

16 **Abstract**

17 In this study, we use data from the Juno and Galileo spacecraft to analyze the internal magnetic dynamo of Ganymede. As the only known moon with a strong internal magnetic field, Ganymede is a uniquely interesting object in the context of understanding the formation and structure of planetary magnetospheres. Using a spherical harmonic model centered on the moon, we report a dipole approximation for Ganymede of $g_0^1 = -716.4$ nT, $g_1^1 = 56.0$ nT, and $h_1^1 = 27.0$ nT. We find that using a quadrupole fit rather than a dipole fit provides only a marginal increase in accuracy, and instead favor the use of a dipole approximation until more data can be obtained. The magnetic moment estimates provided here can be used as a baseline for interpreting data from future spacecraft flybys of the moon, and can serve as inputs into numerical models studying Ganymede’s magnetosphere.

28 **Plain Language Summary**

29 Jupiter’s moon Ganymede is the only known moon to possess its own strong internal magnetic field. This makes it a uniquely interesting planetary body in the context of understanding how planetary magnetic fields in the solar system form and interact with the space environment. Juno’s recent flyby of the moon has provided us with a new set of spacecraft data from Ganymede for the first time in twenty years, and using that data we calculate a new best estimate of the properties of the moon’s internal field. This estimate can be used as a baseline for future studies of Ganymede using data and numerical simulations.

37 **1 Introduction**

38 Ganymede is both the largest moon in our solar system and the only known moon to possess a global internal magnetic field, the discovery of which (M. Kivelson et al., 1996) spurred a variety of studies working to characterize the moon’s unique properties. These works revealed that Ganymede, embedded in the corotating plasma of the Jovian magnetosphere, creates a magnetosphere that in many ways resembles a planetary magnetosphere in the solar wind. Ganymede’s magnetic field dominates the local Jovian field, stands off the incoming plasma, and reconnects with the Jovian field to create open field lines that reach from the moon’s poles out toward Jupiter (e.g. M. G. Kivelson et al., 1997; Williams et al., 1997). Particles precipitating along these open field lines create auroral emission (McGrath et al., 2013), while ionospheric particles flow outwards (Frank et al., 1997; Vasyliūnas & Eviatar, 2000), reminiscent of the polar outflows observed at Earth.

50 Unlike at other magnetospheres in the solar system, however, the plasma flowing past Ganymede is moving at subalfvenic, submagnetosonic speeds. With thermal and magnetic pressure dominating over ram pressure, this means that no bow shock is formed upstream of the moon, and that the magnetosphere takes a shape that more resembles a cylinder than it does the teardrop shape of familiar planetary magnetospheres. Due to this unique situation, Ganymede’s magnetosphere has been the subject of many modeling studies. These have used a variety of different numerical schemes, including single-fluid MHD (Jia et al., 2009; Fatemi et al., 2016), multi-fluid MHD (Paty & Winglee, 2004, 2006), Hall-MHD (Dorelli et al., 2015), hybrid (Fatemi et al., 2016; Poppe et al., 2018; Romanelli et al., 2022), and particle-in-cell modeling (Tóth et al., 2016; Zhou et al., 2019).

60 Taken together, previous studies of Ganymede present an image of of the moon that invites more attention: A magnetosphere featuring similar processes to those found in planetary magnetospheres, but in a plasma regime not found elsewhere in the solar system (Jia & Kivelson, 2021). As such, further investigations are forthcoming. With Juno’s

64 recent flyby, we now have new data from Ganymede’s magnetosphere for the first time
 65 in twenty years, and the upcoming JUICE orbiter is expected to revolutionize our un-
 66 derstanding of the moon.

67 For all of these investigations, it is crucial to have as accurate a representation as
 68 possible of the strength of the moon’s internal magnetic field. Our knowledge of the moon’s
 69 magnetic moments serves as a baseline for interpreting spacecraft data and as a funda-
 70 mental input into numerical models. The most recent estimations of Ganymede’s inter-
 71 nal dipole moment were provided by M. Kivelson et al. (2002), who used data from three
 72 of Galileo’s flybys of the moon to fit a spherical harmonic magnetic field model. With
 73 Juno’s recent flyby, we now have the opportunity to revisit this model and update the
 74 fit with more observations. In this study, we combine data from Galileo and Juno to es-
 75 timate the internal magnetic moments of Ganymede. Following the method of M. Kivel-
 76 son et al. (2002), we provide updated spherical harmonic coefficients for both a simple
 77 dipole fit and a quadrupole fit, and discuss the applicability of the quadrupole approx-
 78 imation.

