

although wet oxygen shows large discrepancies at around 400 mc. In fact, wet oxygen appears to go through a minimum in this frequency range, a fact which is not presently understood.

If one considers the surface resistance  $R_{s1}$  to be the same as the dynamic low-frequency barrier resistance, a serious objection to the above model is raised when one calculates the values of  $R_{s1}$  from the data (see Table II), for it is seen that  $R_{s1}$  is about two to three orders of magnitude lower than the low frequency dynamic resistance (approximately 10 megohms at  $-1$  volt bias). Furthermore, the expected inverse proportionality between  $R_{s1}$  and the reverse current in different ambients is not apparent (if anything they seem to be directly proportional).

One way out of this difficulty is to consider a more complete equivalent circuit for the surface. Fig. 3 shows a schematic representation of a gold bonded diode, where  $R_{s1}$  is the resistance along the surface which shunts the transition capacitance  $C_t$ , and  $C_s$  is the capacitance associated with the surface space-charge region. In addition, we shall introduce a second surface resistance  $R_{s2}$  which expresses the dependence of the reverse current on the surface generation rate, and is analogous to the diffusion resistance at the bulk junction (omitted from the diagram because it is very large compared to the reactance of  $C_t$ ). It is clear that  $R_{s2}$  is in parallel with  $C_s$  in order to provide a dc current path. Although  $R_{s1}$ ,  $R_{s2}$ , and  $C_s$  are represented as lumped constants, they are actually distributed over the surface and may vary from point to point.

Experimental information indicates that  $C_t \gg C_s$ , otherwise the measured equivalent

TABLE II  
CALCULATED LEAKAGE RESISTANCE IN  
DIFFERENT AMBIENTS

Ambient	Reverse Bias	$R_{s1}$ (K Ohm)
Ozone	0 Volt	4.7
Ozone	-1	18
Dry O <sub>2</sub>	0	6
Dry O <sub>2</sub>	-1	47
Wet O <sub>2</sub>	0	18
Wet O <sub>2</sub>	-1	156

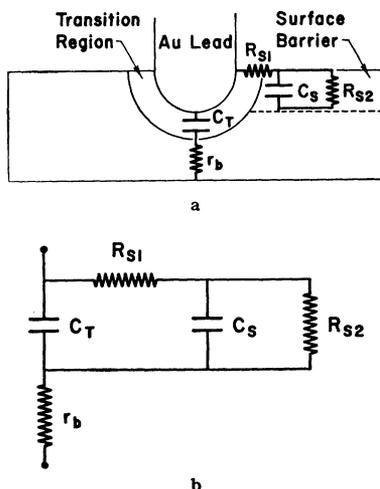


Fig. 3—(a) Schematic representation of gold-bonded diode. (b) Equivalent circuit of gold-bonded diode.

capacitance would differ from the transition capacitance  $C_t$ . At microwave frequencies,  $C_s$  short-circuits  $R_{s2}$  so that the equivalent series resistance is still expressed by (2). However, at dc and low frequencies, the main contribution to the dynamic barrier resistance is given by  $R_{s2}$  which may be much larger than  $R_{s1}$ .

While this work was in progress, D. E. Sawyer of Lincoln Laboratories, Lexington, Mass., reported a  $1/f$  frequency dependence (in the range 10 to 250 mc) for the equivalent series resistance of a variable capacity diode.<sup>2</sup> While our experimental conditions differ from his in several important instances (different diode structure, higher frequency range, etc.) there is nevertheless no adequate explanation for this difference.

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<sup>2</sup> D. E. Sawyer, Device Research Conf., Ithaca, N. Y., June, 1959.

### WWV Standard Frequency Transmissions\*

Since October 9, 1957, the National Bureau of Standards radio stations WWV and WWVH have been maintained as constant as possible with respect to atomic frequency standards maintained and operated by the Boulder Laboratories, National Bureau of Standards. On October 9, 1957, the U.S.A. Frequency Standard was 1.4 parts in  $10^9$  high with respect to the frequency derived from the UT 2 second (provisional value) as determined by the U. S. Naval Observatory. The atomic frequency standards remain constant and are known to be constant to 1 part in  $10^9$  or better. The broadcast frequency can be further corrected with respect to the U.S.A. Frequency Standard, as indicated in the table; values are given as parts in  $10^{10}$ . This correction is *not* with respect to the current value of frequency based on UT 2. A minus sign indicates that the broadcast frequency was low.

The WWV and WWVH time signals are synchronized; however, they may gradually depart from UT 2 (mean solar time corrected for polar variation and annual fluctuation in the rotation of the earth). Corrections are determined and published by the U. S. Naval Observatory.

