

A Characterization of Strategic Complementarities *

Federico Echenique †

October 24, 2006

Abstract

I characterize games for which there is an order on strategies such that the game has strategic complementarities. I prove that, with some qualifications, games with a unique equilibrium have complementarities if and only if Cournot best-response dynamics has no cycles; and that all games with multiple equilibria have complementarities.

As applications of my results, I show: 1. That generic 2×2 games either have no pure-strategy equilibria, or have complementarities. 2. That generic two-player finite ordinal potential games have complementarities.

JEL Classification: C62, C71.

Keywords: Strategic complementarities, supermodular games, non-standard analysis, Cournot best-response dynamics, potential games.

*I thank Elvio Accinelli, Bob Anderson, Juan Dubra, Paul Milgrom, Stephen Morris, Charles Pugh, Ilya Segal, Chris Shannon, Xavier Vives, and seminar participants at Arizona State and Stanford Universities. A conversation with Ted O'Donoghue and Clara Wang prompted me to work on the research presented here. The non-standard proof in Theorem 3 owes a great deal to Bob Anderson, I am deeply grateful for his help. I worked out the results in Section 8 in response to Stephen Morris's very stimulating questions. Finally, part of this paper was written while I visited UC Berkeley's Economics Department, I appreciate Berkeley's hospitality. Any errors are my responsibility.

†Division of Humanities and Social Sciences, MC 228-77, California Institute of Technology, Pasadena, CA 91125. email: fede@hss.caltech.edu

1 Introduction

A game has strategic complementarities (Topkis, 1979; Vives, 1990) if, given an order on players' strategies, an increase in one player's strategy makes the other players want to increase their strategies. For example, the players could be firms in price competition; if each firm's optimal price is an increasing function of the prices set by their opponents, the game has strategic complementarities. In games of strategic complementarities (GSC), Nash equilibria have a certain order structure; in particular, there is a smallest and largest equilibrium (Topkis, Vives, (Zhou, 1994)). Further, the set of all rationalizable strategies, and the set of limits of adaptive learning, is bounded below by the smallest equilibrium and above by the largest equilibrium (Vives, 1990; Milgrom and Roberts, 1990; Milgrom and Shannon, 1994). GSC are a well-behaved class of games, and a useful tool for economists.

Consider the coordination game in Figure 1, is it a GSC? That is, is there an order on players' strategies so that best-responses are monotone increasing? Yes, let α be smaller than β . Then, player 2's best response to α is α and to β is β . So, when 1 increases her strategy from α to β , 2's best response increases from α to β . Similarly for 1. So, with this order the coordination game is a GSC.

	α	β
α	2, 2	0, 0
β	0, 0	1, 1

Figure 1: A coordination game.

The question I address is: what does this depend on? That is, when can we find an order on strategies so that a game is a GSC? Note that how strategies are ordered is not part of the description of a game—it does not affect the available strategies or payoffs. We as analysts use the order as a tool, therefore we are justified in choosing the order to conform to our theory. Often, results on GSC are used by coming up with a clever order on strategies that makes a situation into a GSC, this paper is concerned with how often such orders exists.

We normally introduce strategic complementarities by assuming supermodular payoffs. The crucial feature for most results on GSC is that the game's best-response correspondences are increasing.

ondence is monotone increasing, and the assumption of supermodular payoffs is sufficient for monotone increasing best-responses.¹ I shall argue that it is enough, for the purpose of this paper, to define a GSC as a game for which there is a partial order on strategies so that best-responses are monotone increasing (and such that strategies have a lattice structure).

My results are:

1. With some qualifications, a game with a unique pure-strategy Nash equilibrium is a GSC if and only if Cournot best-response dynamics has no cycles except for the equilibrium.
2. A game with two or more pure-strategy Nash equilibria is always a GSC.

I illustrate my results with two applications: Generically, 2×2 games are either GSC or have no pure-strategy equilibria. And, generically, a finite two-player ordinal potential game is a GSC, but ordinal potential games with more than two players need not be GSC.

I now discuss my results.

1. With some qualifications, in games with a unique Nash equilibrium, strategic complementarities is equivalent to the absence of cycles in Cournot best-response dynamics. If b is the game's best-response function (the product of the players' best-response functions) then Cournot best-response dynamics starting at x is defined by $x_0 = x$, $x_n = b(x_{n-1})$, $n = 1, 2, \dots$. Absence of cycles means that, if x is not an equilibrium, Cournot best-response dynamics starting at x never returns to x , i.e. $x_n \neq x$ for all $n \geq 1$, or, equivalently, that $x \neq b^n(x)$ for all $n \geq 1$. In finite games, absence of cycles is equivalent to global stability, that is that $b^n(x)$ converges to the equilibrium for all x . In infinite games, absence of cycles is a weaker condition than global stability—so I show that a game with a unique, globally stable, equilibrium is a GSC.

2. A game with two or more pure-strategy equilibria is a GSC, so the vast majority of games that we encounter in applied work are GSC. The order in the coordination game of Figure 1 that makes its best-response function increasing involves making one Nash equilibrium the smallest point in the joint strategy space, and the other equilibrium the largest point in the strategy space. I show that, if a game has at least two equilibria, the same trick always works; we can order the strategies such that one equilibrium is the largest strategy profile and the other equilibrium is the smallest, and such

¹In fact the first paper on GSC in economics, (Vives, 1985), defined GSC like I do here.

that best-responses are monotone increasing. This result has implications for the use of complementarities to obtain predictions in games.

The literature on GSC has developed a set-valued prediction concept: the set of strategies that are larger than the smallest Nash equilibrium and smaller than the largest Nash equilibrium. This “interval prediction” contains all rationalizable strategies, and all strategies that are limits of adaptive learning. Is the interval prediction in general a sharp prediction? Milgrom and Roberts suggest that the answer may be negative:

Indeed, for some games, these bounds are so wide that our result is of little help: it is even possible that these bounds are so wide that the minimum and maximum elements of the strategy space are equilibria. (Milgrom and Roberts, 1990, p. 1258)

Milgrom and Roberts go on to argue that, in some models, “the bounds are quite narrow.” They present as examples an arms-race game, and a class of Bertrand oligopoly models, where there is a unique equilibrium.

My results imply that this is *generally* the case: if a game does not have a unique equilibrium, the interval prediction is essentially vacuous, as all games with multiple equilibria are GSC where the smallest and largest equilibria are the smallest and largest strategy profiles. This happens because games with multiple equilibria always involve a kind of coordination problem—namely the problem of coordinating on one equilibrium—and this coordination problem can be formalized through an order on strategies that makes the game a GSC.

I show that, in some games, no order that makes the game a GSC avoids a trivial interval prediction. In fact, the coordination game in Figure 1 is such a game. On the other hand, in the coordination game, all strategy profiles are rationalizable, which may suggest that the interval prediction coincides in general with rationalizability. I present an example where no order that makes the game a GSC, avoids strictly dominated strategies in the interval prediction—this is further evidence that the interval prediction is problematic.

I wish to emphasize that GSC are still a very useful tool. In a given game, complementarities jointly with the rest of the structure of the game can provide sharp results. In a sense, complementarities is like compactness—most spaces we work with can be compactified, but compactness is still a very powerful tool. For example, Topkis’s (1979) algorithm for finding the smallest and largest Nash equilibria in GSC is very useful on a

given game with complementarities; and once Topkis’s algorithm has delivered an interval prediction we can judge if it is sharp or not *in that particular game*. Other examples are Amir’s (1996) elegant methods for analyzing Cournot oligopoly models using complementarities, and the equilibrium uniqueness results in the literature on global games (Morris and Shin, 2000).²

The point of this paper is that complementarities alone do not possess important predictive power, but that we can use complementarities to understand properties of a particular game. My results are a contribution to the theory of GSC, delineating the boundaries of the set of GSC, but I do not provide new positive results on GSC, and I do not increase the scope of applicability of existing results on GSC.

(Lippman, Mamer, and McCardle, 1987), (Sobel, 1988), (Milgrom and Roberts, 1990), (Milgrom and Shannon, 1994), (Milgrom and Roberts, 1994), (Echenique, 2002), and (Echenique and Sabarwal, 2000) present comparative statics results for a parameterized GSC. They prove that, if a parameter is complementary to players’ choices, some selections of equilibria are monotone increasing in the parameter. My results prompt the question: can all systematic comparative statics conclusion be rationalized as coming from a parameterized GSC? The answer, it turns out, is no: there are parameterized models (with multiple equilibria) such that no order delivers the comparative statics as an application of results for GSC. In a sense, comparative statics acts as an “identifying restriction,” we do not have enough degrees of freedom in selecting the order on strategies so as to make the game a GSC and, at the same time, preserve monotone comparative statics.

In Section 2 I give some preliminary definitions and present the model that the results apply to. Section 3 presents my results for games with a unique equilibrium, and section 4 presents my results for games with multiple equilibria. Section 5 discusses the interval prediction. Section 6 discusses comparative statics restrictions. In section 7 I present an application to 2×2 games, and in section 8 an application to potential games. Section 9 contains the proof of Theorem 3.

²Amir’s analysis does not proceed by introducing a convenient order on strategy spaces like I do (see also (Amir and Lambson, 2000)). My results—which, unlike Amir’s, require prior knowledge of some equilibria of the game—imply that there are more Cournot oligopoly models that can be made into a GSC than the ones identified by Amir. But the structure, in addition to complementarities, that Amir uses in his paper enables him to obtain substantive results about Cournot oligopoly, and his results cannot be generalized using my characterization.

2 Definitions

2.1 Preliminaries

A detailed discussion of the concepts defined in this subsection can be found in (Topkis, 1998). A pair (X, \leq) , where X is a set and \leq is a transitive, reflexive, antisymmetric binary relation, is a **partially ordered** set; (X, \leq) is **totally ordered** if, for all $x, y \in X$, $x \leq y$ or $y \leq x$ (\leq is then a total order on X); (X, \leq) is a **lattice** if whenever $x, y \in X$, both $x \wedge y = \inf \{x, y\}$ and $x \vee y = \sup \{x, y\}$ exist in X . Note that a totally ordered set is a lattice. A nonempty subset A of X is a **sublattice** if for all $x, y \in A$, $x \wedge_X y, x \vee_X y \in A$, where $x \wedge_X y$ and $x \vee_X y$ are obtained taking the infimum and supremum as elements of X (as opposed to using the relative order on A).

A lattice (X, \leq) is **complete** if for every nonempty subset A of X , $\inf A, \sup A$ exist in X . A nonempty subset A of X is **subcomplete** if $B \subseteq A$, $B \neq \emptyset$ implies $\inf_X B, \sup_X B \in A$, again taking \inf and \sup of B as a subset of X . For two subsets A, B of X , say that A is smaller than B in the **strong set order** if $a \in A$, $b \in B$ implies $a \wedge b \in A$, $a \vee b \in B$.

