.

This abruptly terminating energy source has previously been invoked to explain IXPs (in which the flux stays roughly constant and then declines very rapidly) seen in short GRB afterglow light curves. However, we find that the distribution of observed IXP durations is very narrow, while the distribution of released energy in IXPs is very wide. Both behaviors are the

opposite to what would be expected from an SMNS collapse, and the comparison of the model with observations strongly disfavors the interpretation of energy injection from a pre-collapse SMNS.

The huge amount of energy injected to the blast wave before the SMNS collapses leads to extremely bright radio transients (due to deceleration of the subrelativistic ejecta by the surrounding environment). Such sources have already previously been ruled out in all 17 short GRBs in which deep searches have been carried out (Ricci et al. 2021). Furthermore, we calculate here the all-sky rate of such sources and find that at 3 GHz, $1 \lesssim N(>1 \text{ mJy}) \lesssim 50$ sources are expected. This can be put to the test with existing and future radio surveys. The advantage of this technique over follow-ups of specific GRBs is that it can constrain also the possibility that the mergers that lead to SMNSs (that inject a large amount of energy to a subrelativistic outflow) are preferentially those that do not lead to GRBs. Such a trend is reasonable considering that simulations of BNS mergers find unfavorable conditions for the formation of an ultrarelativistic jet (as required for powering GRBs) in cases where a long-lived NS is formed (Ciolfi et al. 2019; Ciolfi 2020).

An independent line of reasoning stems from the typical time intervals between the binary merger and the launch of an sGRB jet. Beniamini et al. (2020b) have studied sGRBs with known redshift and shown that the jet-launching delay is typically $\lesssim 0.1$ s. These results are inconsistent with expectations from the model where sGRBs are powered by long-lived rapidly rotating NSs instead of BH accretion. The reason is that shortly after its formation the environment surrounding the magnetar is very baryon rich, preventing the formation of an ultrarelativistic jet, as required for powering the GRB prompt emission (see Beniamini et al. 2017 for details). For values of the dipole field consistent with powering short GRBs ($\sim 10^{15}$ – 10^{16} G), the pulsar wind achieves high magnetization (and hence high Lorentz factor) only after a delay of $\gtrsim 10$ s, which is significantly longer than the values inferred from observed sGRBs ($\lesssim 0.1$ s, as mentioned above).

All three lines of evidence (IXP, radio afterglow, and jet-launching time) shed serious doubts on the formation of long-lived or indefinitely stable magnetars from BNS mergers. This, however, appears to be inconsistent with the estimates of large fractions of such outcomes mentioned at the head of this section. We propose that all these pieces of information can be consistently resolved if merger remnants tend to collapse early on after the merger—while the proto-NS is still undergoing differential rotation and/or neutrino cooling. This can be tested in the future with detailed GRMHD simulations of differentially rotating NSs with neutrino cooling. Although such a calculation is beyond the scope of this work, we roughly outline below why such an outcome is at least plausible.

After GW emission becomes unimportant, the remnant has a slowly rotating core and rapidly rotating envelope (e.g., Kiuchi et al. 2014; Hanauske et al. 2017; Ciolfi et al. 2019). The angular frequency Ω increases with circumferential radius r until a maximum is reached, and then the rotational rate gradually drops and asymptotically approaches the Keplerian rate at large radii. Such a differentially rotating system can be divided into two regions: (1) in the outer region where $d\Omega/dr < 0$, the magnetorotational instability (MRI; Balbus & Hawley 1998) generates strong MHD turbulence/dissipation and hence leads to efficient transport of angular momentum; (2) in the inner region where $d\Omega/dr > 0$, MRI does not operate,

but the free energy associated with differential rotation is spent to amplify the toroidal magnetic field, which grows and saturates owing to nonlinear dissipation—such energy dissipation tends to push the system toward uniform rotation, because the system has the general tendency of evolving toward the minimum energy state (Lynden-Bell & Pringle 1974). However, the mechanism for magnetic energy dissipation, as well as the dissipation rate, is currently unknown (the dissipation in the above-mentioned simulations is largely due to numerical viscosity).