WWV and WWVH time signals are maintained in close agreement with UT 2 by making step adjustments in time of precisely plus or minus twenty milliseconds on Wednesdays at 1900 UT when necessary; a retarding time adjustment was made at WWV and WWVH on December 16, 1959.

\* Received by the IRE, January 25, 1960.

### WWV FREQUENCY WITH RESPECT TO U. S. FREQUENCY STANDARD

1959 1600 UT	Parts in $10^{10}$ †
December 1	-30
2	-29
3	-29
4	-29
5	-29
6	-28
7	-28
8	-28
9	-28
10	-28
11	-28
12	-28
13	-28
14	-28
15	-28
16	-28
17	-28
18	-28
19	-28
20	-28
21	-28
22	-28
23	-28
24	-28
25	-28
26	-28
27	-28
28	-28
29	-28
30	-28
31	-28

† 30-day moving average seconds pulses at 15 mc. Method of averaging is such that an adjustment of frequency of the control oscillator appears on the day it is made. No change or adjustment in the control oscillator was made during December, 1959.

Note: Beginning January 1, 1960, the value of the USFS has been arbitrarily increased by 74 parts in  $10^{10}$  to bring it into agreement with a cesium resonator frequency of 9192, 631, 770 cps. See "National standards of time and frequency in the United States," National Bureau of Standards, Proc. IRE, vol. 48, pp. 105-106; January, 1960.

NATIONAL BUREAU OF STANDARDS  
Boulder, Colo.

### The Tunnel-Emission Amplifier\*

During the recent tumult caused by the "tunnel diode," this author had cause to reflect upon just what significant statements might be made concerning this device. The more important conclusions may be summarized as follows:

- 1) The device employs a *controlled source of majority carriers*.
- 2) Its frequency response is essentially limited by the number of majority carriers available.
- 3) In times past many negative resistance devices have been introduced, but in the course of time have given way to stable three-terminal amplifying devices.

Once interest in a negative resistance is abandoned, it becomes clear that semiconductors are of questionable value, since their carrier densities are inherently quite low. Metals with very large electron densities may be used as a carrier source, and insulators provide the necessary forbidden regions.

\* Received by the IRE, December 28, 1959.

## SURFACE TUNNELING

Let us consider the behavior of a metal-insulator-metal layer structure with a voltage impressed between the two metal layers. A simplified energy band picture of such a structure is shown in Fig. 1(a). Under the bias condition shown, electrons near the Fermi level in the negative metal may "tunnel" through the forbidden region into the insulator conduction band and thus make their way to the positive metal. In order to find the total tunnel current we must find the number of electrons per second incident on the junction as a function of energy, multiply by the tunneling probability which will also depend upon the energy, and integrate over the available electron energies. An approximate expression may be obtained by assuming a "hard" Fermi sphere in the metal, an insulator whose forbidden region is centered on the metal Fermi level, and neglecting the contribution of electrons appreciably below the Fermi level. The results of such calculations are

$$J \approx J_0 \frac{\pi V_1}{2V_f} \frac{E}{E_0} e^{-E_0/E} \quad (1)$$

where

$$J_0 = \frac{3qN_0\hbar k_f}{4m}$$

$$E_0 = \frac{qmaV_1^2}{\hbar^2}$$

$V_1$  is half the insulator forbidden band gap,  
 $V_f$  is the metal Fermi level,  
 $k_f$  is the wave number of an electron at the metal Fermi level,  
 $N_0$  is the electron density in the metal,  
 $m$  is the electronic mass, and  
 $q$  is the electronic charge.

Since the tunneling distance for electrons in the metal is much shorter than for insulator valence electrons, tunneling from the metal would be expected to dominate the process by a considerable margin. The values for aluminum and aluminum oxide are

$$J_0 \approx 10^{12} \text{ amp/cm}^2$$

$$E_0 \approx 1.5 \times 10^8 \text{ V/cm.}$$

The tunnel current as a function of electric field is shown in Fig. 2.

## TUNNEL EMISSION

Suppose we make the positive metal layer thin compared with an electronic mean free path. Electrons tunneling from the negative metal "emitter" on the left into the insulator conduction band may continue through the thin metal base. Those which possess sufficient momentum to overcome the metallic work function will be emitted from the surface to the right.

This structure may be useful as a "tunnel cathode" for conventional or microwave tubes, or it may be used as the emitter of a transistor-like three-terminal amplifier.