79 In addition to possessing an internal magnetic field, Ganymede also may host a sub-
 80 surface ocean of liquid water. Europa and Callisto are both known to have subsurface
 81 oceans, the first indications of which were the induced magnetic fields observed by Galileo
 82 (Khurana et al., 1998). Follow-up investigations searched for a similar inductive response
 83 at Ganymede, but the moon’s strong magnetic field made it difficult to observe smaller
 84 magnetic signatures of this kind (M. Kivelson et al., 2002). Specifically, studies of Ganymede’s
 85 magnetic field were unable to determine whether observed magnetic variations were due
 86 to an inductive response or to quadrupole terms in the moon’s internal field. A recent
 87 study using the Hubble space telescope analyzed time variations in Ganymede’s auro-
 88 ral ovals, and determined that the presence of subsurface ocean in the moon is likely (Saur
 89 et al., 2015), but in-situ signatures of magnetic induction have still never been observed.
 90 During Juno’s flyby of Ganymede, the moon was situated near the center of the Jovian
 91 magnetodisk, and as such we do not expect there to be a strong magnetic inductive sig-
 92 nature present. This means, however, that our analysis of the flyby data is well-situated
 93 to examine more closely the relative importance of quadrupole terms in Ganymede’s field.

94 In section 2 of this paper, we present an overview of the flyby geometry and mag-
 95 netic field data from Juno’s flyby of Ganymede. In section 3, we present our method of
 96 spherical harmonic analysis. In section 4, we present the results of our analysis and dis-
 97 cuss our findings in relation to the previously calculated magnetic moments. And in sec-
 98 tion 5, we summarize our work and consider future implications.

99 **2 Overview of Juno’s Ganymede flyby**

100 **2.1 Flyby geometry**

101 An overview of Juno’s Ganymede flyby is shown in Figure 1. In this figure, the upper-
 102 right panel shows a time series of the measured vector magnetic field, while the other
 103 three panels show the flyby geometry in GphiO coordinates. In this Ganymede-centered
 104 coordinate system, +X points in the direction of Ganymede’s orbital motion, +Y points
 105 toward Jupiter, and +Z points in the direction of Jupiter’s spin axis. Because the Jo-
 106 vian plasma flow surrounding Ganymede moves more quickly than the moon’s orbital
 107 motion, +X GphiO also points in the direction of the wake, which is shown as a light
 108 gray shaded region in the flyby plots. To help interpret the three dimensional nature of
 109 the flyby geometry plots, one can visualize the lower-left panel as the front of a cube,
 110 and then picture folding the lower-right and upper-left panels inward onto two other faces
 111 of the cube.

112 Juno began the flyby in the positive X and negative Y quadrant, meaning that it
 113 was downstream from Ganymede on its anti-Jovian side. Over the course of the flyby,

114 Juno passed through the wake region, eventually ending slightly upstream from Ganymede
 115 on the moon’s Jupiter-facing side. In panels a, c, and d, we have also plotted the tra-
 116 jectories of Galileo’s G01, G02 and G28 flybys. These are the three crossings that were
 117 used by M. Kivelson et al. (2002) to model Ganymede’s internal magnetic field, and will
 118 therefore be used in this study as well (the reasons for including these Galileo orbits while
 119 excluding others will be discussed later in the paper). From figure 1 we can see that Juno’s
 120 flyby covers a different section of parameter space than the relevant Galileo orbits, par-
 121 ticularly with regards to sampling the downstream wake region. This should prove help-
 122 ful in our modeling of the moon’s internal field, as increased coverage is beneficial in con-
 123 straining multipole spherical harmonic moments.