The magnetic energy dissipation timescale may be written as some multiplicity factor $\xi > 1$ times the Alfvén crossing time $t_A \sim \sqrt{4\pi\rho R^2/B_\phi} \sim 10 \text{ ms } B_{\phi,16}^{-1}$, where we have taken $\rho \sim 10^{15} \text{ g cm}^{-3}$ for the typical core density, an NS radius $R \sim 10 \text{ km}$, and a toroidal field strength $B_\phi = 10^{16} B_{\phi,16} \text{ G}$. On a timescale ξt_A , the magnetic energy associated with the toroidal fields $E_B = B_\phi^2 R^3/6$ (B_ϕ being the volume-averaged field strength) is dissipated, giving rise to a dissipation rate of $\dot{E}_B = E_B/(\xi t_A)$. If the free energy associated with differential rotation is $E_{dr} \sim 10^{53} \text{ erg}$, then the timescale for removing differential rotation is given by $t_{diff} \sim E_{dr}/\dot{E}_B \sim (4 \text{ s}) \xi E_{dr,53} E_{B,50}^{-3/2}$. We see that, even for a conservative choice of $\xi \sim 1$, $E_B \gtrsim 2.5 \times 10^{50} \text{ erg}$ is required to remove the differential rotation in about 1 s (i.e., to *increase* the rotation rate of the inner core to that of the outer regions). Such a strong magnetic field ($B_\phi \gtrsim 4 \times 10^{16} \text{ G}$) is energetically possible (Ciolfi et al. 2019), but it may inevitably lead to a very large viscosity in the outer region (where the density is much lower) and to rapid spin-down of the remnant.

The consequence may be that, before the inner core is spun up, most of the energy dissipation occurs in the MRI-dominated outer region and that the majority of the angular momentum is rapidly transported to large radii $\gg 10 \text{ km}$. In that case, the mass added to the core has a specific angular momentum that is smaller than the minimum angular momentum of a uniformly rotating SMNS of the same mass. Accretion of low angular momentum gas, along with neutrino cooling, will increase the central density (Kaplan et al. 2014), so it is possible that the remnant collapses to a BH because the rotation energy is much less than the mass-shedding limit $E_\Omega \ll E_{\Omega,max}$ (as discussed in Section 3.1). After the collapse, the gas with larger specific angular momentum than that of the BH, but less than that of the innermost stable orbit, will quickly plunge into the BH. The outermost layers will then slowly accrete onto the BH and power a GRB jet. As we have shown in Sections 4.1 and 4.2, even a modest reduction of E_Ω by a factor of 2 compared to $E_{\Omega,max}$ strongly suppresses the imprints of long-lived magnetar remnants on GRB and all-sky radio data and leads to a self-consistent understanding of these observations within a BH central engine framework.

Finally, we note that our results supporting a BH central engine powering short GRBs may also be extendable to long GRBs, the chief reason being the similarity in many of the observed properties between the two types of GRBs (e.g., in terms of the luminosities, the bulk Lorentz factors, and the

prompt GRB light-curve morphology and spectral shape). Occam’s razor would suggest that the simplest explanation is that they share a central engine and jet-launching mechanism. An additional consideration is the total mass involved in a stellar collapse leading to a long GRB, which could a priori easily exceed M_{max} and lead to a proto-NS that would not remain stable for long enough to power the observed GRB.

Searches for conclusive proof for the existence/nonexistence of long-lived NS remnants in GRBs are of significant importance to the field. If future evidence will be able to conclusively prove the existence of these objects, this will require a serious reevaluation of our physical understanding as outlined above and undoubtedly lead to interesting astrophysical insights.

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Appendix Distribution of Ejecta Masses and Extracted Energies

The distribution of extracted energies and ejecta masses for the EOSs used in this work is presented in Figure 6.

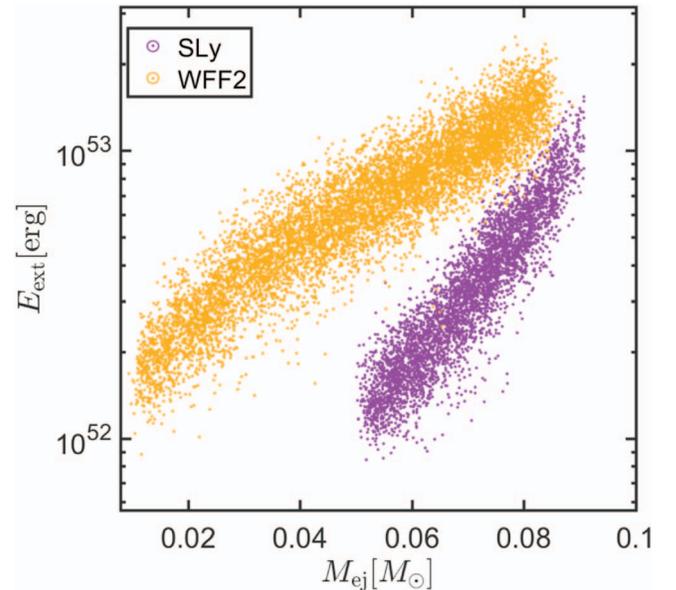


Figure 6. Extracted energies as a function of ejecta masses for the two EOSs used in this paper assuming that the remnant is initially rotating at the mass-shedding limit. The data here are shown for systems that produce SMNSs or stable NSs. Lower ejecta masses (leading to HMNSs or prompt collapse) are possible but are not associated with a significant extracted energy and therefore are not seen in this figure.

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