

A Comparison of Laser and Microwave Approaches to CW Beamed Energy Launch

Jordin T. Kare[†] and Kevin L. G. Parkin[‡]

[†]*Kare Technical Consulting, 908 15th Ave. East Seattle WA 98112, USA*

[‡]*Division of Engineering and Applied Science, California Institute of Technology,
1200 East California Boulevard, Pasadena, CA 91125, USA*

Abstract. One approach to beamed energy propulsion uses a solid heat exchanger to absorb energy from a distant source and transfer it to a working fluid. Systems of this type can be designed using either microwave or laser sources. In general, microwave sources have been expected to be less expensive than lasers for a given power, but to be more limited in range and/or energy density. With the development of high power millimeter-wave sources and low-cost diode laser arrays, both assumptions are open to question. In this paper, we compare current and projected microwave and laser source technologies for a 100-kilogram-class ground-to-orbit launch system and identify key issues affecting the system-level trade between the two approaches.

HEAT-EXCHANGER LAUNCH CONCEPTS

The laser-driven Heat Exchanger (HX) approach to ground-to-orbit laser launch was proposed by Kare in 1993 [1] as an alternative to pulsed ablative propulsion, primarily as way to continue laser launch development with continuous-wave (CW) lasers after the end of large-scale development of high-average-power pulsed lasers. [2] The microwave thermal rocket was independently proposed by Parkin in 2003 [3] as an adaptation of nuclear thermal propulsion to an external ground-based microwave energy source rather than an on-board nuclear reactor.

Both Kare and Parkin offered conceptual designs for a system capable of launching 100 kg payloads to low Earth orbit. The two designs differ radically, as shown in Table 1, effectively illustrating the wide design space available with heat-exchanger propulsion. Nevertheless, either system could be implemented with only minor changes using either a laser or microwave source. This suggests that we can compare laser and microwave-based systems without considering the details of the vehicle design. This paper compares the two systems from the standpoint of the technical maturity, efficiency, and capital cost of the beam source – from power plant through laser or microwave generator to transmitting optics or antennas.

The reference laser source considered is described by Kare in [4]. It consists of a few thousand independent beam modules, each of which produces 50 kW of beam power at 1.08 μm . Each beam module consists of six 10-kW diode-pumped fiber lasers feeding a single 1-meter-class telescope with its own pointing and tracking system. Beam modules are preferred over a single large laser and beam director due to their much lower development cost and ability to leverage industrial and military laser development.

TABLE 1. Approximate parameters of proposed launch system concepts

	Laser (Kare)	Microwave (Parkin)
Design vacuum I_{sp}	600 seconds	800-1000 seconds
Heat exchanger material	Metallic Ni	Silicon Carbide
Heat exchanger type	Laminar flow	Turbulent flow
Operating temperature	1000 C	2500 C
Operating flux	5 MW/m ²	30 MW/m ²
Propellant feed system	Pressure fed	Pump fed
Vehicle type	Expendable	Reusable
Power at vehicle	100 MW	300 MW
Powered trajectory length	600-800 km	200 km
Powered flight time	400 s	200 s
Design payload to orbit	100 kg	100 kg

The microwave source is a phased array of several hundred closely-spaced parabolic dish antennas, each fed by a single 1 MW-class gyrotron oscillator operating at 140 GHz (2.1 mm wavelength). The antennas are mechanically steered to track the vehicle, with fine pointing done electronically via phase control over the array. This design is derived from a 30 MW, 245 GHz, ground-based beam facility proposed and analyzed by Myrabo, Benford, and Dickinson [5,6], with the frequency chosen to correspond to the shortest-wavelength commercially available gyrotrons. An optimization among atmospheric transmission, array size, and possible future gyrotron technology has yet to be attempted.