124 **2.2 Magnetic field measurements**

125 The upper-right panel of Figure 1 shows magnetic field data from Juno’s encounter
 126 with Ganymede. These measurements were taken by the Juno Magnetic Field investi-
 127 gation (MAG), which is composed of two sets of triaxial fluxgate magnetometers. MAG
 128 samples the vector magnetic field at a rate of 64 Hz and with a resolution of ~ 0.05 nT
 129 (Connerney et al., 2017). During the flyby, Juno sampled several distinct regions of Ganymede’s
 130 magnetosphere, signatures of which can clearly be seen in the magnetic field data. At
 131 16:43, a field rotation is evident as Juno began to enter into the Ganymede system. Fol-
 132 lowing this there is a period of increased variability in the magnetic field from 16:46 to
 133 16:51 as Juno moved into Ganymede’s wake region. Juno then moved to its closest ap-
 134 proach of the moon, reaching an altitude of 1035 km at $\sim 16:56$. As expected, this cor-
 135 responds to the strongest measured magnetic fields during the flyby, and after this point
 136 the magnetic field measurements become weaker until there is once again a field rota-
 137 tion at $\sim 17:01$, signaling Juno’s exit from the Ganymede system.

138 In this study we also use data from the Galileo magnetometer, which used two tri-
 139 axial fluxgate magnetometers to measure the vector magnetic field at a resolution of 3
 140 Hz. We combine this data from Galileo with the measurements from Juno to fit a spher-
 141 ical harmonic model of Ganymede’s internal field, as described in the next section.

142 **3 Method of spherical harmonic analysis**

143 **3.1 Orbit Selection**

144 Galileo performed eight flybys of Ganymede, but in our analysis we only use data
 145 from the G01, G02, and G28 flybys, as these were the orbits that M. Kivelson et al. (2002)
 146 used in their analysis of the moon’s internal field. Other Galileo orbits were considered
 147 by that study, but were determined to be too far from the Moon to be useful in constrain-
 148 ing quadrupole moments. See Figure 5 of that study for additional discussion of why other
 149 orbits were excluded, informed by a full analysis of the expected quadrupole contribu-
 150 tions to the magnetic field measured by Galileo.

151 **3.2 Background subtraction**

152 The magnetic field measured during flybys by Juno and Galileo is a composition
 153 of both Ganymede’s internal magnetic field and the background magnetic field of Jupiter.
 154 In order to accurately model Ganymede’s internal dynamo, we therefore first need to re-
 155 move the background Jovian field from our measurements. We accomplish this in the
 156 same manner as M. Kivelson et al. (2002), fitting a polynomial to the Jovian magnetic
 157 field measurements taken before and after the flyby. For each flyby, we fit a degree two
 158 polynomial to the magnetic field measurements taken before entering the ganymede sys-
 159 tem and after exiting it (as signaled by a large field rotation). We then subtract the re-
 160 sult from our measurements to obtain data representing just Ganymede’s internal mag-
 161 netic field.