Let (X, \leq) be a lattice. Say that a correspondence $\phi : X \rightrightarrows X$ is **weakly increasing** over $A \subseteq X$ if $x, y \in A$ and $x \leq y$ implies that there is $z \in \phi(x)$ and $z' \in \phi(y)$ with $z \leq z'$. Also, say that ϕ is **increasing in the strong set order** if $x < y$ implies that $\phi(x)$ is smaller in the strong set order than $\phi(y)$. Note that when ϕ is a function, i.e. single valued, both concepts coincide with the usual notion of “monotone weakly increasing.”

A correspondence $\phi : X \rightrightarrows X$ takes **finite values** if $\phi(x)$ is a finite set for all $x \in X$.

2.2 The Model

All results in the paper are results about functions, or correspondences, on a set X . The reader should think of the results as dealing with the best-response function, or correspondence, of a game.

Let $\Gamma = \{I, \{u_i\}_{i \in I}, \{S_i\}_{i \in I}\}$ be a normal-form game. That is, I is a set of players, and each player $i \in I$ is endowed with a strategy space S_i and a payoff function $u_i : X = \times_{j \in I} S_j \rightarrow \mathbf{R}$. If $\beta_i : X \rightrightarrows S_i$ is player i 's best-response correspondence, $\beta_i(s) = \operatorname{argmax}_{\tilde{s}_i} u_i(\tilde{s}_i, s_{-i})$, then $\phi : X \rightrightarrows X$ defined by $\phi = \times_{i \in I} \beta_i$ is the game's best-response correspondence. If best-responses are always unique, then β_i is a function, and $f = \times_{i \in I} \beta_i$ is the game's best-response function. The set of fixed points of ϕ —or, if best-responses

are unique, of f —coincides with the set of pure-strategy Nash equilibria of Γ .

I shall only deal with pure strategies and pure-strategy equilibria, but one can apply my results to the best-response correspondence of the mixed extension of a game. The interpretation of my results for the mixed extension of a game is straightforward.³

A game $\Gamma = \{I, \{u_i\}_{i \in I}, \{S_i\}_{i \in I}\}$ is a **game of strategic complementarities** (GSC) if there is an order \leq on X such that (X, \leq) is a lattice and ϕ is weakly increasing. If Γ has unique best-responses, Γ is a GSC if there is an order \leq on X such that (X, \leq) is a lattice and f is a monotone increasing function.

It will be useful to interpret some assumptions in terms of Cournot best-response dynamics: If players meet to play Γ over and over again, and if they, in each round of play n , choose a best response to their opponents' play in $n - 1$, we say that they follow Cournot best-response dynamics. If ϕ is Γ 's best-response correspondence, all Cournot best-response dynamics are generated by $x_n \in \phi(x_{n-1})$ (for some initial x_0).

Definition 1. *Let X be a set and $\phi : X \rightarrow X$ be a correspondence. A point $x \in X$ is a **cycle** of ϕ if there is $n \in \mathbf{N}$ such that $x \in \phi^n(x)$. Let X be a topological space. A fixed point e is **globally stable** for ϕ if, for every $x \in X$ and every sequence $\{x_k\}$ with $x_0 = x$ and $x_k \in \phi(x_{k-1})$, $x_k \rightarrow e$. By interpreting $f : X \rightarrow X$ as a correspondence with singleton values, these definitions extended to functions.*

Absence of cycles means that no Cournot best-response dynamics will get caught in a cycle.⁴ And global stability means that players that engage in Cournot best-response dynamics will eventually approach Nash equilibrium play.

3 Unique Equilibrium

Let X be a set, $f : X \rightarrow X$ a function and $\phi : X \rightarrow X$ a correspondence. First, I consider the problem of when there is an order \leq such that (X, \leq) is a lattice and f is monotone increasing. Second, I consider the problem of when there is an order \leq

³I focus on pure strategies because the GSC literature considers usually orders on pure strategies. It may be desirable to order both pure and mixed strategies in a way that is consistent (for example by using the first-order stochastic dominance order on mixed strategies) but unless all strategy spaces are chains, this is incompatible with strategic complementarities, see (Echenique, 2000).

⁴Cournot best-response dynamics is a very naive learning model, my results do not depend of any virtues of Cournot dynamics as a learning model. The absence of cycles should be viewed as a technical condition. It is true, though, that Cournot dynamics is easy to implement on a computer, and therefore the condition of absence of cycles is easy to verify computationally.

such that (X, \leq) is a lattice and ϕ is weakly increasing. Third, I discuss some technical issues.

Theorem 2. *Let $f : X \rightarrow X$ have a unique fixed point $e \in X$. There is a total order \leq on X such that f is monotone increasing if and only if f has no cycles besides e .*

The proof of Theorem 2 follows from Theorem 3 below. Let me say here that: a) It is immediate that the absence of cycles is necessary for the existence of a total order such that f is increasing. For example, if $x = f(f(x)) = f^2(x)$ and $x \neq f(x)$ then f cannot be monotone increasing, as one and only one of $x < f(x)$ and $f(x) < x$ must hold. Similarly for $x = f^n(x)$, $n \geq 2$. b) When X is finite it is easy to prove sufficiency, the idea is as follows. Absence of cycles implies that for each x there is an n such that $e = f^n(x)$; now let $x < y$ whenever the smallest n such that $e = f^n(x)$ is larger than the smallest n such that $e = f^n(y)$, this gives $f(x) < f(y)$. It remains to order the elements that are the same number of iterates away from e , which is slightly cumbersome but easy (see the proof of Theorem 3 for the details, and for the proof when X is infinite).

Theorem 2 may have some mathematical interest, independently of the application to game theory that I emphasize.

Absence of cycles is a non-topological condition that is weaker than global stability: global stability implies the absence of cycles other than e , but absence of cycles does not imply global stability—for example, let X be the unit disk in \mathbf{R}^2 and f be a rotation of X by an irrational number, then f has a unique fixed point, $(0, 0)$, and no cycles, but $(0, 0)$ is clearly not globally stable. The existence of an order such that f is increasing is a non-topological statement, so it cannot depend on global stability.

3.1 Examples

Let $\Gamma = \{I, \{u_i\}_{i \in I}, \{S_i\}_{i \in I}\}$ be a normal-form game with a unique Nash equilibrium. If all players have unique best-responses—which, as these are pure-strategy best-responses, is generically the case when Γ is a finite game—then, by Theorem 2, Γ is a GSC if and only if Cournot best-response dynamics has no cycles except for e .⁵ In particular, if e is globally stable under Cournot best-response dynamics, then Γ is a GSC. One implication of these results is that a game that satisfies the dominant diagonal condition in (Gabay and Moulin, 1980), and has thus a unique, globally stable, equilibrium, is a GSC.

⁵See section 3.3 for the difference between lattice and totally ordered strategy spaces.

	α	β	γ
α	2, 2	0, 0	0, 0
β	0, 0	1, -1	-1, 1
γ	0, 0	-1, 1	1, -1

Γ_1

	α	β
α	1, -1	2, -2
β	0, 0	1, -1

Γ_2

Figure 2: A non-GSC, and a GSC that is zero-sum.

As an illustration of Theorem 2, consider Γ_1 , the 3×3 game on the left in Figure 2. This game has a unique pure-strategy equilibrium, and best-response dynamics has the cycles $(\alpha, \alpha) \rightarrow (\alpha, \alpha)$, $(\beta, \alpha) \rightarrow (\alpha, \gamma) \rightarrow (\gamma, \alpha) \rightarrow (\alpha, \beta) \rightarrow (\beta, \alpha)$, and $(\beta, \beta) \rightarrow (\beta, \gamma) \rightarrow (\gamma, \gamma) \rightarrow (\gamma, \beta) \rightarrow (\beta, \beta)$. Therefore there is no order on strategies such that the game in Figure 2 is a GSC.

Consider Γ_2 , the zero-sum game on the right in Figure 2 as a second illustration of Theorem 2. This is a GSC because it has a unique equilibrium and no cycles. The intuitive idea that zero-sum games and GSC are different is therefore false.

3.2 Non-unique best-responses

Theorem 2 for functions can be generalized to correspondences with finite values, but the characterization is not completely tight. Absence of cycles implies the existence of a total order that makes the correspondence weakly monotone, but a weakly monotone correspondence may have cycles, as weak monotonicity does not control all selections from the correspondence.

Theorem 3. *Let $\phi : X \rightarrow X$ have a unique fixed point $e \in X$. If ϕ takes finite values and has no cycles besides e , there is a total order \leq on X such that ϕ is weakly increasing. Further, if $\{e\} = \phi(e)$ and there is a total order \leq on X such that ϕ is increasing in the strong set order, then ϕ has no cycles besides e .*

The proof of Theorem 3 is in section 9.

I need the hypothesis of a correspondence with finite values to use non-standard analysis the way I do. If Γ is a game with unique best-responses, of course the best-responses have finite values, and both weakly increasing and increasing in the strong set order coincide with monotone increasing, so Theorem 3 implies Theorem 2. Also, if Γ is a finite game, then best-responses take finite values. I have not been able to extend the characterization in Theorem 3 to arbitrary games with infinite strategy spaces and non-unique best-responses.

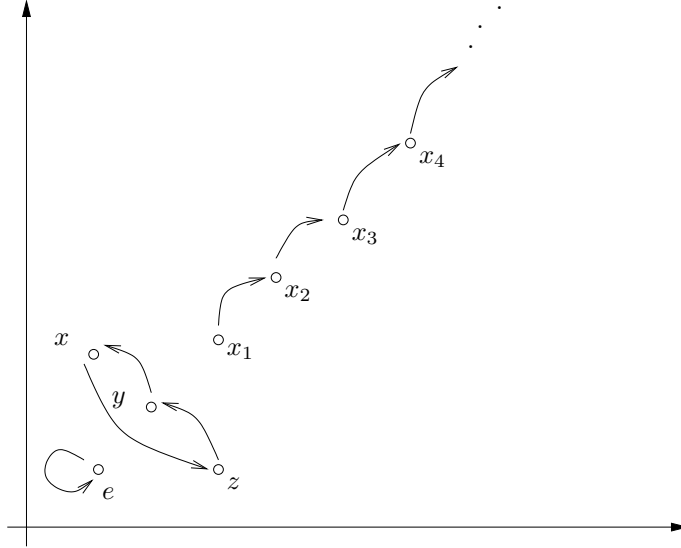


Figure 3: Arrows show action of $f : \{e, x, y, z, x_1, x_2, \dots\} \rightarrow \{e, x, y, z, x_1, x_2, \dots\}$

Global stability implies absence of cycles, thus we obtain

Corollary 4. *Let X be a topological space and $\phi : X \rightarrow X$ a correspondence with finite values and a unique fixed point $e \in X$. If e is globally stable then there is a total order \leq on X such that ϕ is weakly increasing.*

3.3 Totally ordered strategy space vs. a lattice strategy space, and completeness.

Theorems 2 and 3 give necessary and sufficient conditions for a game to be a GSC with a totally ordered strategy space. I defined GSC as games with lattice strategy spaces, is there some loss in focusing on totally ordered strategies? Yes, but it is essentially a technical problem: Consider Theorem 2. If a game's best-response function does not have cycles, then the game is a GSC because there is a total order on strategies such that best responses are monotone increasing, and a totally ordered set is a lattice. On the other hand, if Γ is a GSC where each S_i is a complete lattice, and best-responses f are continuous, then a unique Nash equilibrium is globally stable (Vives, 1990; Milgrom and Roberts, 1990) so f has no cycles and there is a total order on strategies such that f is increasing. In particular this implies that, in finite games, a game with a unique equilibrium is a GSC if and only if best responses have no cycles.