TECHNOLOGY READINESS

Laser

Fiber lasers up to 1 kW power are in commercial production; using the NASA Technology Readiness Level (TRL) scale [7], they are TRL 8 (TRL 9 being reserved for technology that has actually been used in a launcher or similar field application). Multi-kW single-fiber lasers are regarded by the laser community as feasible [8]; alternatively, fiber lasers appear to be well-suited to phase-locking or wavelength-combining techniques that would provide the radiance (power per unit area per unit solid angle) of a multi-kW laser without further increases in single-fiber power. We assign a TRL of 3 (“Analytical and experimental critical function and/or characteristic proof of concept”) to 10-kW fiber laser sources, but expect that multi-kilowatt fiber lasers will be developed independently of any laser launch project, because of their wide potential applications.

Lower power lasers could be used for a launcher, although each laser requires a diffraction-limited minimum aperture, so the total telescope area is inversely proportional to the unit laser power. However, existing lasers would require considerable redesign to reduce costs to a practical level for a launch system, so they can only be considered breadboard versions (TRL 5) of launch system hardware.

Other suitable laser technologies for the modular laser source are also at TRL 3, including Diode Pumped Alkali-vapor Lasers (DPALs) [9] and noncoherent laser diode arrays with spectral beam combining [10].

Microwave Source

Individual 900 kW continuous wave (CW) gyrotrons at 110 GHz and 140 GHz are TRL 8: in commercial production, with further development being driven by their application to electron cyclotron-resonance heating (ECH) systems for magnetic-confinement fusion experiments such as DIII-D [11].

In principle, any number of gyrotron oscillators can be phase-locked to produce a common frequency. Phase locking of microwave oscillators has been used since the 1940s and has reached powers exceeding 1 GW [12]. Phase locking of gyrotron oscillators has been analyzed [13], but it has been demonstrated only at low power and with small numbers of oscillators [14]. Hence, phase locking of gyrotrons is at TRL 3-4. We estimate that developing the hardware for a large phase-locked 140 GHz gyrotron array will require a development effort comparable to that for 10-kW-class fiber lasers. The technical risk of such an effort is probably low compared to laser development, but the cost may be high because several high-power gyrotrons are needed for realistic tests.

A master oscillator - power amplifier (MOPA) configuration avoids the phase stability issues of large phase-locked oscillator arrays. However, CW gyrotron amplifiers above 100 GHz are substantially less developed than power oscillators, placing them also at TRL 4. A near term TRL 5-6 option is to use larger numbers of less powerful gyro-klystron amplifiers developed for W-band (94 GHz) radar applications, but the cost of such a system is unknown.

Apertures and Array

The laser system's optical telescope/beam director technology is TRL 8 – existing high-power laser systems such as the Tactical High Energy Laser use essentially similar beam directors at comparable power levels. The baseline launch system is sized specifically to avoid the need to correct for atmospheric turbulence, so adaptive optics technologies are not needed, and each beam module operates independently, so no special techniques are needed for an array of modules. The specific hardware used for launch system beam modules will be new, however, so the beam director is TRL 5.

Millimeter-wave steerable dish antennas have such an extensive field history that they can reasonably be classed as TRL 9. Receive-only millimeter-wave phased arrays of steerable dishes have been demonstrated in radioastronomy. High power phased arrays with electronic steering and tracking are used in military radars. Feed systems (except for rotary joints) are comparable to fusion experiment ECH feed systems.

However, a launch system array would be unprecedented in size and average power, and in the combination of number of apertures, precision, and tracking requirements. In particular, no suitable real-time phase measurement and correction system has been demonstrated or, to our knowledge, designed. Consequently, we place the phase control system, and thus the phased array as a whole, at TRL 2-3.

Table 2 summarizes the technology readiness levels for the two systems.

TABLE 2. Estimated Technology Readiness Levels

Laser		Microwave	
Laser		Gyrotron	
1 kW	4-6	Single 1 MW	8
10 kW	3	Phase locked array	3
		Gyroklystron MOPA	5
Overall source	3		3
Beam director		Antenna array	
Telescope	8-9	mm-wave dish	9
Fore optics	6	Feed	5
Fiber feed	4	Phase control	2-3
Pointing/tracking	5	Integrated system	2-3
Overall aperture	4		2-3
Overall system	3		2-3

EFFICIENCY

Source Efficiency

Nominal efficiencies and likely ranges of efficiency for laser and microwave sources are given in Table 3.