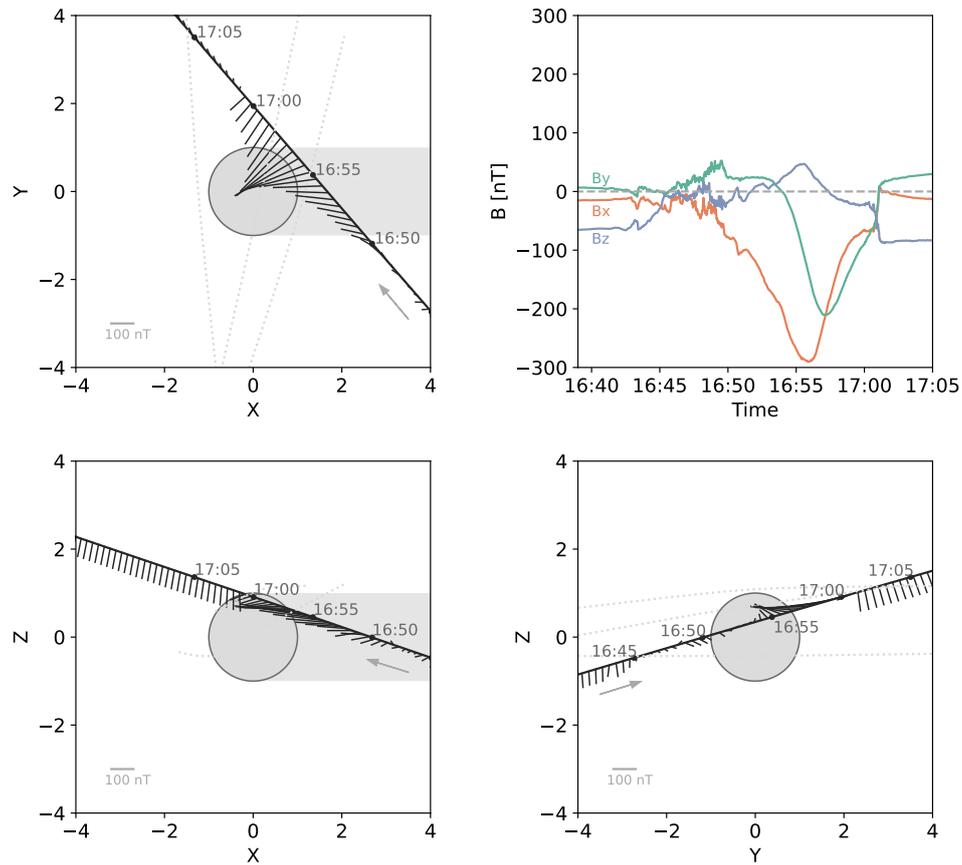


Figure 1. Magnetic field measurements from the Juno flyby of Ganymede. The upper-right panel shows a time-series of the data, while the other three panels show Juno's trajectory through the Ganymede system. The thinner lines anchored in Juno's trajectory represent the measured vector magnetic field averaged over every thirty seconds, and the shaded gray region represents Ganymede's wake. All of the panels in this figure use the GphiO coordinate system, which is defined in the text.

162 **3.3 Method of least-squares fitting**

163 After removing the background magnetic field for each orbit, we then combine the
 164 data from Galileo and Juno and perform a least-squares fit across all of the orbits at once.
 165 Because the Juno magnetometer takes data at a higher time resolution than Galileo, the
 166 Juno flyby contains a much higher total number of measurements. This means that the
 167 Juno flyby will be weighted much more highly by the fitting analysis if no modifications
 168 are made. We would prefer that each flyby is weighted equally, as gaining information
 169 from several parts of the spatial parameter space is vital for spherical harmonic analy-
 170 sis. We therefore downsample the Juno measurements to be at the same cadence as Galileo.

171 Similarly, a standard least-squares fitting routine will by default weight the fit most
 172 strongly toward the measurements with the highest field magnitude, meaning that the
 173 fit will be optimized primarily for the flybys that passed closest to the moon and mea-
 174 sured the strongest fields. To counteract this, we follow the method of M. Kivelson et
 175 al. (2002), applying a weighting method where the data from orbit i is weighted inversely
 176 by $B_{max}^i / (\sum_i (B_{max}^i)^2)^{1/2}$, with B_{max}^i representing the largest field magnitude measured
 177 during that orbit.

178 We fit the data to a model consisting of a multipole moment centered at ganymede
 179 and a uniform cartesian background magnetic field (we denote this background field as
 180 UFX, UFY, UFZ, using GphiO coordinates). The uniform background fields are intended
 181 to approximate magnetopause currents, and are allowed to vary from orbit to orbit, while
 182 the multipole moment is not allowed to vary between the passes. We perform the fit for
 183 both a dipole field and a quadrupole field. In the dipole case, we are fitting three spher-
 184 ical harmonic coefficients (g_0^1, g_1^1, h_1^1) along with four different sets of three parameters
 185 that represent the uniform fields during each flyby. This gives us a total of 15 param-
 186 eters. In the quadrupole case, we once again have four sets of three parameters repre-
 187 senting the uniform fields, but are now fitting eight spherical harmonic coefficients ($g_0^1,$
 188 $g_1^1, h_1^1, g_2^0, g_2^1, g_2^2, h_2^1, h_2^2$), giving us a total of 20 parameters. A full description of our
 189 least-squares fitting method is provided in Appendix A.

190 **4 Results and Discussion**

191 The results of our analysis are shown in Table 1. We present the magnetic moments
 192 obtained from both the dipole and quadrupole fits, along with the corresponding uni-
 193 form fields found for each orbit. The performance of the fit for each orbit is plotted in
 194 Figure 2, where the spacecraft measurements are shown with solid lines and the model
 195 fits with dotted lines.