In GSC where strategy spaces are non-complete lattices, best-responses may have cycles. Consider the example in Figure 3. The arrows in the figure show the action of a function $f : \{e, x, y, z, x_1, x_2, \dots\} \rightarrow \{e, x, y, z, x_1, x_2, \dots\}$. Let the infinite set $\{e, x, y, z, x_1, x_2, \dots\}$ be ordered as a subset of \mathbf{R}^2 . The function f has a unique fixed point, e , a cycle $z \rightarrow y \rightarrow x \rightarrow z$, and it is monotone increasing. The example works because Cournot best-response dynamics starting at x_1 (or any other point larger than x, y and z) is a monotone increasing sequence x_1, x_2, \dots that does not converge to a fixed point different from e . So the characterization in Theorem 2 is not completely tight. As I remarked earlier, complementarities is a non-topological condition, so the characterization must be independent of completeness of strategy spaces. In a sense, then, it is impossible to avoid problems like the one in Figure 3.

In the usual definition of GSC—supermodular games—there is a link between the order and the topology on the strategy spaces that, among other things, ensures the existence of equilibria (by Tarski’s Theorem), and that if equilibrium is unique it must be globally stable. This link is (order) completeness. Here I construct orders that make best-responses monotone increasing, but that do not have any relation to the topology on the strategy spaces. In finite games this does not matter: a finite game without equilibria cannot be a GSC, and a game with a unique equilibrium is a GSC if and only if this equilibrium is globally stable. In infinite games, though, there may be GSC without equilibria, and GSC with a unique equilibrium that is not globally stable. I wish to emphasize that, despite this technical problem, for games with multiple equilibria, all of Vives’s, Topkis’s and Milgrom and Roberts’s results hold trivially with the order that I construct in section 4.

4 Multiple Equilibria

A game with two or more Nash equilibria is (almost trivially) a GSC: set one equilibrium \underline{e} as the smallest strategy profile, another equilibrium \bar{e} as the largest, and let all other strategy profiles x be unordered, except for satisfying $\underline{e} \leq x \leq \bar{e}$. I work out the details in Theorem 5, and then Theorem 8 presents a more interesting and non-trivial order.

Theorem 5. *Let $\phi : X \rightarrow X$ have at least two different fixed points. There is an order \leq on X such that (X, \leq) is a complete lattice, ϕ is weakly increasing, and the set of fixed points of ϕ is a complete sublattice of X .*

Proof. Let \underline{e}, \bar{e} be different fixed points of ϕ . Define \leq on X by $x \leq y$ if and only if one of the following is true: $x = y$, $x = \underline{e}$, or $y = \bar{e}$. Then, for any non-singleton $A \subseteq X$, \underline{e} is the unique lower bound on A , hence $\inf A = \underline{e}$; similarly $\sup A = \bar{e}$ as \bar{e} is the unique upper bound on A . Thus, for all $x, y \in X$, $x \vee y, x \wedge y \in X$, and for all non-empty $A \subseteq X$, $\inf A, \sup A \in X$, so X is a complete lattice.

Now, let $x \leq y$ and $x \neq y$; if $x = \underline{e}$ then $\underline{e} \in \phi(x)$, so $\underline{e} \leq z$ for all $z \in \phi(y)$, and similarly if $y = \bar{e}$. If $x = y$ then any $z = z' \in \phi(x) = \phi(y)$ satisfies $z \leq z'$. Thus if $x \leq y$ there is $z \in \phi(x)$ and $z' \in \phi(y)$ with $z \leq z'$, so ϕ is weakly increasing.

Finally, if A is a non-singleton set of fixed points, then \underline{e} is the unique lower bound, and \bar{e} is the unique upper bound, on A . So, $\inf A = \underline{e}$ and $\sup A = \bar{e}$. But \underline{e} and \bar{e} are fixed points, so the set of fixed points is a complete sublattice of X . \square

Remarks:

1. The usual definitions of GSC ensure that best-responses are increasing in the strong set order, and that ϕ takes subcomplete- sublattice-values. The order that I construct in Theorem 5 does not guarantee that ϕ has these properties (unless, of course, ϕ is a function), but Topkis's, Vives's, Milgrom and Roberts's, and Milgrom and Shannon's results are (trivially) true with the constructed order.
2. By Zhou's version of Tarski's Fixed Point Theorem the equilibrium set of a GSC is a complete lattice. Topkis, Vives and Zhou present examples where it is not a sublattice (see (Echenique, 2001), though). By Theorem 5 there is a partial order on X such that this equilibrium set is a complete sublattice, without eliminating complementarities.

For clarity, I include the statement of Theorem 5 when ϕ is a function as:

Corollary 6. *Let $f : X \rightarrow X$ have at least two different fixed points. There is an order \leq on X such that (X, \leq) is a complete lattice, f is monotone increasing, and the set of fixed points of f is a complete sublattice of X .*

For a class of finite games, it is possible to improve on the trivial order of Theorem 5. In particular, certain elements in X can be excluded from the interval prediction $[\underline{e}, \bar{e}]$.

Let X be a finite set, and $f : X \rightarrow X$ be a function. Denote by \mathbb{C} the **set of cycles** of f , so

$$\mathbb{C} = \{x \in X : \exists n \in \mathbf{N} \text{ s.t. } f^n(x) = x\}.$$

Note that $\underline{e}, \bar{e} \in \mathbb{C}$.

A **path** in X is a sequence $\pi = \{x_1, \dots, x_L\}$ such that, $x_l \notin \mathbb{C}$ for $1 \leq l \leq L$, $f(x_1) \in \mathbb{C} \setminus \{\underline{e}, \bar{e}\}$, and $f^{-1}(x_L) = \emptyset$. Let Π be the set of all paths.

If $\pi = \{x_1, \dots, x_L\}$ is a path, let $H_\pi = L$ denote the **length** of π . For each $x_l \in \pi$, let $h_\pi(x_l) = l$. Let $A = \cup \{\pi : \pi \in \Pi\}$.

If $e \in X$ is a fixed point of f , the **basin** of e , denoted \mathbb{B}_e , is the set of points $z \in X$ such that $e = f^n(z)$ for some n . For each $z \in \mathbb{B}_e$, let $g_e(z) = \inf \{n \in \mathbf{N} : f^n(z) = \underline{e}\}$. Define $f^0(z) = z$, so $g_e(\underline{e}) = 0$. Let $H_e = \sup \{g_e(z) : z \in \mathbb{B}_e\}$, and let

$$H_{\bar{e}} = \sup \{\inf \{n \in \mathbf{N} : f^n(z) = \underline{e}\} : z \in \mathbb{B}_{\bar{e}}\}.$$

Suppose, without loss of generality, that $H_e \geq H_{\bar{e}}$ (if $H_e < H_{\bar{e}}$ just relabel \underline{e} and \bar{e}). For each $z \in A$, let

$$g(z) = \inf \{H_e - [H_\pi - h_\pi(z)] : \pi \in \Pi, z \in \pi\}.$$

I claim that $X = \mathbb{C} \cup A \cup \mathbb{B}_e \cup \mathbb{B}_{\bar{e}}$: Let $z \in X$. Since X is finite, for large enough n , either $f^n(z)$ is a fixed point or it is a cycle. If $f^n(z)$ is eventually \underline{e} or \bar{e} , then $x \in (\mathbb{B}_e \cup \mathbb{B}_{\bar{e}})$. If $f^n(z)$ is eventually some other $x \in \mathbb{C}$, then either $z \in \mathbb{C}$ in the first place, or $z \in A$. In any case, $x \in \mathbb{C} \cup A \cup \mathbb{B}_e \cup \mathbb{B}_{\bar{e}}$, which establishes the claim. Also, note that by definition of \mathbb{C} , A , \mathbb{B}_e and $\mathbb{B}_{\bar{e}}$, $A \cap \mathbb{C} = \emptyset$, $A \cap \mathbb{B}_e = \emptyset$, $A \cap \mathbb{B}_{\bar{e}} = \emptyset$, $\mathbb{B}_e \cap \mathbb{B}_{\bar{e}} = \emptyset$, $\mathbb{B}_e \cap \mathbb{C} = \{\underline{e}\}$ and $\mathbb{B}_{\bar{e}} \cap \mathbb{C} = \{\bar{e}\}$.

Before I define \leq I need two auxiliary orders. I'll define \leq_e on \mathbb{B}_e and $\leq_{\bar{e}}$ on $\mathbb{B}_{\bar{e}}$ such that f restricted to either \mathbb{B}_e or $\mathbb{B}_{\bar{e}}$ is monotone increasing, and such that \underline{e} is the largest element of \mathbb{B}_e , and \bar{e} is the largest element of $\mathbb{B}_{\bar{e}}$. I claim that $f(\mathbb{B}_e) \subseteq \mathbb{B}_e$, and that $f(\mathbb{B}_{\bar{e}}) \subseteq \mathbb{B}_{\bar{e}}$. To see this, let $x \in \mathbb{B}_e$. If $f(\underline{e}) = \underline{e}$, then $f(x) \in \mathbb{B}_e$. Suppose that $f(\underline{e}) \neq \underline{e}$, then there is $n \in \mathbf{N}$ such that $f^n(\underline{e}) = \underline{e}$. But $f(x) \neq \underline{e}$ implies $n \geq 2$, so $f^{n-1}(f(x)) = \underline{e}$, and $f(x) \in \mathbb{B}_e$. The proof that $f(\mathbb{B}_{\bar{e}}) \subseteq \mathbb{B}_{\bar{e}}$ is similar.

Now I can obtain \leq_e and $\leq_{\bar{e}}$ from Theorem 2. First, $f|_{\mathbb{B}_e}$, the restriction of f to \mathbb{B}_e , maps \mathbb{B}_e into \mathbb{B}_e , has exactly one fixed point, and no cycles. By Theorem 2, there is a total order—say \leq_e —on \mathbb{B}_e such that $f|_{\mathbb{B}_e}$ is monotone increasing and \underline{e} is the largest element of \mathbb{B}_e . Second, by a similar argument, there is a total order $\leq_{\bar{e}}$ on $\mathbb{B}_{\bar{e}}$ such that $f|_{\mathbb{B}_{\bar{e}}}$ is monotone increasing and \bar{e} is the *smallest* element of $\mathbb{B}_{\bar{e}}$ —simply reverse the order that Theorem 2 delivers on $\mathbb{B}_{\bar{e}}$.

Let $\underline{x} = \inf_{\leq_e} \mathbb{B}_e$ and $\bar{x} = \sup_{\leq_{\bar{e}}} \mathbb{B}_{\bar{e}}$.