The laser diode efficiency is a compromise between the 50–55% efficiencies of current production diode arrays at 25 C, and efficiencies of 70-75% that have been demonstrated in single diodes [15]. A further few-percent gain in efficiency is possible by operating diode arrays at 10 C.

For CW gyrotrons at 110 GHz, the advent of single depressed collectors in the mid 1990s raised practical gyrotron DC efficiency from 30% to 50%, with a 62% theoretical limit [16]. In practice, the current state of the art allows routine operation at 40% efficiency, with 50% as a goal for near-future systems. Multistage collectors offer further improvements but are as yet untried.

Gyrotrons have a small advantage in DC power supply efficiency because they operate at high voltage; ohmic losses and semiconductor voltage drops are more significant in low-voltage, high-current diode laser supplies.

TABLE 3. Laser and gyrotron efficiency

	Nominal	Range
Laser diodes (DC-diode light)	65%	55-75%
Fiber conversion (diode light – fiber light)	80%	70-90%
Laser DC efficiency	52%	39-69%
Power supply	95%	90-95%
Laser wallplug efficiency	49%	35-64%
Gyrotrons (depressed collector)	50%	40-55%
Power supply	97%	95-99%
Gyrotron wallplug efficiency	49%	38-54%

Aperture Efficiency

The aperture efficiency η_{ap} accounts for power lost between the laser or gyrotron output and free space, due to absorption, scattering, spillover (energy lost around the edges of optics), and blockage or diffraction by secondary reflectors and struts. For the laser system, η_{ap} will be in the range of 0.8 to 0.9, assuming all optics including the primary mirror are multilayer coated for high reflectance. Our nominal value is $\eta_{ap} = 0.83$, i.e., 50 kW module output power from 60 kW of laser power.

The losses for a single microwave aperture will probably be in the same range, although in the absence of a specific antenna and feed design the uncertainties are larger. The ECH system on the D-III-D fusion experiment has waveguide losses of 2%/40 m and 0.6% per dihedral (sharp) bend [17], so waveguide losses from the gyrotron to the antenna feed can be as small as a few percent, provided the gyrotron is adjacent to the antenna. We take the same nominal value of $\eta_{ap} = 0.83$, with the caveat that system trades – for example, locating the gyrotrons in a common building outside the antenna array – could lower the efficiency 10% or more.

Array Efficiency

To a first approximation, if individual antennas are uniformly illuminated and in perfect phase, a phased array of dish antennas has an efficiency η_{array} equal to f_{fill} , the fraction of the array area filled by antenna surface. The lost energy is radiated into sidelobes of the desired main beam. A close-packed hexagonal array of circular dishes has $f_{fill} = \pi/(2\sqrt{3}) \approx 0.907$. Practical issues, such as ensuring dishes do not collide if there is a drive or control failure, may reduce f_{fill} considerably.

If the array is mechanically steered away from zenith by an angle θ_z (except by

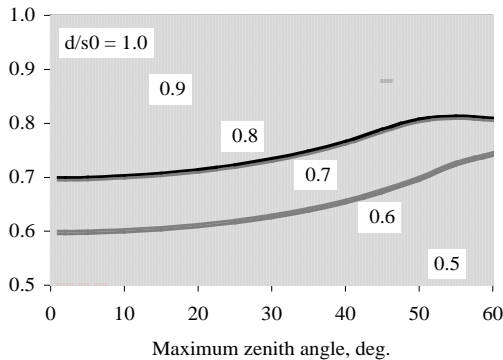


FIGURE 1. Efficiency of a phased array of steerable dishes, averaged over zenith angle, due to fill factor (sidelobe) losses and mutual blockage. d is the row width (\sim dish diameter); s_0 is the row spacing.

tilting the entire array as a unit) the projected spacing between antennas in the direction of the steering will be $s = s_0 \cos(\theta_z)$. This will initially increase efficiency as the apparent gaps between antennas are reduced, then decrease efficiency as antenna beams are blocked by neighboring antennas. Approximating a row of circular dishes as a simple rectangular strip of width d , the angle-dependent array efficiency is $\eta(\theta_z) = d/(s_0 \cos(\theta_z))$ for $\cos(\theta_z) \geq d/s_0$, and