196 Our addition of Juno’s flyby does not drastically change the multipole fits found
 197 by M. Kivelson et al. (2002). Using just the Galileo orbits, that study reported a g_0^1 term
 198 of -727.3 nT when fitting a dipole with uniform background fields. We find that the ad-
 199 dition of Juno data changes this g_0^1 term to -716.4 nT. The secondary dipole moments
 200 for this fit are comparably small for both studies (a few tens of nT). In fitting a quadrupole,
 201 we find a slightly larger change, with M. Kivelson et al. (2002) reporting a g_0^1 term of
 202 -711.0 nT while we find a g_0^1 of -748.3 nT. However, the quadrupole fit only represents
 203 a minor increase in performance when compared to the dipole fit. Our dipole fit had an
 204 RMS value of 10.0 nT, and the quadrupole fit an RMS of 8.3 nT. We would naturally
 205 expect the fit to become more accurate when adding in five extra parameters, but the
 206 accuracy increase here is quite minor. Furthermore, we find the quadrupole terms (g_2^0
 207 through h_2^2) to be smaller than the g_0^1 term by more than an order of magnitude, sug-
 208 gesting that the main dipole field of Ganymede is very dominant. For these reasons, we
 209 conclude that the use of a quadrupole fit is in danger of overfitting the data, and is not
 210 justified here. We suggest that the dipole fit should be treated as the most accurate rep-
 211 resentation we have until more data is obtained, and that deviations from the dipole field

212 could still be the result of small quadrupole terms or induction from a subsurface ocean,
 213 as suggested by M. Kivelson et al. (2002)

214 The question of whether induction from a subsurface ocean is present at Ganymede
 215 was investigated by M. Kivelson et al. (2002), but was left as an open question to the
 216 future. That study favored a subsurface ocean as the explanation for magnetic field vari-
 217 ations observed between orbital passes, but the authors did not view their evidence con-
 218 clusive enough to treat the subject as fully closed. Unfortunately, the Juno flyby of Ganymede
 219 occurred when the moon was found close to the center of the magnetodisk, when any in-
 220 duction signature that is present is expected to be at its weakest point. For this reason,
 221 we were unable to use Juno data to provide further analysis of induction signatures, and
 222 we leave that question to future studies with expanded datasets.

	g_0^1	g_1^1	h_1^1	g_2^0	g_2^1	g_2^2	h_2^1	h_2^2	UFX	UFY	UFZ	RMS
Dipole Fit	-716.4	56.0	27.0	-	-	-	-	-				10.0
									G01	31.7	3.2	-36.5
									G02	38.1	99.9	28.6
									G28	-1.4	-42.9	76.3
									Juno	-7.0	57.8	-25.9
Quadrupole Fit	-748.3	41.1	20.8	22.5	23.3	-26.8	16.5	-10.6				8.3
									G01	30.9	1.5	-32.7
									G02	37.7	84.9	24.0
									G28	-9.4	-52.0	48.7
									Juno	-8.2	58.5	-22.8

Table 1. Magnetic moments resulting from spherical harmonic fits using Juno and Galileo data. The dipole and quadrupole moments are fixed for all passes in the fit, while the uniform background fields are allowed to vary from orbit to orbit. UFX, UFY, and UFZ represent uniform, cartesian background fields in the GphiO coordinate system. RMS is the root-mean-square calculated over all of the orbits for the corresponding fit. All entries are in units of nanotesla.

223 5 Summary

224 In this study we used data from the Galileo and Juno spacecraft to fit a spherical
 225 harmonic model to the internal magnetic field of Ganymede. The magnetic moments re-
 226 sulting from this analysis are presented in Table 1. We found that the addition of data
 227 from Juno only slightly changed the previous reported results from Galileo, and that the
 228 main dipole field is greater than the other multipole moments by over an order of mag-
 229 nitude. We favor the use of a dipole approximation, as the quadrupole fit does not per-
 230 form substantially better and is still dominated by the main dipole term.