Definition 7. Define the order \leq on X by: $z \leq z'$ if and only if one (or more) of the following is true :

1. $z = z'$,
2. $z, z' \in \mathbb{B}_{\underline{e}}$ and $z \leq_{\underline{e}} z'$ or $z, z' \in \mathbb{B}_{\bar{e}}$ and $z \leq_{\bar{e}} z'$,
3. $z \in \mathbb{B}_{\underline{e}}$ and $z' \in \mathbb{C}$,
4. $z' \in \mathbb{B}_{\bar{e}}$ and $z \notin \mathbb{B}_{\bar{e}}$,
5. $z \in \mathbb{B}_{\underline{e}}$, $z' \in A$, and $g_{\underline{e}}(z) \geq g(z')$.

REMARKS:

1. Note that \leq coincides with $\leq_{\underline{e}}$ on $\mathbb{B}_{\underline{e}}$ and with $\leq_{\bar{e}}$ on $\mathbb{B}_{\bar{e}}$. So, $g_{\underline{e}}$ is monotone decreasing—that is, $z < z'$ implies $g_{\underline{e}}(z) \geq g_{\underline{e}}(z')$. Also, by construction of $\leq_{\underline{e}}$, $g_{\underline{e}}(z) > g_{\underline{e}}(z')$ implies that $z < z'$. Further, if $z \in \mathbb{B}_{\underline{e}}$ and $z < \underline{e}$, then $g_{\underline{e}}(f(z)) = g_{\underline{e}}(z) - 1$. See the proof of Theorem 2, or the heuristic following the statement of Theorem 2 in Section 3.
2. For all $x \in X$, $\underline{x} \leq x$, so \underline{x} is the smallest element in X .

I now prove that (X, \leq) is a lattice (steps 1 and 2), that f is monotone increasing (step 3), and that any other lattice order that makes f monotone increasing must have a larger interval prediction (step 4).

STEP 1: I prove that \leq is a partial order. By definition of \leq (item 1), \leq is reflexive. I need to prove that it is antisymmetric and transitive.

To prove that \leq is antisymmetric, let $z \leq z'$ and $z \neq z'$, I shall prove that $z' \not\leq z$. First, $z \leq z'$ cannot be due to item 1 of the definition of \leq . Second, if $z \leq z'$ because of item 2, then $z' \not\leq z$, as $\leq_{\underline{e}}$ and $\leq_{\bar{e}}$ are antisymmetric. Third, if $z \in \mathbb{B}_{\underline{e}}$ then $z' \leq z$ only if $z' \in \mathbb{B}_{\underline{e}}$ as well. So, if $z \leq z'$ by item 3 or item 5 we get immediately $z' \not\leq z$. Fourth, if $z' \in \mathbb{B}_{\bar{e}}$ then $z' \leq z$ only if $z \in \mathbb{B}_{\bar{e}}$ as well. So, if $z \leq z'$ by item 4 we get immediately $z' \not\leq z$.

Now I shall prove that \leq is transitive: let $z \leq z'$ and $z' \leq z''$, I shall prove that $z \leq z''$. If either $z \leq z'$ or $z' \leq z''$ is due to item 1, it is immediate that $z \leq z''$. So, suppose that $z \neq z'$ and $z' \neq z''$.

First, let $z \leq z'$ be due to item 2. If $z, z' \in \mathbb{B}_{\bar{e}}$ then it must be that $z'' \in \mathbb{B}_{\bar{e}}$, but then $z \leq z''$, as $\leq_{\bar{e}}$ is transitive. Now let $z, z' \in \mathbb{B}_{\underline{e}}$. Assume $z'' \in \mathbb{B}_{\underline{e}} \cup \mathbb{B}_{\bar{e}}$. Either $z'' \in \mathbb{B}_{\bar{e}}$

so $z \leq z''$ by item 4 or $z'' \in \mathbb{B}_e$ and $z \leq z''$ because \leq_e is transitive. Now assume that $z'' \notin \mathbb{B}_e \cup \mathbb{B}_{\bar{e}}$. Either $z'' \in \mathbb{C}$ and we get $z \leq z''$ by item 3; or $z'' \in A$, but then $z' \leq z''$ is due to item 5, so $z \leq_e z'$ implies that $g_e(z) \geq g_e(z') \geq g(z'')$. Thus $z \leq z''$ by item 5.

Second, let $z \leq z'$ be due to item 3; $z' \leq z''$ can then only be due to item 4. So $z'' \in \mathbb{B}_{\bar{e}}$, and we have $z \leq z''$ by item 4.

Third, if $z \leq z'$ is due to item 4, then $z' \in \mathbb{B}_{\bar{e}}$, so $z' \leq z''$ implies that $z'' \in \mathbb{B}_{\bar{e}}$, and we have $z \leq z''$ by item 4.

Fourth, if $z \leq z'$ is due to item 5, then $z' \in A$. But then $z' \leq z''$ implies that $z'' \in \mathbb{B}_{\bar{e}}$, so we get $z \leq z''$ by item 4.

STEP 2: I prove that (X, \leq) is a lattice. Since X is finite, (X, \leq) is then a complete lattice.

Let $z, z' \in X$. If $z \leq z'$ or $z' \leq z$, then $z \vee z'$ and $z \wedge z'$ are trivial. So let z and z' be unordered, and note that, when z and z' are unordered, $z \vee z'$ is the smallest element of $\{\tilde{z} \in X : z < \tilde{z}\} \cap \{\tilde{z} \in X : z' < \tilde{z}\}$, and $z \wedge z'$ is the largest element of $\{\tilde{z} \in X : \tilde{z} < z\} \cap \{\tilde{z} \in X : \tilde{z} < z'\}$.

I shall need the following two facts, the facts are immediate from the definition of \leq .

FACT 1: If $z \in (\mathbb{C} \cup A) \setminus \{\bar{e}\}$, then $\underline{x} \in \{\tilde{z} \in X : \tilde{z} < z\} \subseteq \mathbb{B}_e$.

FACT 2: If $z \in (\mathbb{C} \cup A) \setminus \{\bar{e}\}$, then $\{\tilde{z} \in X : z < \tilde{z}\} = \mathbb{B}_{\bar{e}}$.

First, let $z \in \mathbb{B}_e$. Since z and z' are unordered, we must have $z' \in A$. Also, $z \neq \underline{x}$, as \underline{x} is the smallest element in X , so $z = \underline{x}$ would imply that z and z' are ordered. Note that $z \in \mathbb{B}_e \setminus \{\underline{x}\}$ implies that $\underline{x} \in \{\tilde{z} \in X : \tilde{z} < z\} \subseteq \mathbb{B}_e$, and $\{\tilde{z} \in X : z < \tilde{z}\} = \mathbb{B}_{\bar{e}}$. Hence, by facts 1 and 2,

$$\underline{x} \in \{\tilde{z} \in X : \tilde{z} < z\} \cap \{\tilde{z} \in X : \tilde{z} < z'\} \subseteq \mathbb{B}_e,$$

and

$$\{\tilde{z} \in X : z < \tilde{z}\} \cap \{\tilde{z} \in X : z' < \tilde{z}\} = \mathbb{B}_{\bar{e}}.$$

But \leq is a total order on \mathbb{B}_e , and \mathbb{B}_e is finite, so any non-empty subset of \mathbb{B}_e has a largest element. Thus $z \wedge z'$ exists. Similarly, $\mathbb{B}_{\bar{e}}$ is finite and totally ordered by \leq . So $\mathbb{B}_{\bar{e}}$ has a smallest element (namely \bar{e}), and $z \vee z'$ exists.

Second, let $z \in A$. Since z and z' are unordered we must have $z' \notin \mathbb{B}_{\bar{e}}$. Further, if $z' \in \mathbb{B}_e$ then we already proved above that $z \wedge z'$ and $z \vee z'$ exist. Let $z' \in (\mathbb{C} \cup A) \setminus \{\bar{e}\}$. Using facts 1 and 2 in as above, we know that $\{\tilde{z} \in X : \tilde{z} < z\} \cap \{\tilde{z} \in X : \tilde{z} < z'\}$ is a non-empty subset of \mathbb{B}_e , and that $\{\tilde{z} \in X : z < \tilde{z}\} \cap \{\tilde{z} \in X : z' < \tilde{z}\} = \mathbb{B}_{\bar{e}}$. Since \mathbb{B}_e and $\mathbb{B}_{\bar{e}}$ are finite, totally ordered sets, $z \wedge z'$ and $z \vee z'$ exist in X .

Third, let $z \in \mathbb{C} \setminus \{\underline{e}, \bar{e}\}$. Since z and z' are unordered, we must have $z' \in (\mathbb{C} \cup A) \setminus \{\underline{e}, \bar{e}\}$. If $z' \in A$, then we know that $z \wedge z'$ and $z \vee z'$ exist in X from the argument in the previous paragraph. If, $z' \in \mathbb{C}$, then

$$\underline{x} \in \{\tilde{z} \in X : \tilde{z} < z\} = \{\tilde{z} \in X : \tilde{z} < z'\} \subseteq \mathbb{B}_{\underline{e}}$$

and

$$\{\tilde{z} \in X : z < \tilde{z}\} = \{\tilde{z} \in X : z' < \tilde{z}\} = \mathbb{B}_{\bar{e}}.$$

Again $\mathbb{B}_{\underline{e}}$ and $\mathbb{B}_{\bar{e}}$ are finite and totally ordered by \leq , so $z \wedge z'$ and $z \vee z'$ exist in X .

Finally, if $z \in \mathbb{B}_{\bar{e}}$, z and z' cannot be unordered, as $z' \notin \mathbb{B}_{\bar{e}}$ implies $z' \leq z$, and $\mathbb{B}_{\bar{e}}$ is totally ordered by \leq .

STEP 3: Now I prove that f is monotone increasing.

Let $z \leq z'$. I need to prove that $f(z) \leq f(z')$. First, if $z \leq z'$ is due to item 1, then $f(z) \leq f(z')$ because $f(z) = f(z')$. And if $z \leq z'$ is due to item 2 it is immediate that $f(z) \leq f(z')$ by the definitions of $\leq_{\underline{e}}$ and $\leq_{\bar{e}}$.

Second, let $z \leq z'$ be due to item 3. $z \in \mathbb{B}_{\underline{e}}$ implies that $f(z) \in \mathbb{B}_{\underline{e}}$, and $z' \in \mathbb{C}$ implies that $f(z') \in \mathbb{C}$. So, we get $f(z) \leq f(z')$ by item 3.

Third, let $z \leq z'$ be due to item 4. $z' \in \mathbb{B}_{\bar{e}}$ implies that $f(z') \in \mathbb{B}_{\bar{e}}$. Also, $z \notin \mathbb{B}_{\bar{e}}$ implies $f(z) \notin \mathbb{B}_{\bar{e}}$, as, for any $\tilde{z} \in X$, $f(\tilde{z}) \in \mathbb{B}_{\bar{e}}$ implies $\tilde{z} \in \mathbb{B}_{\bar{e}}$ by the definition of $A_{\bar{e}}$. Hence $f(z) \leq f(z')$ due to item 4.