$s_0 \cos(\theta_z)/d$ for $\cos(\theta_z) < d/s_0$. Figure 1 shows the result of using this simple model and averaging the losses over angle from $\theta_z = 0$ to a given maximum angle (a rough approximation to averaging over a vehicle trajectory).*

Amplitude variations or phase errors between dishes, and pointing errors or nonuniform illumination of individual dishes, also lower the array efficiency. For example, for random phase errors of rms magnitude σ , the efficiency is $e^{-(2\pi\sigma/\lambda)^2}$; $\sigma = 0.036 \lambda$ (a 13° phase error or a path length error of $\sim 80 \mu\text{m}$), corresponds to 95% efficiency.

We take nominal array efficiency of 0.9 (static fill factor) x 0.9 (trajectory-averaged fill factor/blockage) x 0.95 (amplitude/phase errors) = 0.77, but note that the efficiency for a real array could easily be lower.

Atmospheric Absorption and Scattering

At $1.08 \mu\text{m}$, loss in the atmosphere is dominated by particulate scattering, which varies widely from site to site. Cook [18] calculates the overall transmission for YAG lasers ($1.06 \mu\text{m}$) vertically from sea level to 150 km as 0.73 for year-round average conditions in the Sea of Japan, but notes that the transmission from 3 km altitude would be greater than 0.9. We assume a land site can be found with vertical transmission of 0.85 or better under most clear-sky conditions.

Microwave losses at the wavelengths of interest are dominated by water vapor absorption. Water vapor has an atmospheric scale height of 1-2 km, and site surveys for infrared and millimeter wave astronomy projects have identified several mountaintop sites within the continental United States with low precipitable water vapor (PWV). High peaks unfortunately tend to have issues of site accessibility, environmental and public use considerations, and weather availability, but as with the laser system we assume a usable site can be found with a PWV of 7 mm or less, corresponding to $\sim 85\%$ vertical transmission at 140 GHz, most of the time.

Atmospheric losses increase exponentially with path length through the atmosphere, but for zenith angles less than 60° and 85% zenith transmission, the trajectory-averaged losses (as opposed to the worst-case losses) will be larger than the zenith losses by a factor of only 1.2 – 1.5. For system comparisons and costing we assume a trajectory-average transmission $\eta_{\text{atm}} = 0.8$ for both systems.

Neither laser nor 140 GHz radiation will penetrate visible clouds, fog, or precipitation without large losses, so neither system has a large advantage with respect to weather-related availability.

APERTURE SIZE, BEAM DIVERGENCE, AND SCALING

The most difficult aspect of comparing microwave and laser systems relates to the scaling of the systems with power and beam divergence. Even for nominally equal

* Mutual blockage will be a more severe problem if vehicles are to be launched from the ground with beamed power, i.e., without a booster stage, since that will require the array to point nearly to the horizon in at least one direction.

beam divergence, the two systems will have different beam profiles, zenith-angle dependence, and beam shapes, and thus different losses as a function of range and zenith angle.

To permit a preliminary comparison, we take the laser system as a reference. The baseline system is designed to produce a circular Gaussian beam with an effective angular width θ_{beam} (full width to $1/e^2$ flux, 87% encircled energy) of $16 \mu\text{rad}$ at $\theta_z = 60^\circ$. The beam width is the result of convolving several effects (diffraction of the Gaussian initial beams, atmospheric turbulence, jitter, and module-to-module pointing errors) and is thus relatively insensitive to any particular change in the system design.