231 The upcoming JUICE mission, scheduled to launch in April of 2023, will be the first
 232 spacecraft ever to orbit Ganymede (or any moon other than Earth’s). One of JUICE’s
 233 primary mission objectives is to study Ganymede’s intrinsic magnetic field and its in-
 234 teractions with the Jovian magnetosphere, and over the several years that JUICE is ex-
 235 pected to orbit the moon it will provide us with a a wealth of data to accomplish that
 236 objective. The work presented in this study may serve as a baseline of comparison for
 237 the studies that JUICE will enable.

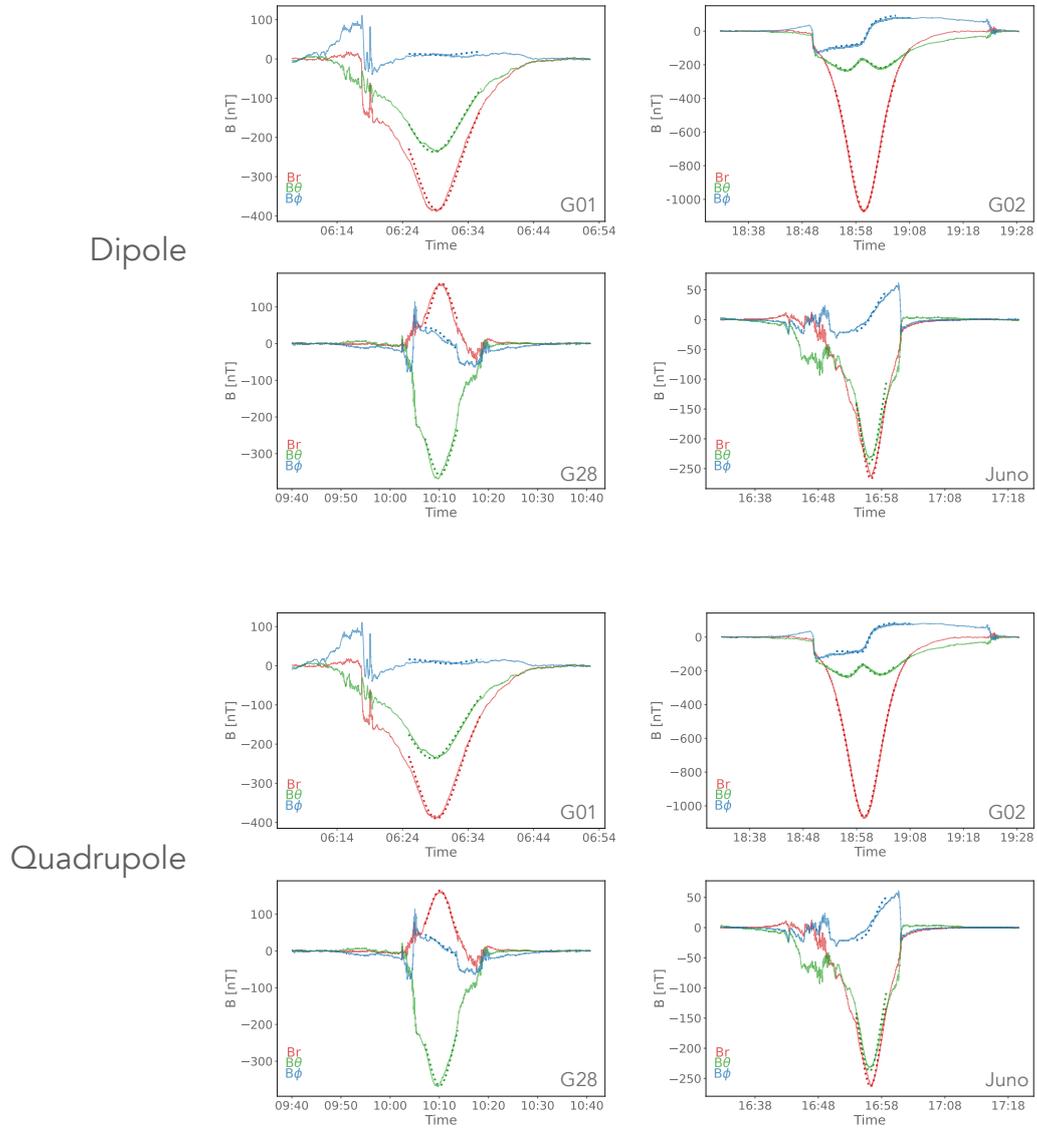


Figure 2. Data-model comparison for spherical harmonic fits using Juno and Galileo data. In each panel, the measured magnetic field for that orbit is shown with solid lines, while the dotted lines represent the field calculated from the magnetic moments shown in Table 1. These panels all use the Gsph coordinate system, a Ganymede-centric, spherical system in which r is the radial distance, θ is the colatitude measured from the rotation axis, and ϕ is the longitude as measured from the Jupiter-facing meridian. The top set of 4 panels fit a dipole to the data, while the bottom set of four fit a quadrupole.