Fourth, let $z \leq z'$ be due to item 5. So, $z \in \mathbb{B}_{\underline{e}}$ and $z' \in A$. If $f(z') \in \mathbb{C}$, then $f(z) \leq f(z')$ by item 3, as $f(z) \in \mathbb{B}_{\underline{e}}$. Assume $f(z') \notin \mathbb{C}$. Since $z \leq z'$, $g_{\underline{e}}(z) \geq g(z')$. Now there must be a path $\hat{\pi}$ such that $g(z') = H_{\underline{e}} - [H_{\hat{\pi}} - h_{\hat{\pi}}(z')]$. Since $f(z') \notin \mathbb{C}$, we must have $f(z') \in \hat{\pi}$, and $h_{\hat{\pi}}(f(z')) = h_{\hat{\pi}}(z') - 1$. So,

$$\begin{aligned} g(f(z')) &\leq H_{\underline{e}} - [H_{\hat{\pi}} - h_{\hat{\pi}}(f(z'))] \\ &= H_{\underline{e}} - [H_{\hat{\pi}} - h_{\hat{\pi}}(z')] - 1 \\ &= g(z') - 1 \end{aligned}$$

On the other hand, $z \in \mathbb{B}_{\underline{e}}$, so either $z = \underline{e}$ or $z < \underline{e}$. First, if $z = \underline{e}$, then $f(z) = \underline{e}$, so $g_{\underline{e}}(z) = g_{\underline{e}}(f(z))$. Then $g_{\underline{e}}(z) \geq g(z')$ and $g(f(z')) \leq g(z') - 1$ implies that $g_{\underline{e}}(f(z)) \geq g(f(z'))$, so $f(z) \leq f(z')$ by item 5.

Second, if $z < \underline{e}$, then $g_{\underline{e}}(f(z)) = g_{\underline{e}}(z) - 1$. So, $g_{\underline{e}}(z) \geq g(z')$ implies that $g_{\underline{e}}(f(z)) = g_{\underline{e}}(z) - 1 \geq g(z') - 1 \geq g(f(z'))$. Thus $f(z) \leq f(z')$ by item 5.

STEP 4: Let \preceq be a partial order on X , such that (X, \preceq) is a complete lattice, f is monotone increasing, \underline{e} is the smallest fixed point of f , and \bar{e} is the largest fixed point of f . Let $z \in X$ be such that $\underline{e} \leq z \leq \bar{e}$. I prove that $\underline{e} \preceq z \preceq \bar{e}$.

Let $x^* = \inf_{\preceq} X$. By Theorem 4.3.4 in (Topkis, 1998), there is a $k \in \mathbf{N}$ such that $\underline{e} = f^k(x^*)$. Let K be the smallest such k , and note that $\underline{e} = f^k(x^*)$ for all $k \geq K$, as \underline{e} is a fixed point of f . Note also that the existence of K implies that $x^* \in \mathbb{B}_{\underline{e}}$, and note that $H_{\underline{e}} \geq K$.

Now, by the definition of \leq , $\underline{e} \leq z \leq \bar{e}$ implies that either $z \in \mathbb{C}$ or $z \in A$. Suppose, first, that $z \in \mathbb{C}$. Let $n \in \mathbf{N}$ be such that $z = f^n(z)$, at least one such n exists because $z \in \mathbb{C}$. Let $M \in \mathbf{N}$ be such that $K \leq nM$. Now, $x^* \preceq z$, because $x^* = \inf_{\preceq} X$. So, f monotone increasing implies that $f^{nM}(x^*) \preceq f^{nM}(z)$. But $K \leq nM$ implies that $f^{nM}(x^*) = \underline{e}$, so we have that $\underline{e} \leq z$. Repeat the argument with $\sup_{\preceq} X$ in the place of x^* and we get $z \preceq \bar{e}$.

Suppose now that $z \in A$. Then $\underline{e} \leq z$ implies that $g_{\underline{e}}(\underline{e}) \geq g(z)$. But $g_{\underline{e}}(\underline{e}) = 0$, so $0 \geq g(z)$. There is $\hat{\pi} \in \Pi$ such that $z \in \hat{\pi}$ and $g(z) = H_{\underline{e}} - [H_{\hat{\pi}} - h_{\hat{\pi}}(z)]$. Thus we have

$$H_{\hat{\pi}} - h_{\hat{\pi}}(z) \geq H_{\underline{e}} \geq K.$$

Let $z' = z_{H_{\hat{\pi}}}$. Then $z' \in \pi$, and

$$f^{H_{\hat{\pi}} - h_{\hat{\pi}}(z)}(z') = z.$$

Since $x^* = \inf_{\preceq} X$, we have $x^* \preceq z'$, so f monotone increasing and $H_{\hat{\pi}} - h_{\hat{\pi}}(z) \geq K$ implies that

$$\underline{e} = f^{H_{\hat{\pi}} - h_{\hat{\pi}}(z)}(x^*) \preceq f^{H_{\hat{\pi}} - h_{\hat{\pi}}(z)}(z') = z.$$

This proves that $\underline{e} \preceq z$. Now for \bar{e} : Recall that $H_{\underline{e}} \geq H_{\bar{e}}$, so $H_{\hat{\pi}} - h_{\hat{\pi}}(z) \geq H_{\bar{e}}$. By definition of $H_{\bar{e}}$, then,

$$f^{H_{\hat{\pi}} - h_{\hat{\pi}}(z)}(\sup_{\preceq} X) = \bar{e}.$$

But $z' \preceq \sup_{\preceq} X$ so

$$z = f^{H_{\hat{\pi}} - h_{\hat{\pi}}(z)}(z') \preceq f^{H_{\hat{\pi}} - h_{\hat{\pi}}(z)}(\sup_{\preceq} X) = \bar{e}.$$

This proves that $\underline{e} \preceq z \preceq \bar{e}$. □

Theorem 8. *Let X be a finite set, and $f : X \rightarrow X$ be a function. Let $\underline{e}, \bar{e} \in X$ be two fixed points of f . There is an order \leq on X such that (X, \leq) is a complete lattice, f is monotone increasing, and, for all $z \in \mathbb{B}_{\underline{e}}$ and $z' \in \mathbb{B}_{\bar{e}}$, $z < \underline{e}$ and $\bar{e} < z'$. Further, the interval prediction is*

$$[\underline{e}, \bar{e}] = X \setminus (\mathbb{B}_{\underline{e}} \cup \mathbb{B}_{\bar{e}}) \cup \{\underline{e}, \bar{e}\}.$$

Proof. Let g be the restriction of f to $\mathbb{B}_{\underline{e}}$. The range of g is in $\mathbb{B}_{\underline{e}}$, so $g : \mathbb{B}_{\underline{e}} \rightarrow \mathbb{B}_{\underline{e}}$. Since $g^n(x) = \underline{e}$ for some n for all x in $\mathbb{B}_{\underline{e}}$, g has exactly one fixed point, \underline{e} , and no cycles but \underline{e} . Then, by Theorem 2 there is a total order \preceq on $\mathbb{B}_{\underline{e}}$ such that g is monotone increasing. Also, the proof of Theorem 3 (step 2) shows that \underline{e} is the largest element in $\mathbb{B}_{\underline{e}}$. Similarly there is a total order \preceq' on $\mathbb{B}_{\bar{e}}$ such that the restriction of f to $\mathbb{B}_{\bar{e}}$ is monotone increasing and \bar{e} is the smallest element in $\mathbb{B}_{\bar{e}}$.

Now, let $h : X \setminus (\mathbb{B}_{\underline{e}} \cup \mathbb{B}_{\bar{e}}) \cup \{\underline{e}, \bar{e}\} \rightarrow X \setminus (\mathbb{B}_{\underline{e}} \cup \mathbb{B}_{\bar{e}}) \cup \{\underline{e}, \bar{e}\}$ be the restriction of f to $X \setminus (\mathbb{B}_{\underline{e}} \cup \mathbb{B}_{\bar{e}}) \cup \{\underline{e}, \bar{e}\}$. By Theorem 5 there is an order \preceq'' on $\hat{X} = X \setminus (\mathbb{B}_{\underline{e}} \cup \mathbb{B}_{\bar{e}}) \cup \{\underline{e}, \bar{e}\}$ such that (\hat{X}, \preceq'') is a complete lattice, h is monotone increasing, \underline{e} is the smallest element, and \bar{e} is the largest element.

Finally, define the order \leq on X by $x \leq y$ if and only if one of the following is true, a) $x \in \mathbb{B}_{\underline{e}}, y \notin \mathbb{B}_{\underline{e}}$ b) $x \notin \mathbb{B}_{\underline{e}} \cup \mathbb{B}_{\bar{e}}, y \in \mathbb{B}_{\underline{e}}$ c) $x, y \in \mathbb{B}_{\underline{e}}$ and $x \preceq y$ d) $x, y \in \mathbb{B}_{\bar{e}}$ and $x \preceq' y$, or e) $x, y \notin \mathbb{B}_{\underline{e}} \cup \mathbb{B}_{\bar{e}}$ and $x \preceq'' y$. It is routine to check that (X, \leq) is a complete lattice, and that f is monotone increasing. \square

The next section discusses how Theorem 8 improves on the order in Theorem 5.

5 Discussion of the interval prediction.

I show that there are games for which the interval prediction is unavoidably vacuous, and that there are games for which the interval prediction must contain strictly dominated strategies.

1. Consider the coordination game in Figure 1. I shall show that there is no order on strategies that preserves complementarities, and where the interval prediction is sharper than the whole strategy space. Let

$$b = b_1 \times b_2 : \{\alpha, \beta\}^2 \rightarrow \{\alpha, \beta\}^2$$

be the game's best-response function, and \leq be an order on $\{\alpha, \beta\}^2$ such that b is monotone increasing. Now, it must be that (α, β) and (β, α) are incomparable under \leq . To see this, let $(\alpha, \beta) < (\beta, \alpha)$, then $b(\beta, \alpha) = (\alpha, \beta) < b(\alpha, \beta) = (\beta, \alpha)$, and b is not increasing. Similarly if $(\beta, \alpha) < (\alpha, \beta)$. Then, for $(\{\alpha, \beta\}^2, \leq)$ to be a lattice, it must be that $(\alpha, \beta) \vee (\beta, \alpha)$ and $(\alpha, \beta) \wedge (\beta, \alpha)$ equals either (α, α) and (β, β) or, respectively, (β, β) and (α, α) . But $(\alpha, \beta) \vee (\beta, \alpha) \neq (\alpha, \beta) \wedge (\beta, \alpha)$, hence either (α, α) is the smallest strategy profile and (β, β) is the largest, or vice versa.