A nominally equivalent microwave system with a uniformly-illuminated circular phased array of diameter D would have an elliptical beam (due to the foreshortening of the array as seen from off-zenith) with an Airy profile. The angular divergence to the first zero (83% en-ellipsed energy) would be $2.44 \lambda/D$ (minor axis) by $2.44 \lambda/D \cos(\theta_z)$ (major axis). Defining the geometric mean of these to be the microwave system's θ_{beam} :

$$\theta_{beam}^2 = (2.44 \lambda/D)^2 / \cos(\theta_z), \text{ or } D = (2.44 \lambda / \theta_{beam}) / \sqrt{\cos(\theta_z)} \quad (1)$$

The array diameter for $16 \mu\text{rad}$ divergence at 140 GHz and $\theta_z = 60^\circ$ is 462 meters, which is uncomfortably large: the array area is $168,000 \text{ m}^2$. However, the microwave system can trade power for aperture, by having the vehicle fly a shorter, higher-acceleration trajectory.* This trade is not wholly independent of the vehicle and system design; for example, the vehicle propulsion system mass will tend to increase with beam power, and the effects of gravity on the trajectory will be reduced. For a first-order estimate, however, we assume that by adjusting the heat exchanger size and other system parameters, we can maintain a constant payload for a constant product $P_{beam} D$.

SYSTEM COST

A full launch system cost estimate is well beyond the scope of this paper, but a rough estimate of the capital costs is possible. We consider only the cost of the source, transmitting aperture, and prime power, assuming the launcher has a dedicated power plant. The capital cost of the system is given by

$$C_{sys} = c_s P_s^\alpha + c_{ps} \frac{P_s^\beta}{\eta_s} + c_{prime} \frac{P_s}{\eta_s \eta_{ps}} + C_{ap} N_{ap}^\gamma \quad (2)$$

where

- c_s = Source (laser or gyrotron) cost per output watt
- c_{ps} = DC power supply cost per DC watt

* The laser system can do this also, but the baseline laser system cost is already dominated by the laser cost, so reducing aperture area and cost is not useful. The laser system would benefit from a trade in the opposite direction, toward longer range and lower power, but θ_{beam} is limited by atmospheric turbulence and cannot be much reduced without using adaptive optics. Minimum acceleration is also limited by Earth's gravity, and maximum trajectory length by Earth's curvature, and the laser system is near these limits as well.

- c_{prime} = Prime power (generator) cost per watt
- C_{ap} = Unit aperture (dish or beam projector) cost
- P_s = Total source power in watts
- η_s, η_{ps} = Source, DC power supply, efficiency
- N_{ap} = Number of apertures
- α, β, γ = Scaling exponents for costs

The cost scaling exponents account for the learning curve – the decrease in unit cost of hardware with increasing production. This is often expressed as a learning curve factor f (cost reduction for each doubling of the number of units); for cost-scaling exponent x , $x = 1 + \ln(1 - f) / \ln(2)$, e.g., a 10% learning curve corresponds to an exponent of 0.85

For the laser system, we assume $\alpha = 0.76$ (a 15% learning curve, typical for unique complex assemblies) for laser cost scaling. As a reference point, we estimate a cost of \$100/watt, or \$1M per unit, for a hypothetical 10 kW fiber laser, quantity one. Current sub-1-kW fiber lasers are more expensive (\$200 – 500/watt) but use single telecommunications-type laser diodes (\$75-150/watt) as pumps, while higher power fiber lasers will use diode laser bars, currently about \$30/watt in single quantity [19]. This gives a predicted cost of \$10.50/watt for 15,000 lasers ($P_s = 150$ MW). That figure includes the cost of DC power supplies, which are commodity products with modest learning curves (95%) but are cheap, nominally \$0.35/DC watt in 10,000 unit quantities. \$10.50/watt is consistent with a previous estimate of \$6 – 10/watt for fiber lasers by one of us (Kare [20]) based on the projected cost of diode laser arrays.

The cost of telescopes varies widely depending on requirements; a single research-quality 1-m astronomical telescope can cost \$0.5 – 1 M, and a fast-slewing beam director much more. The launch system beam projector has looser requirements on the optics and mount than a typical astronomical telescope, but adds high power and a pointing and tracking subsystem. Using a single-unit cost of \$750K and a cost exponent γ of 0.85 (10% scaling factor), the unit cost for 2500 beam projectors would be \$228K.

The cost for prime power depends on how heavily the launch system is used. A launch system will require several hundred megawatts of electricity, with intermittent loading. If the system is lightly used (a few launches per day) an energy storage system (batteries, flywheels, etc.) might be acceptable, recharged from the national grid or a small generator. However, for heavier use, or bursts of several successive launches, a dedicated power source will be needed. We assume a dedicated gas-turbine power plant, with an installed cost of approximately \$0.60/watt.