238 **Appendix A Least Squares Fitting**

239 In this study we use a weighted least-squares fit, combining data from multiple fly-
 240 bys to find a single set of multipole components, while allowing constant background com-
 241 ponents to vary for each flyby. This amounts to solving the matrix equation $\mathbf{b} = \mathbf{A}\mathbf{x}$,
 242 where \mathbf{b} is the measured magnetic field data, \mathbf{x} is the matrix of coefficients that we wish
 243 to solve for, and \mathbf{A} is the matrix relating these two as a function of spacecraft position.
 244 To find where the square of the error $(\mathbf{A}\mathbf{x} - \mathbf{b})$ is minimized, we solve the equation

$$\frac{d}{d\mathbf{x}} \frac{1}{2} (\mathbf{A}\mathbf{x} - \mathbf{b})^T (\mathbf{A}\mathbf{x} - \mathbf{b}) = 0 \tag{A1}$$

245 which reduces to

$$\mathbf{x} = (\mathbf{A}^T \mathbf{A})^{-1} \mathbf{A}^T \mathbf{b} \tag{A2}$$

246 Because a least square fit biases toward fitting the data with the highest magni-
 247 tude, our fit is by default optimized for the flybys with the strongest magnetic fields and
 248 lowest orbital altitudes. In order to weight our separate flybys more equally, we use the
 249 same method as M. Kivelson et al. (2002) and weight the data from each orbit inversely
 250 by $B_{max}/(\sum_i (B_{max})^2)^{1/2}$, with B_{max} representing the largest field magnitude measured
 251 during that orbit. Modifying equation A2 to include this weighting method, we have

$$\mathbf{x} = (\mathbf{W}\mathbf{A}^T \mathbf{W}\mathbf{A})^{-1} \mathbf{W}\mathbf{A}^T \mathbf{W}\mathbf{b} \tag{A3}$$

252 For each data point in \mathbf{b} , we have three components of the magnetic field as mea-
 253 sured in the Gsph coordinate system. The matrix \mathbf{A} corresponding to that measurement
 254 takes the form $[\mathbf{A}_{sph}, \mathbf{U}\mathbf{F}_{G1}, \mathbf{U}\mathbf{F}_{G2}, \mathbf{U}\mathbf{F}_{G28}, \mathbf{U}\mathbf{F}_{Juno}]$. Here, \mathbf{A}_{sph} represents the subma-
 255 trix of schmidt-normalized coefficients from the spherical harmonic expansion, which de-
 256 pends only on spacecraft position (see e.g. Connerney, 1981; Connerney et al., 2018, for
 257 a full description of these terms). For a dipole fit, this submatrix will be size 3×3 , while
 258 for a quadrupole fit it will be 3×8 . The $\mathbf{U}\mathbf{F}$ submatrices relate the cartesian background
 259 fields for each orbit to the Gsph coordinate system. Because the data from each orbit
 260 only affects one of these submatrices, for any given data point the three $\mathbf{U}\mathbf{F}$ submatri-
 261 ces that don't correspond to that orbit will be 0, while the $\mathbf{U}\mathbf{F}$ matrix corresponding to
 262 that orbit takes the form

$$\begin{pmatrix} \sin(\theta) \cos(\phi) & \sin(\theta) \sin(\phi) & \cos(\theta) \\ \cos(\theta) \cos(\phi) & \cos(\theta) \sin(\phi) & -\sin(\theta) \\ \sin(\phi) & \cos(\phi) & 0 \end{pmatrix} \tag{A4}$$

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 267 the planetary data system. The Galileo data can be found at <https://tinyurl.com/GanymedeData>. The Juno data can be found at <https://tinyurl.com/JunoGanymedeData>.

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