	α	β	γ	δ
α	2, 2	0, 0	0, 0	0, 0
β	0, 0	0, 1	1, 0	0, 0
γ	0, 0	1, 0	0, 1	0, 0
δ	0, 0	0, 0	0, 0	1, 1

Γ_3

	α'	β'
α	-1, 0	-1, 1
β	2, 2	0, 0
γ	0, 0	2, 2

Γ_4

Figure 4:

2. I show that this does not depend on the coordination game being $2X2$, it depends on the cycles in best-responses between the non-equilibrium strategy profiles (α, β) and (β, α) .⁶ In fact, consider the $4X4$ coordination game Γ_3 in Figure 4. In this game, best-responses have three cyclical orbits (besides the fixed-point cycles $(\alpha, \alpha) \rightarrow (\alpha, \alpha)$ and $(\delta, \delta) \rightarrow (\delta, \delta)$):

$$\begin{aligned}
 &(\beta, \alpha) \rightarrow (\alpha, \beta) \rightarrow (\gamma, \alpha) \rightarrow (\alpha, \gamma) \rightarrow (\beta, \alpha), \\
 &(\delta, \gamma) \rightarrow (\beta, \delta) \rightarrow (\delta, \beta) \rightarrow (\gamma, \delta) \rightarrow (\delta, \gamma), \\
 &\text{and } (\beta, \beta) \rightarrow (\gamma, \beta) \rightarrow (\gamma, \gamma) \rightarrow (\beta, \gamma) \rightarrow (\beta, \beta).
 \end{aligned}$$

Then, if a partial order \leq makes the $4X4$ coordination game into a GSC, no strategy that belongs to a cyclical orbit can be the smallest, or the largest, strategy profile of the game. To see this, suppose, for example, that (β, α) is the smallest strategy profile. Then $(\beta, \alpha) < (\alpha, \beta)$, so if b is monotone increasing, $b^3(\beta, \alpha) \leq b^3(\alpha, \beta)$. But $(\beta, \alpha) = b^3(\alpha, \beta)$ and $(\alpha, \beta) = b^3(\beta, \alpha)$. So it must be that the smallest and largest element in the strategy space is (α, α) and (δ, δ) , as a finite lattice has a smallest and a largest element.

3. The coordination game shows that it is *in general* impossible to sharpen the Milgrom-Roberts interval prediction. Theorem 8 does not improve on the order from Theorem 5 in the $2X2$ and $4X4$ coordination games discussed above. The reason is that the basins of both extremal equilibria in these examples are singletons, and all Theorem 8 guarantees is that non-equilibrium elements in the basins of the two extremal equilibria are not in the interval prediction.

On the other hand, all strategies in the coordination games are rationalizable. Theorem 8 may suggest that the interval prediction coincides with the set of rationalizable strategies. In fact, Theorem 8 leaves the non-equilibrium elements in the basins of two

⁶In both coordination games, all strategy profiles are rationalizable. So, it follows from Milgrom and Roberts's results that all strategy profiles are in the interval prediction. I show this directly here and in item 1 to make explicit the role of cycles.

equilibria out of the interval prediction, and the non-equilibrium element in the basin of an equilibrium are not rationalizable. I present an example where no order that makes the game a GSC, avoids strictly dominated strategies in the interval prediction.

Consider Γ_4 , the example on the right in Figure 4. In Γ_4 , player 1 has a strictly dominated strategy, α , but there is no order on strategies that preserves complementarities, and such that the interval prediction rules out 1 playing α .

There are two pure-strategy equilibria in Γ_4 , (γ, β') and (β, α') . Let us set $\underline{e} = (\gamma, \beta')$ and $\bar{e} = (\beta, \alpha')$. It is easy to check that the basins of \underline{e} and \bar{e} are, respectively, $\mathbb{B}_{\underline{e}} = \{(\alpha, \beta'), \underline{e}\}$ and $\mathbb{B}_{\bar{e}} = \{\bar{e}\}$. Then, Theorem 8 implies that there is an order such that best-responses in Γ_4 are monotone increasing, and the interval prediction is

$$[\underline{e}, \bar{e}] = \{(\gamma, \beta'), (\alpha, \alpha'), (\beta, \beta'), (\gamma, \alpha'), (\beta, \alpha')\}.$$

Note that the strategy pair (α, α') , where 1 selects a strictly dominated strategy, is in the interval prediction.

In fact, it is unavoidable that (α, α') is in the interval prediction. Let \leq be an order on $\{\alpha, \beta, \gamma\} \times \{\alpha', \beta'\}$ such that $(\{\alpha, \beta, \gamma\} \times \{\alpha', \beta'\}, \leq)$ is a complete lattice, and the best-response function, f , is monotone increasing. Say that $\underline{e} = (\gamma, \beta') < (\beta, \alpha') = \bar{e}$. Suppose we want $(\alpha, \alpha') \notin [\underline{e}, \bar{e}]$. Then, as (β, β') and (γ, α') are pairs of rationalizable strategies, we must have $(\beta, \beta'), (\gamma, \alpha') \in [\underline{e}, \bar{e}]$ (one can prove this directly, as in items 1 and 2 above). If $(\alpha, \alpha') < \underline{e}$ then $(\beta, \beta') = f(\alpha, \alpha') \leq \underline{e} = f(\underline{e})$, impossible since $(\beta, \beta') \in [\underline{e}, \bar{e}]$. Similarly, we cannot have $\bar{e} < (\alpha, \alpha')$, so (α, α') must be incomparable to either \underline{e} or \bar{e} . Say it is incomparable to \underline{e} , then we must have $(\alpha, \beta') = (\alpha, \alpha') \wedge \underline{e}$. But then there are only two candidates for $(\alpha, \alpha') \vee \underline{e}$: (β, β') and (γ, α') . But (β, β') and (γ, α') are cycles, as $(\gamma, \alpha') = f(\beta, \beta')$ and $(\beta, \beta') = f(\gamma, \alpha')$. Then they cannot be ordered, and we cannot have a smallest upper bound on (α, α') and \underline{e} . Similarly, (α, α') and \bar{e} cannot be unordered. So, it must be that $(\alpha, \alpha') \in [\underline{e}, \bar{e}]$.

6 Comparative Statics

In a parameterized GSC, if a parameter t is complementary to players' choices, there are selections of equilibria that are monotone increasing in t (Lippman, Mamer, and McCardle, 1987; Sobel, 1988; Villas-Boas, 1997; Milgrom and Roberts, 1990, 1994; Milgrom and Shannon, 1994; Echenique, 2002; Echenique and Sabarwal, 2000). By theorems 3 and 5, most games can be rationalized as GSC. A natural question is: can any comparative

	α	β
α	a, b	c, d
β	e, f	g, h

Γ_4

	α	β
α	$1, 1$	$0, 1$
β	$0, 1$	$1, 0$

Γ_5

Figure 5: Γ_3 used in the proof of, and Γ_4 illustrates, Proposition 9

statics conclusion be rationalized as coming from a parameterized GSC? The answer is no, comparative statics conclusions act as an “identifying condition” that restricts the choice of an order on strategy spaces.

Using the framework in (Milgrom and Roberts, 1994), the question can be phrased as follows. Let $f_t, f_{t'} : X \rightarrow X$, let e be a fixed point of f_t , and e' a fixed point of $f_{t'}$. Is there an order on X such that $e < e'$ and such that $f_t(x) \leq f_{t'}(x)$ for all x ?

In general the answer is no. Consider the following example, let $x, e, e' \in X$ with $e = f_t(e)$, $e' = f_{t'}(e')$ and $e \neq e'$. Suppose that $e' = f_t(x)$ and $e = f_{t'}(x)$. If there is an order \leq such that $f_t(z) \leq f_{t'}(z)$ for all $z \in X$, then $e = f_t(e) \leq f_{t'}(e) = e'$ and $e < e'$ because $e \neq e'$. But $e' = f_t(x) \leq f_{t'}(x) = e$, a contradiction.

The example above shows that we cannot rationalize comparative statics conclusions by a model where the parameter is complementary to players’ choices. Alternatively, is there an order on X such that $e < e'$ and such that f_t and $f_{t'}$ are monotone increasing functions? That is, can we rationalize a comparative statics conclusion as coming from parameterized GSC, even though the parameter may not be complementary to the strategies? The following example shows that this need not be the case. Let $x, e, e' \in X$ with $e = f_t(e)$, $e' = f_{t'}(e')$ and $e \neq e'$. Suppose that $x = f_t(e')$, $e = f_{t'}(x)$ and $e' = f_{t'}(e)$. Then $e < e'$ implies that $f_t(e) \leq f_t(e')$, so $e < x$. Then $f_{t'}(e) \leq f_{t'}(x)$ implies that $e' < e$, a contradiction.

7 Application 1: 2X2 Games

As an application of Theorems 3 and 5 I show that, generically, 2X2 games either have no equilibria or have complementarities. Essentially, then, 2X2 games are either isomorphic to “Matching Pennies”, or they are GSC.

Proposition 9. *Generically, a 2X2 game either has no pure-strategy Nash equilibrium, or it is a GSC.*

Proof. Consider the game in Figure 5 on the left. Suppose that a, b, c , etc. are such that (β, β) is the unique Nash equilibrium, and (β, β) is a strict equilibrium, so $c < g$ and $f < h$. I will rule out all possible cycles in best-response dynamics, except for the cycle involving (β, β) . Then Theorem 2 implies that the game is a GSC.

Since $c < g$ and $f < h$, (α, α) is not a best response to (α, β) or to (β, α) . This rules out the cycles $(\alpha, \alpha) \rightarrow (\alpha, \beta) \rightarrow (\alpha, \alpha)$, $(\alpha, \beta) \rightarrow (\alpha, \alpha) \rightarrow (\alpha, \beta)$, $(\alpha, \alpha) \rightarrow (\beta, \alpha) \rightarrow (\alpha, \alpha)$, $(\beta, \alpha) \rightarrow (\alpha, \alpha) \rightarrow (\beta, \alpha)$, $(\alpha, \alpha) \rightarrow (\beta, \alpha) \rightarrow (\alpha, \beta) \rightarrow (\alpha, \alpha)$, and $(\alpha, \alpha) \rightarrow (\alpha, \beta) \rightarrow (\beta, \alpha) \rightarrow (\alpha, \alpha)$.

Finally, the cycle $(\beta, \alpha) \rightarrow (\alpha, \beta) \rightarrow (\beta, \alpha)$ requires that $a \geq e$ and $b \geq d$. But then (α, α) would be an equilibrium, contradicting that (β, β) is the unique Nash equilibrium. Similarly for $(\alpha, \beta) \rightarrow (\beta, \alpha) \rightarrow (\alpha, \beta)$. These are all possible cycles.

We have shown that all $2X2$ games with a unique, strict Nash equilibrium are GSC. All games with more than one equilibrium are GSC by Theorem 5. The property that a unique equilibrium is strict is generic in the class of $2X2$ games. \square

Proposition 9 does not extend to more complex games than $2X2$, see the example in Figure 2 on the left. The “genericity” qualification in Proposition 9 is necessary. Consider the game on the right in Figure 5. This game has a unique Nash equilibrium (α, α) in pure strategies, and a cycle, $(\alpha, \alpha) \rightarrow (\alpha, \beta) \rightarrow (\beta, \alpha) \rightarrow (\alpha, \alpha)$. The cycle is produced by player 2’s indifference when 1 chooses α , which is non-generic.