We do not yet have a good estimate for cooling system costs, and they are likely to be site-dependent. For this paper we assume cooling costs are small compared to generator costs, particularly since only about half of the prime power becomes waste heat. Thus we lump cooling costs into c_{prime} , along with costs for power and cooling water distribution, and assume $c_{prime} = \$0.80/\text{watt}$, with no learning curve discount, for both systems.

Large gyrotrons currently cost about \$1/watt for 2-10 units. A 15% learning curve ($\alpha = 0.76$) gives a gyrotron cost of ~\$0.40/watt for 200 units. Power supplies for a 1MW

gyrotron cost about \$1/RF watt (\$0.50/DC watt at $\eta_s \approx 0.5$) but support hardware (superconducting magnet, stand, connectors, control electronics) and waveguide feeds raise the total cost for an installed gyrotron source to about \$4/RF watt. Gyrotron power supplies and support hardware are specialized, but less so than the gyrotrons themselves, so we assume those costs scale with a 90% learning curve ($\beta = 0.85$). This gives a source cost of roughly \$2.20/watt for 200 gyrotrons, or \$1.80/watt for 600. This is consistent with estimates from experts in the field [21]. As another point of comparison, the International Thermonuclear Experimental Reactor (ITER) ECH system, with 27 1 MW gyrotrons (24 at 170 GHz, 3 at 120 GHz) has a projected cost of \$82.5 million, almost exactly \$3/watt. [22] This includes \$26.3 million for power supplies, \$14.5 million for RF sources (gyrotrons) and controls, and \$41.7 million for transmission lines (waveguides); launcher hardware would have a higher duty cycle and add phase locking requirements, but have less waveguide complexity.

Microwave antenna cost can be estimated by analogy to astronomical arrays, specifically the Atacama Large Millimeter Array (ALMA) [23]. ALMA will have 64 12-meter mm-wave antennas, with a projected cost of approximately \$3.3M each, including mounts, which is \$29.5K/m² (FY2000 dollars) [24].

The ALMA array has a maximum operating frequency of 790 GHz, but has tolerances similar to those for a 140 GHz launch array because power beaming requires very low losses. In particular, ALMA has specified a 25 μm rms surface roughness, which would produce a 2.1% scattering loss at 140 GHz but nearly 3 dB (50%) loss at 790 GHz. Launch array antennas must also handle high power and provide full performance while slewing, and we include the as-yet-undetermined cost of the phase control system in the antenna cost. We therefore assume 12-meter power beaming antennas would cost 1/3 more than ALMA antennas (\$4.45M or \$40K/m²) at quantity 64, with a 10% learning curve ($\gamma = 0.85$).

Scaling of antenna cost with antenna diameter d is unclear; assuming $C_{ap} \propto d^\delta$ we

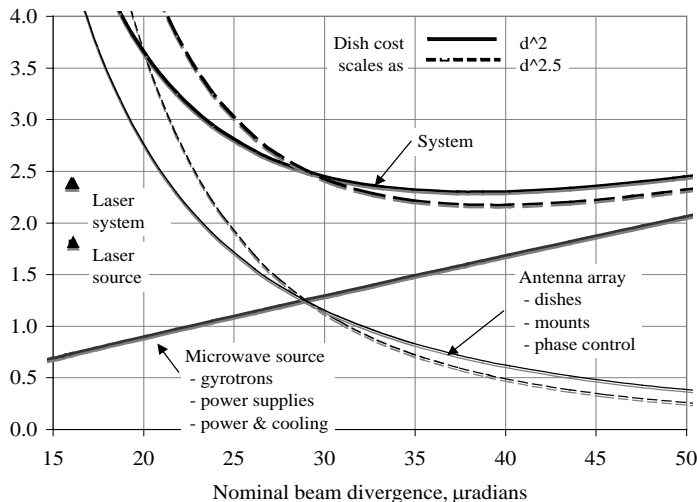


FIGURE 2. Microwave system cost vs. beam divergence ($\propto 1/\text{array diameter}$)

have found examples and estimates ranging from $\delta=1.5$ [25] to $\delta=2.7$. ($\delta=2.0$ is a constant cost per square meter). Figure 2 shows the scaling of the aperture cost and source cost (including prime power) for the microwave system as a function of the beam divergence, for $\delta = 2.0$ and 2.5. Both the number and size of the antennas vary enter into the calculation, so the total array cost varies as $D^{3\delta/2-\gamma}$ or, equivalently, as $\phi_{beam}^{\gamma-3\delta/2}$.

