

# Rapid Near-Optimal VQ Design with a Deterministic Data Net

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We present a new algorithm for fixed-rate vector quantizer (VQ) design. A fixed-rate VQ of dimension  $d$  and rate  $(\log K)/d$  represents each vector in  $\mathbb{R}^d$  by one of  $K$  possible codewords. Given a pdf  $p(\mathbf{x})$  on  $\mathbb{R}^d$  and an integer  $K \geq 1$ , an optimal VQ  $\{\mu_1^*, \dots, \mu_K^*\} \subset \mathbb{R}^d$  achieves expected distortion  $\Delta = \min_{\{\mu_1, \dots, \mu_K\} \subset \mathbb{R}^d} \int_{\mathbb{R}^d} p(\mathbf{x}) \min_{k \in \{1, \dots, K\}} \|\mathbf{x} - \mu_k\|^2 d\mathbf{x}$ .

Let  $p(\mathbf{x})$  denote the empirical distribution of an  $n$ -point training set. Optimal VQ design is NP-hard even for  $K = 2$  [1]. Iterative design finds a locally optimal VQ [4]. For any  $\varepsilon > 0$ , an  $\varepsilon$ -approximation algorithm guarantees a VQ with expected distortion  $D \leq (1 + \varepsilon)\Delta$ . The best prior  $\varepsilon$ -approximation algorithms are a deterministic  $O(\varepsilon^{-2K^2 d n \log^K n})$ -time  $\varepsilon$ -approximation [5] and a randomized  $O(\exp(\varepsilon^{-8} K^3 (\ln K) (\ln \frac{1}{\varepsilon} + \ln K)) n \log^K n)$ -time  $\varepsilon$ -approximation [2]. (The problem is called “ $K$ -clustering” and “ $K$ -median” in those papers.)

We present a new deterministic  $\varepsilon$ -approximation algorithm running in time quasilinear in  $n$ . The algorithm, which also serves as an approximation algorithm for the  $d$ -dimensional fixed-rate operational distortion-rate function, extends to a variety of network VQ problems.

Define a *data net* to be a set  $\mathcal{Z} \subset \mathbb{R}^d$ , regions  $\{A_z\}_{z \in \mathcal{Z}}$ , and mapping  $\zeta : \mathbb{R}^d \rightarrow \mathcal{Z}$  such that

1.  $\int_{A_z} p(x) \|x - z\|^2 d\mathbf{x} \leq \varepsilon \Delta / K$  for all  $z \in \mathcal{Z}$
2. For any  $\mu \in \mathbb{R}^d$  and  $x \notin A_{\zeta(\mu)}$ ,  $\|x - \zeta(\mu)\|^2 \leq (1 + \varepsilon) \|x - \mu\|^2$ .

Our deterministic algorithm designs a data net of size  $M = c^d K^2 (K^2 + \varepsilon^{-2}) \varepsilon^{-d-1}$  for some constant  $c$ , within time  $Mn \log \log n$  and then returns the best codebook  $\{\mu_1, \dots, \mu_K\} \subset \mathcal{Z}$ .

**Theorem 1** *The above deterministic algorithm finds a rate- $(\log K)/d$  fixed-rate VQ with distortion  $D \leq (1 + \varepsilon)\Delta$  within time*

$$Mn \log \log n + M^{K+1} n.$$

Subsequent to codebook design, individual encodings can be performed in time  $\log(K/\varepsilon)$  using [3].

We can improve Theorem 1’s dependence on  $K$  at the expense of  $d$ . The algorithm can also perform efficient VQ design for simply characterized continuous distributions.

The algorithm generalizes to give  $\varepsilon$ -approximation algorithms for many network VQ design problems. A few

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examples follow. Many more examples (including all combinations of listed examples) follow similarly.

**Multiresolution VQ (MRVQ):** A transmitter describes source  $X$  to  $L$  receivers. Receiver  $\ell$  gets only the first  $\sum_{i=1}^{\ell} \log K_i$  bits of the binary description.

**Multiple description VQ (MDVQ):** A transmitter sends  $L$  packets describing source  $X$ . Any subset of packets may be lost in transmission.

**Side information VQ (SIVQ):** A transmitter describes source  $X$  to a receiver that has access to side information unavailable to the encoder.

**Broadcast VQ (BCVQ):** A transmitter describes multiple sources to a family of decoders. Each source is intended for a distinct subset of the receivers, and each component of the description is received by a distinct subset of the receivers.

**Joint source-channel VQ (JSCVQ):** A transmitter describes a single source to a single receiver. The description may be corrupted during transmission.

**Remote source VQ (RSVQ):** An encoder observes a noisy copy of the true source and describes it to the decoder. The decoder reconstructs the true source as accurately as possible.

In each example, let  $S$  be the number of sources ( $S = 1$  in all but the BCVQ),  $K$  be the maximal number of codewords that can be distinguished by any single decoder,  $T$  be the total number of  $d$ -dimensional codewords in the code, and  $\Delta$  be the optimal performance (an expected distortion over some distribution on the reconstructions at different receivers).

**Theorems 2–7** *In each scenario above, designing a data net of size  $M = c^d K^2 (K^2 + \varepsilon^{-2}) \varepsilon^{-d-1}$  for each source, and using the best  $T$  codewords from those data nets gives a code with performance  $D \leq (1 + \varepsilon)\Delta$  in time*

$$SMn \log \log n + (SM)^{T+1} n.$$

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