8 Application 2: Ordinal Potential Games

A game $\Gamma = \{I, \{u_i\}_{i \in I}, \{S_i\}_{i \in I}\}$ is an **ordinal potential game** if there is a function $P : S = \times_{i \in I} S_i \rightarrow \mathbf{R}$ such that

$$u_i(s_i, s_{-i}) < u_i(s'_i, s_{-i}) \text{ if and only if } P(s_i, s_{-i}) < P(s'_i, s_{-i}),$$

for all $s_i, s'_i \in S_i$, $s_{-i} \in S_{-i}$, and $i \in I$. Potential games were studied in detail by (Monderer and Shapley, 1996) (see their paper for references to earlier work on potential games).

My results shed some light on the relation between GSC and ordinal potential games. I show that, generically, a finite two-player ordinal potential game is a GSC; and that ordinal potential games with more than two players need not be GSC.⁷

⁷Further, it is easy to see that GSC need not be ordinal potential games. I do not discuss this here, the counterexamples are very simple.

	α	β	
α	-1, -1, -1	-1, -1, -1	
β	1, 1, 0	0, 0, 1	
γ	0, 0, 1	1, 1, 0	
	α		

	α	β
α	1, 1, 1	1, 0, 1
β	0, 1, 1	0, 0, 0
γ	0, 0, 0	0, 1, 1
	α	β

Figure 6: A three-player ordinal potential game that is not a GSC.

Proposition 10. *Let Γ be a finite two-player game with unique best responses. If Γ is an ordinal potential game, then it is a GSC.*

Proposition 10 does not extend to games with more than two players. For a counterexample, consider the three-player game in Figure 6. Here, player 1 chooses a strategy in $S_1 = \{\alpha, \beta, \gamma\}$ (rows), player 2 chooses a strategy in $S_2 = \{\alpha, \beta\}$ (columns), and player 3 a strategy in $S_3 = \{\alpha, \beta\}$ (matrices). The payoffs are indicated in the figure.

The game in Figure 6 has a unique equilibrium, (α, α, β) , and the best-response cycle $(\beta, \beta, \alpha) \rightarrow (\gamma, \alpha, \alpha) \rightarrow (\beta, \beta, \alpha)$. By Theorem 2, then, there is no order on strategies so that his game is a GSC. But by Monderer and Shapley’s results, the game has a generalized ordinal potential, as it has the finite improvement property (this is a bit cumbersome to check). Now just perturb the game a bit, it still will not be a GSC because the best-response cycle will persist, and it will be an ordinal potential game by Monderer and Shapley’s Corollary 2.6.

Proof of Proposition 10 To prove Proposition 10, I need two definitions and two lemmas. Let $\Gamma = \{S_1, S_2, u_1, u_2\}$ be a two-player game with unique best-responses, and let $\beta(s_1, s_2) = (\beta_1(s_2), \beta_2(s_1))$ be Γ ’s best-response function—note the minor change in notation. A *best-response cycle* of Γ is a sequence (s^0, s^1, \dots, s^n) in $S = S_1 \times S_2$, where $s^k = \beta(s^{k-1})$, $1 \leq k \leq n$, $s^0 = s^n$, and $s^{k-1} \neq s^k$, $1 \leq k \leq n$. The use of the term “cycle” here is inconsistent with the rest of the paper, but no confusion should arise because it will be clear, at all times in this section, that a cycle is the whole path (s^0, s^1, \dots, s^n) , not a point in the range of the path.

An *infinite improvement path* in S is a sequence (w^0, w^1, \dots) such that:

- (w^0, w^1, \dots) is not eventually constant (i.e. there is no K such that the sequence (w^K, w^{K+1}, \dots) is constant).
- w^{k-1} and w^k differ in at most one component,

- if w^{k-1} and w^k differ, and i is the player that changes strategy between w^{k-1} and w^k , then $u_i(w^{k-1}) < u_i(w^k)$.

The definition of an infinite improvement path differs from the one in Monderer and Shapley. However, it is immediate to modify their Lemma 2.3 to show:

Lemma 11. (*Monderer and Shapley, 1996*) *An ordinal potential game cannot have an infinite improvement path.*

I do not include a proof of Lemma 11 in this paper.

Lemma 12. *Let Γ be a two-player game with unique best responses and a unique Nash equilibrium. If Γ has a best-response cycle, then it has an infinite improvement path.*

Proof. Let (s^0, s^1, \dots, s^n) be a best-response cycle. We must have $n \geq 2$, or (s^0, s^1, \dots, s^n) is a constant sequence.

I claim that either $s_1^0 \neq s_1^2$, $s_2^0 \neq s_2^2$, or both hold. Suppose, by way of contradiction, that $s_1^0 = s_1^2$ and $s_2^0 = s_2^2$. Then $s_1^0 = \beta_1(s_2^1)$ and $s_2^0 = \beta_2(s_1^1)$. Now $s_1^1 = \beta_1(s_2^0)$ and $s_2^1 = \beta_2(s_1^0)$ imply that (s_1^0, s_2^1) and (s_1^1, s_2^0) are Nash equilibria. But there is a unique Nash equilibrium, so $(s_1^0, s_2^1) = (s_1^1, s_2^0)$; impossible, as $(s_1^0, s_2^0) = s^0 \neq s^1 = (s_1^1, s_2^1)$. Suppose, without loss of generality, that $s_2^0 \neq s_2^2$.

Extend the sequence (s^0, s^1, \dots, s^n) to the infinite sequence

$$(s^0, s^1, \dots, s^{n-1}, s^0, s^1, \dots).$$

So, s_1^{n+1} refers to s_1^1 , s_2^{2n+3} to s_2^3 , and so on. Construct the sequence

$$w = (w^0, w^1, w^2, \dots) = ((s_1^1, s_2^0), (s_1^1, s_2^2), (s_1^3, s_2^2), (s_1^3, s_2^4), (s_1^5, s_2^4), (s_1^5, s_2^6), \dots).$$

I shall show that w is an infinite improvement path.

If n is odd, we can construct the following finite sequences:

$$\begin{aligned} y^0 &= (s_1^1, s_2^0) & z^0 &= (s_1^0, s_2^1) \\ y^1 &= (s_1^1, s_2^2) & z^1 &= (s_1^2, s_2^1) \\ y^2 &= (s_1^3, s_2^2) & z^2 &= (s_1^2, s_2^3) \\ y^3 &= (s_1^3, s_2^4) & z^3 &= (s_1^4, s_2^3) \\ & & & \vdots \\ & & & \vdots \\ y^{n-1} &= (s_1^n, s_2^{n-1}) = (s_1^0, s_2^{n-1}) & z^{n-1} &= (s_1^{n-1}, s_2^n) = (s_1^{n-1}, s_2^0) \end{aligned}$$

If n is even, we shall only need the y sequence as constructed, with the modification that we get $y^{n-1} = (s_1^{n-1}, s_2^n) = (s_1^{n-1}, s_2^0)$.

It is easy, if somewhat cumbersome, to show that: If n is odd, then

$$w = (y^0, y^1, \dots, y^{n-1}, z^0, z^1, \dots, z^{n-1}, y^0, y^1, \dots).$$

And that, if n is even, then

$$w = (y^0, y^1, \dots, y^{n-1}, y^0, y^1, \dots).$$

In both cases, w is not eventually constant, as $y_0 \neq y_1$ because $s_2^0 \neq s_2^2$.

Let $w^{k-1} \neq w^k$. If $w^{k-1} = (s_1^k, s_2^{k-1})$, and $w^k = (s_1^k, s_2^{k+1})$, then $s_2^{k-1} \neq s_2^{k+1} = \beta_2(s_1^k)$. Best-responses are unique, then $u_2(s_1^k, s_2^{k-1}) < u_2(s_1^k, s_2^{k+1})$. Similarly if $w^k = (s_1^{k+1}, s_2^k)$, and $w^{k-1} = (s_1^{k-1}, s_2^k)$. So, w is an infinite improvement path. \square

By Monderer and Shapley's (1996) Corollary 2.2, Γ has at least one equilibrium. If it has two or more equilibria, it is a GSC by Theorem 5. Let Γ have a unique equilibrium. Lemma 11 implies that Γ cannot have an infinite improvement path, so Lemma 12 implies that it cannot have a best-response cycle; by Theorem 2, then, Γ is a GSC. \square

9 Proof of Theorem 3

I prove the second statement in Step 1. Steps 2 and 3 prove the first statement when X is finite—Step 2 constructs an order such that ϕ is weakly increasing, and Step 3 checks that this is a total order. Steps 4 and 5 prove the first statement for arbitrary X by non-standard analysis methods. The idea is to embed X in a hyperfinite set, apply the result for finite sets to get an order that works in the hyperfinite set, and then restrict the order to X .

STEP 1. Let \leq be a total order on X such that ϕ is increasing in the strong set order, and let $x \neq e$. Suppose, by way of contradiction, that there is $\{x_m\}_{m=0}^K \subseteq X$ such that $x = x_0 = x_K$ and $x_m \in \phi(x_{m-1})$, $1 \leq m \leq K-1$. Note that we must have $x_m \neq e$ for all m because $\phi(e) = \{e\}$ would imply that $x = e$.

Since X is totally ordered by \leq , either $x < x_{K-1}$ or $x_{K-1} < x$, as $x = x_{K-1}$ is ruled out because x is not a fixed point. Suppose that $x < x_{K-1}$, I will show by induction that $x_K < x_{K-1} < \dots < x_0 = x$, a contradiction. First, $x < x_{K-1}$ implies that $\phi(x) \ni x_1$ is smaller than $\phi(x_{K-1}) \ni x$ in the strong set order, so $x_1 \wedge x \in \phi(x)$. Now, $x_1 \wedge x \in \{x_1, x\}$ because \leq is a total order, and $x \notin \phi(x)$ because x is not a fixed point. So we must have

$x_1 < x$. Now for the inductive step, I want to show that, if $x_m < x_{m-1}$, then $x_{m+1} < x_m$ ($1 \leq m \leq K-1$). If $x_m < x_{m-1}$, then $\phi(x_m) \ni x_{m+1}$ is smaller than $\phi(x_{m-1}) \ni x_m$ in the strong set order. Then $\{x_{m+1}, x_m\} \ni x_{m+1} \wedge x_m \in \phi(x_m)$, but $x_m \notin \phi(x_m)$ as $x_m \neq e$, so $x_{m+1} < x_m$.

If, instead, $x > x_{K-1}$ we can apply an analogous argument to reach a contradiction. So there cannot be a K with $x \in \phi^K(x)$.

STEP 2. Let X be finite. Let $\phi : X \rightarrow X$ be a correspondence with a unique fixed point $e \in X$, and no cycles besides e . For all $x \in X$ there is at least one sequence $\{x_m\}_{m=0}^K$ with $x_0 = x$, $x_m \in \phi(x_{m-1})$, $m = 1, 2, \dots, K$, and $x_K = e$; that is a *path* connecting x and e , K is the length of the path. To see that such a path must exist, note that, by absence of cycles, if $x_m \neq e$ for $m = 1, 2, \dots, K$, then $\{x_m\}_{m=0}^K$ are all distinct, so X has at least $K+1$ elements. X is finite, so we must have, for K large enough, that $x_K = e$. For each $x \in X$, let K_x be the smallest K such that there is a path of length K connecting x and e . Clearly, $K_e = 0$. Fix, for each x , a path of minimal length $\{x_m\}_{m=0}^{K_x}$ connecting x and e . Note that $K_{x_1} = K_x - 1$, as the K 's are minimal.