Finally, Table 4 summarizes the cost estimates and relative costs for the two systems, assuming an approximately optimum trade between array size and source power for the microwave system.

TABLE 4. 100-kg launch system beam source cost comparison

	Laser	Microwave	Ratio
Average power at vehicle, MW	100	250	2.5
<i>Average atmospheric transmission</i>	<i>0.8</i>	<i>0.8</i>	<i>1</i>
Power in beam, MW	125	312.5	2.5
<i>Array efficiency</i>	<i>1</i>	<i>0.77</i>	<i>0.77</i>
Transmitted power, MW	125	406	3.25
<i>Aperture efficiency</i>	<i>0.83</i>	<i>0.83</i>	<i>1</i>
Source power, MW	150	487	3.25
laser/gyrotron cost, \$/W	9.80	0.36	0.036
Power supply and support cost, \$/W*	0.70	1.54	2.19
Prime power and cooling cost, \$/W*	1.60	1.60	1
Source cost, \$/W	12.10	3.49	0.29
Source cost, \$M	1,815	1,702	0.94
# apertures	2500	487	n/a
Aperture diameter, m	1	7.5	n/a
Aperture cost, \$/m ² **	n/a	22.8	n/a
Unit aperture cost, \$K	228	994	n/a
Array cost, \$M	570	484	0.85
System cost, \$M	2,385	2,187	0.92

*cost per RF or laser watt; source efficiency included **assumes $\delta = 2.5$

DISCUSSION

Although the cost per watt of bare gyrotrons is estimated to be under 4% the cost of fiber lasers, gyrotrons have less than a 3:1 cost advantage per watt reaching the vehicle once the full source cost and efficiency are considered. This remaining advantage is negated at this scale by the high cost of the microwave antenna array. Trading array size for microwave power leads to a microwave system with roughly 3 times the power at the vehicle as in the laser system – essentially the same ratio as that between the original Kare and Parkin conceptual system designs. The costs of the two systems then differ by much less than the probable errors in our estimates.

The microwave system has a much shorter range and acceleration time than the laser system. This implies higher accelerations and higher loads on the vehicle and payload, but also means the microwave system can launch more payloads in a short period of time, or more total mass over a long period. Both systems have enormous total launch capacity compared to current launchers, so capital cost and payload size are probably more important than launch rate in the near term, but launch rate may be significant for some users.

With the system parameters used here, the microwave system scales favorably to larger payloads and higher powers, since a simple scaling of the system increases power and reduces beam divergence (increasing the useful range) while the laser system beam divergence does not improve with power. Conversely, the microwave system scales down poorly, either for smaller systems or for development and flight demonstrations.

CONCLUSIONS

Microwave- and laser-based beamed energy launchers both have technical unknowns that place them at TRL 2 to 3. For modular laser sources, there is a single major technical issue – scaling unit laser power to ~10 kW or greater. For microwave systems, the clearest technical issue is phase locking of large gyrotron arrays, but the microwave phased array aperture, and specifically phase sensing and control on the required scale, are also major challenges.

Laser systems have a modest advantage in end-to-end efficiency, mainly due to difficult-to-eliminate array losses in a steerable-dish phased array. Other losses need further analysis, but appear to be similar for the two systems.

The laser system cost is, not surprisingly, dominated by the lasers themselves; the laser system will be competitive if and only if laser costs fall at least roughly as projected. For the microwave system, there is no dominant cost element likely to be affected by technical progress or production scaling, but the greatest gains in system performance vs. cost would come from lowering the cost of large millimeter-wave antennas.

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