Let us place to the right of the thin metal "base" region another insulating layer and then a metal "collector." The simplified energy band picture for such a configura-

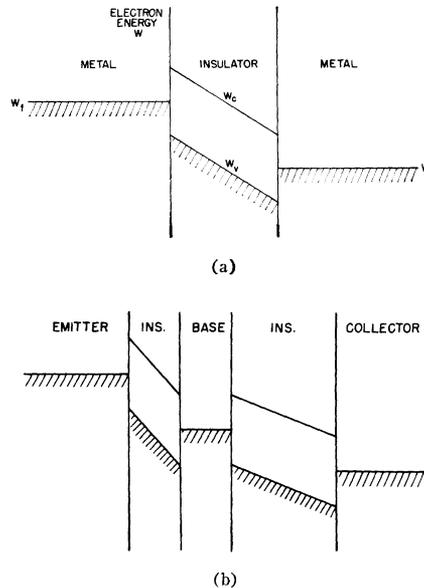


Fig. 1—Simplified energy band models for (a) diode, and (b) triode.

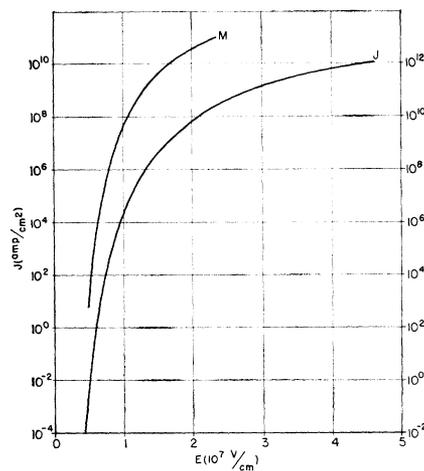


Fig. 2—Tunnel current density and figure of merit as function of electric field.

tion is shown in Fig. 1(b). Electrons tunneling through the thin "base" region now find themselves in the conduction band of the second insulator, and provided the collector is biased positively, will be accelerated to the right and hence collected. Such a device may be characterized in much the same way as a transistor, and the same considerations concerning gains and impedances apply. In the common base connection, power gain is obtained as a result of the impedance transformation between input and output.

## FREQUENCY LIMITATIONS

Since the tunneling itself occurs in an extremely short time, we should expect the operating frequency to be limited by the rather large input capacitance. Using as a figure of merit

$$M = \frac{1}{RC} \quad (2)$$

where  $R$  is the incremental input resistance and  $C$  is the input capacitance, we may estimate the frequency limitation from (1);

$$M \approx \frac{J_0 E_0 e^{-E_0/E}}{\epsilon E}$$

This equation has been evaluated in terms of the electric field and plotted along with the current density in Fig. 2. At a field of  $1.5 \times 10^7$  v/cm the current density would be of the order of  $4 \times 10^6$  amp/cm<sup>2</sup> and  $M$  would be nearly  $10^{12}$  cps. The real limiting factor appears to be just how small the devices may be built in order to keep the current density at as high a value as possible. Since there will always be some lateral current in the thin base region, current crowding problems will exist as in the transistor. Also such high currents will cause local heating of the metal and place a limit on the operating densities. The space charge limitation for typical geometries is of the order of  $10^9$  to  $10^{10}$  amp/cm<sup>2</sup> and hence should not be a problem. It is clear that the input circuit must work at very low impedance levels, just as the negative resistance "tunnel diode."

## EXPERIMENTAL RESULTS

The first observations of surface tunneling were made on diodes constructed as follows: A relatively thick film of aluminum was evaporated on a glass substrate and subsequently anodized in a nonsolvent electrolyte. This method produced  $\text{Al}_2\text{O}_3$  films whose thickness was calculated from the known oxide growth rate to be between 60 and 80 Angstroms. Many small aluminum squares were then evaporated over the oxide. Tunnel current was observed to begin very abruptly at fields of one to two times  $10^7$  volts/cm. The results were quite reproducible between units on one anodized film, but varied by as much as a factor of two between different films.

Triodes were made in the same manner, except the second aluminum evaporation was carefully controlled to give a thin base layer (about 100 Å). Silicon monoxide was then evaporated over the entire area to a thickness of several hundred Angstroms. A thick aluminum collector was evaporated over the insulating film. Tunnel current at the collector was observed to begin very abruptly at emitter-base fields of the same magnitude as in the diode. For the units tested, the emitter-collector current transport factor ( $\alpha$ ) was between 0.1 and 0.3, increasing markedly as the current density increased. This behavior is to be expected from such a device where surfaces may contribute a large number of trapping states.

All units were destroyed at rather small currents (less than 1 ma) indicating that the tunneling had occurred over one very small area. Again this behavior is to be expected from the rather crude techniques employed.

## CONCLUSION

The devices described here are inherently capable of extremely high frequency performance. To realize their theoretical capabilities, however, a large amount of development effort will undoubtedly be necessary. The purity of materials and refinement