Define $X_m = \{x \in X : K_x = m\}$, $m = 0, 1, \dots, M$, where M is such that $X = \bigcup_{m=0}^M X_m$. The collection $\{X_m\}_{m=0}^M$ is a partition of X because it covers X and has disjoint elements, as the K_x s are minimal.

I shall define recursively an order \leq_m on X_m , $m = 0, 1, \dots, M$. Let \preceq be a total order on X such that e is the largest element of X (for example, embed X in \mathbf{N} such that e is mapped to a number larger than any other element in X , and take the relative order on X). Let \leq_0 on X_0 , be the restriction of \preceq to X_0 . Given a total order \leq_m on X_m , let \leq_{m+1} on X_{m+1} be defined by, $x \leq_{m+1} y$ if $x_1 <_m y_1$ or if $x_1 = y_1$ and $x \preceq y$, where x_1 and y_1 are the first elements in the paths connecting x and y , respectively, to e . Note that \leq_m is in fact a total order because it is a lexicographic order.

Finally, define a total order \leq on X by $x \leq y$ if either $k_y < k_x$ or if $k_y = k_x$ and $x \leq_{k_x} y$. Note that e is the largest element in X .

STEP 3. I shall check that ϕ is weakly increasing. Let $x, y \in X$ and $\{x_m\}_{m=0}^{K_x}$, $\{y_m\}_{m=0}^{K_y}$ be the paths of minimal length connecting x and y to e from step 2.

Let $x \leq y$. If $K_y < K_x$ then there is $x_1 \in \phi(x)$ and $y_1 \in \phi(y)$, $x_1 \in \{x_m\}_{m=0}^{K_x}$, $y_1 \in \{y_m\}_{m=0}^{K_y}$, with $K_{y_1} = K_y - 1 < K_x - 1 = K_{x_1}$ because the K 's are minimal. Then, $x_1 \leq y_1$. If $K_y = K_x$ then there is $x_1 \in \phi(x)$ and $y_1 \in \phi(y)$, $x_1 \in \{x_m\}_{m=0}^{K_x}$, $y_1 \in \{y_m\}_{m=0}^{K_y}$ with $x_1 \leq_{K_x+1} y_1$. Then $K_{y_1} = K_y - 1 = K_x - 1 = K_{x_1}$, because the K 's are minimal. Then, $x_1 \leq y_1$. In both cases there is $x_1 \in \phi(x)$ and $y_1 \in \phi(y)$ with $x_1 \leq y_1$, thus proving

that ϕ is weakly increasing

To prove that \leq is a total order, note first that $x \leq x$ because x is in some X_m , and $x \leq_m x$, as \leq_m is an order; thus \leq is reflexive. If $x \leq y$ and $y \leq x$ then we must have $K_x = K_y$, and then $x = y$ because \leq_{K_x} is an order. So, \leq is antisymmetric. Let $x \leq y$ and $y \leq z$. If $K_y < K_x$ or $K_z < K_y$ then $K_z < K_x$ and $x \leq z$. If $K_x = K_y = K_z$ then $x \leq z$ follows from transitivity of \leq_{K_x} . Thus \leq is transitive. Finally, \leq is total because if $x, y \in X$ then there is m, n such that $x \in X_m$ and $y \in X_n$. If $m < n$ or $n < m$, x and y are ordered. If $n = m$, x and y are ordered because \leq_m is a total order.

STEP 4. Suppose first that $\phi(e) = \{e\}$. Let H be a hyperfinite set with $X \subseteq H \subseteq *X$. For all $x \in X$, $\phi(x)$ is finite, then $*\phi$ takes hyperfinite values, and therefore $*\phi(H)$ is hyperfinite, as it is the hyperfinite union of hyperfinite sets. Let $\tilde{H} = H \cup *\phi(H)$, \tilde{H} is hyperfinite.

By the Transfer Principle, $h \in H$ implies $(h \in *\phi(h) \Rightarrow h = e)$. Define $\tilde{\phi} : \tilde{H} \rightarrow \tilde{H}$ by

$$\tilde{\phi}(h) = \begin{cases} *\phi(h) & \text{if } h \in H \\ \{e\} & \text{if } h \in \tilde{H} \setminus H. \end{cases}$$

$\tilde{\phi}$ is internal, and $\tilde{\phi}(e) = *\phi(e) = \{e\}$. I show that e is the only fixed point of $\tilde{\phi}$. Suppose $x \in \tilde{\phi}(x)$. First, if $x \in H$, then $\tilde{\phi}(x) = *\phi(x)$, so $x \in *\phi(x)$ implies that $x = e$ by Transfer. Second, if $x \in \tilde{H} \setminus H$ then $\tilde{\phi}(x) = \{e\}$, so $x = e \in H$, a contradiction.

To show that $\tilde{\phi}$ has no cycles except for e , suppose that $x \in \tilde{\phi}^K(x)$ for some $x \in \tilde{H}$ and $K \in *\mathbf{N}$. Note that $x \in H$ because $x \in \tilde{H} \setminus H$ implies that $\tilde{\phi}^m(x) = \{e\}$ for all m , and $e \in H$. There is a sequence $\{x_m\}_{m=0}^K$ with $x_0 = x_K = x$ and $x_m \in \tilde{\phi}(x_{m-1})$, $m = 1, 2, \dots, K$. If there is m such that $x_m \in \tilde{H} \setminus H$ then $e = x_l$, $m \leq l \leq K$, so $x = e$. On the other hand, if $x_{m-1} \in H$ for all m , then $x_m \in \tilde{\phi}(x_{m-1}) = *\phi(x_{m-1})$ for all m . Then x is a cycle of $*\phi$, so $x = e$ by Transfer.

Then, \tilde{H} is hyperfinite, $\tilde{\phi} : \tilde{H} \rightarrow \tilde{H}$ has a unique fixed point e , and no cycles but e . By steps 2 and 3 above and the Transfer Principle, there is a total order \triangleleft on H such that $x \triangleleft e$ for all $x \in H$, and such that $x \triangleleft y$ implies that there is $z \in \tilde{\phi}(x)$ and $z' \in \tilde{\phi}(y)$ with $z \triangleleft z'$. Let \leq be the restriction of \triangleleft to $X \subseteq \tilde{H}$, \leq is a total order on X , and e is its largest element.

To verify that ϕ is weakly increasing, let $x \leq y$. Then, $x \triangleleft y$ implies that there is $z \in \tilde{\phi}(x)$ and $z' \in \tilde{\phi}(y)$ with $z \triangleleft z'$. But $\tilde{\phi}(x) = *\phi(x) = \phi(x)$ and $\tilde{\phi}(y) = *\phi(y) = \phi(y)$, as $x, y \in X \subseteq H$. Then $z \in \phi(x)$, $z' \in \phi(y)$, and $z \leq z'$ because $z \triangleleft z'$.

STEP 5. Finally, let $\phi(e) \neq \{e\}$, and let $\phi' : X \rightarrow X$ coincide with ϕ on $X \setminus \{e\}$, and

take the value $\{e\}$ on e . By step 4 there is an order \leq on X such that e is its largest element and such that ϕ' is weakly increasing. Now we check that ϕ is weakly increasing in this order as well. We only need to prove that if $x \in X$ then there is $z \in \phi(x)$ and $z' \in \phi(e)$ with $z \leq z'$. But, since $e \in \phi(e)$ and e is the largest element in X , we can set $z' = e$ and be done. \square

References

- AMIR, R. (1996): “Cournot Oligopoly and the Theory of Supermodular Games,” *Games and Economic Behavior*, 15, 132–148.
- AMIR, R., AND V. E. LAMBSON (2000): “On the Effects of Entry in Cournot Markets,” *Review of Economic Studies*, 67(2), 235–254.
- ECHENIQUE, F. (2000): “Mixed Equilibria in Games of Strategic Complements,” Forthcoming in *Economic Theory*.
- (2001): “The Equilibrium Set of a Two-Player Game with Complementarities is a Sublattice,” Forthcoming in *Economic Theory*.
- (2002): “Comparative Statics by Adaptive Dynamics and The Correspondence Principle,” *Econometrica*, 70(2), 833–844.
- ECHENIQUE, F., AND T. SABARWAL (2000): “Strong Comparative Statics of Equilibrium,” Forthcoming in *Games and Economic Behavior*.
- GABAY, D., AND H. MOULIN (1980): “On the Uniqueness and Stability of Nash-equilibria in Noncooperative Games,” in *Applied Stochastic Control in Econometrics and Management Science*, ed. by P. K. A. Bousoussan, and C. Tapiero, pp. 271–293. North Holland Publishing Company.
- LIPPMAN, S. A., J. W. MAMER, AND K. F. MCCARDLE (1987): “Comparative Statics in Non-cooperative Games via Transfinitely Iterated Play,” *Journal of Economic Theory*, 41(2), 288–303.
- MILGROM, P., AND J. ROBERTS (1990): “Rationalizability, Learning and Equilibrium in Games with Strategic Complementarities,” *Econometrica*, 58(6), 1255–1277.

- (1994): “Comparing Equilibria,” *American Economic Review*, 84(3), 441–459.
- MILGROM, P., AND C. SHANNON (1994): “Monotone Comparative Statics,” *Econometrica*, 62(1), 157–180.
- MONDERER, D., AND L. S. SHAPLEY (1996): “Potential Games,” *Games and Economic Behavior*, 14, 124–143.
- MORRIS, S., AND H. S. SHIN (2000): “Global Games: Theory and Applications,” Prepared for the Eighth World Congress of the Econometric Society.
- SOBEL, M. J. (1988): “Isotone Comparative Statics in Supermodular Games,” mimeo, SUNY at Stony Brooks.
- TOPKIS, D. M. (1979): “Equilibrium Points in Nonzero-Sum n -Person Submodular Games,” *SIAM Journal of Control and Optimization*, 17(6), 773–787.
- (1998): *Supermodularity and Complementarity*. Princeton University Press, Princeton, New Jersey.
- VILLAS-BOAS, J. M. (1997): “Comparative Statics of Fixed Points,” *Journal of Economic Theory*, 73(1), 183–198.
- VIVES, X. (1985): “Nash Equilibrium in Oligopoly Games with Monotone Best Responses,” CARESS Working Paper 85-10, University of Pennsylvania.
- (1990): “Nash Equilibrium with Strategic Complementarities,” *Journal of Mathematical Economics*, 19(3), 305–321.
- ZHOU, L. (1994): “The Set of Nash Equilibria of a Supermodular Game Is a Complete Lattice,” *Games and Economic Behavior*, 7(2), 295–300.